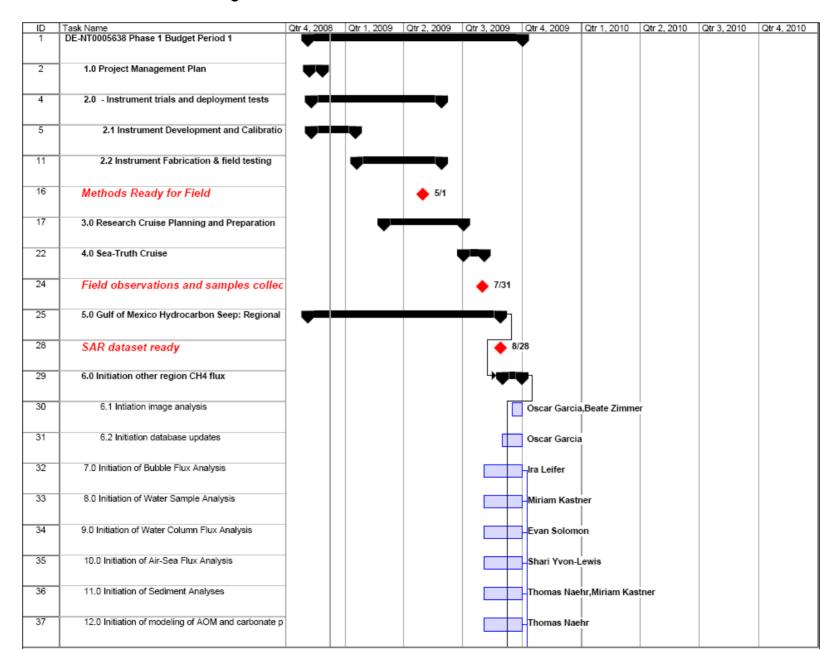


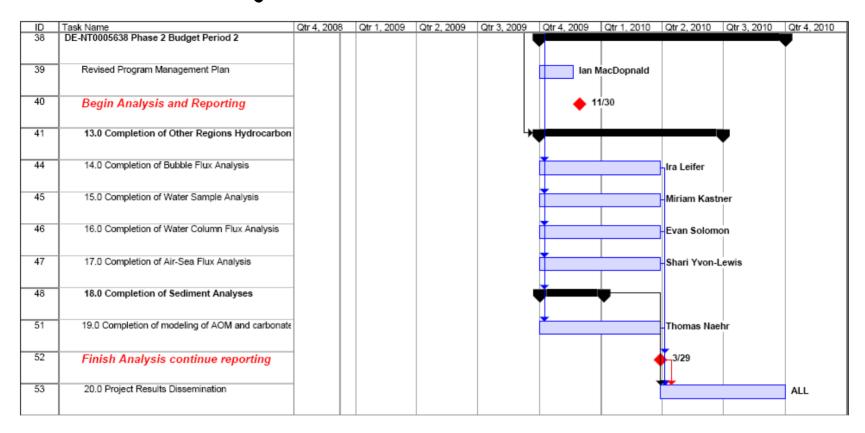
Project Goals & Objectives

- Constrain the flux of methane from gas hydrate on continental margins
 - Use remote sensing inventories to enumerate methane sources in the Gulf of Mexico and selected margins.
 - Make careful measurements of CH₄
 concentrations in bubble-streams from gas
 hydrate deposits: seafloor, water column, air water interface.
 - Model precipitation of carbonate as function of pore-fluid CH₄ concentrations
 - Model fluxes at sites ~500, 1000, 1500 m.
 - Extrapolate to basin-wide fluxes.

Project GANTT 2008-2009



Project GANTT 2009-2010



Project Investigators

- · Texas A&M University Corpus Christi
 - Ian MacDonald, Thomas Naehr, Beate Zimmer, Oscar Garcia
- Scripps Oceanographic Inst
 - Miriam Kastner, Evan Solomon
- Texas A&M University College Station
 - Shari Yvon-Lewis
- UC Santa Barbara
 - Ira Leifer
- Univ. Southern Mississippi
 - Vernon Asper, Kevin Martin

Air-Sea Flux

(Shari Yvon-Lewis, TAMU)

Photos of the equilibrator, a GC system and the 4 pump pumpboard for reference. We will have a 2 unit pump-board on this cruise

 $(\sim 1/2$ the width).



Equilibrator – just outside of main lab on R/V Ron Brown



Pump Board inside main lab of R/V Ron Brown



Saturation Anomaly Instrument (on a 1.5m table)

Bubble Flux (Ira Leifer, UCSB & Kevin Martin U. S. Miss)



- SONAR location and quantification of bubble streams.
- Modeling bubble flux through water column.
- Bubbleometer measurement of gas venting.

Water Column Concentrations (Miriam Kastner & Evan Solomon, Scripps)



 Collect and analyze watercolumn samples

CH₄

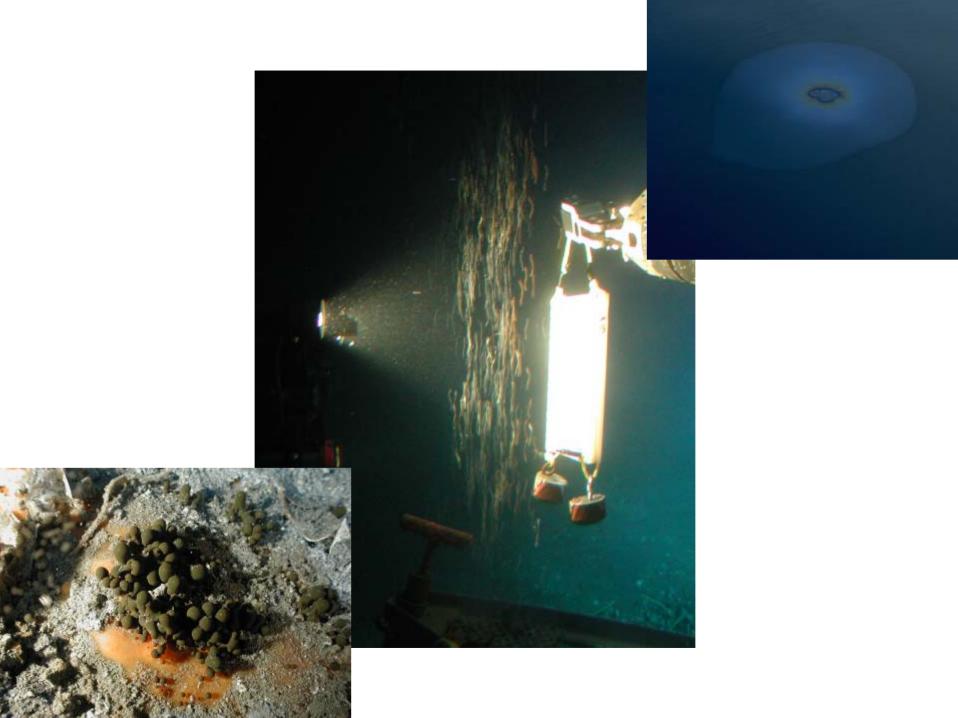
• δ¹³C

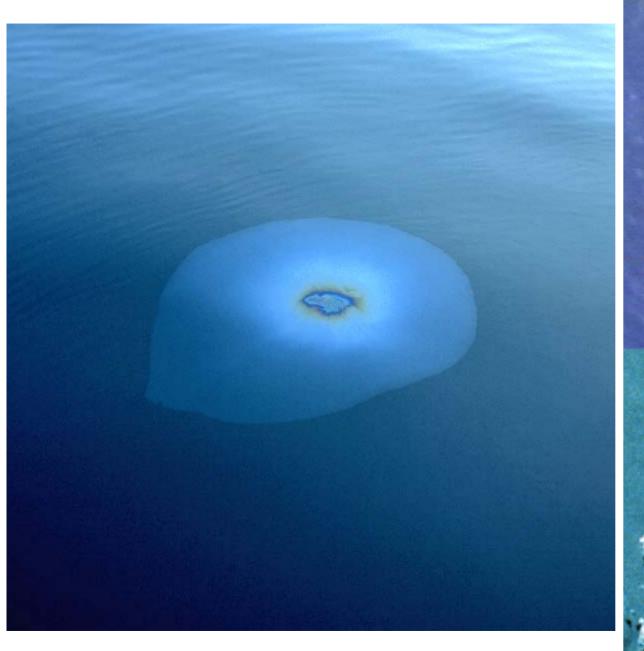
Carbonate Precipitation (Thomas Naehr, TAMUCC)

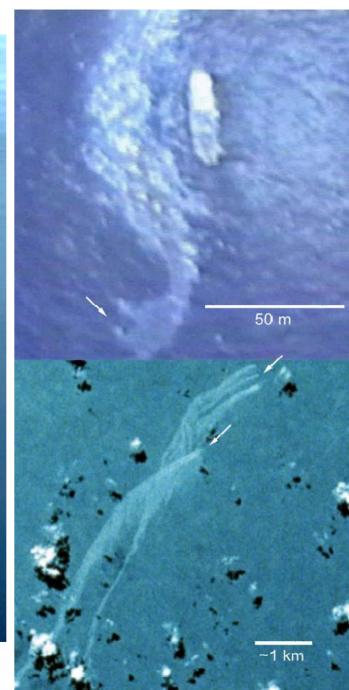


 Seep carbonate system: AOM and authigenic CACO₃ precipitation.

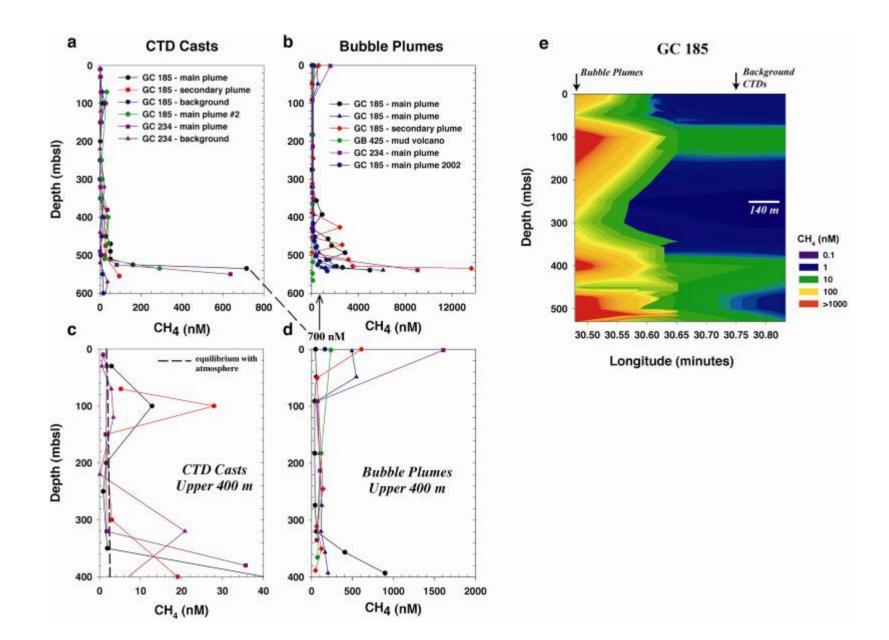
Remote sensing inventory of seep locations.







Seep Methane Maxima



The bubble emission flux distribution can then be converted into volume and mass fluxes and integrated to obtain total values for the seep vent.

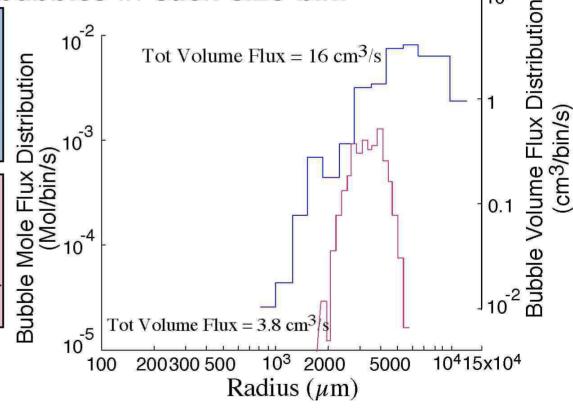
These are the volumes and masses a flux capture device would receive from bubbles in each size bin.

Pulsing Seep

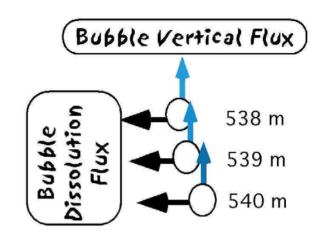
Tot Mole Flux = 0.039 Mol/s Tot Mole Flux = 140 Mol/hr Tot Mole Flux = 3400 Mol/dy Tot Mole Flux = 1.2×10^6 Mol/yr Tot Mass CH₄ = 1.7×10^4 kg/yr

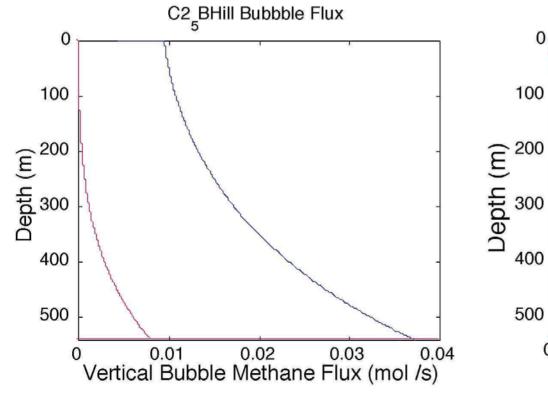
Steady Seep

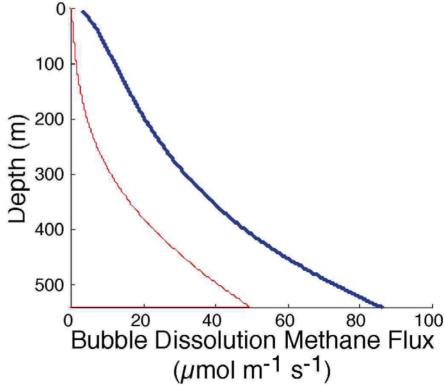
Tot Mole Flux = 0.0081 Mol/s Tot Mole Flux = 29.1 Mol/hr Tot Mole Flux = 699.4 Mol/dy Tot Mole Flux = 2.55×10^5 Mol/yr Tot Mass CH₄ = 4.08×10^3 kg/yr



Combining the calculated bubble composition at each depth with the seep vent flux distribution, the dissolution flux for each meter of rise and the amount of methane remaining in all bubbles can be calculated. Dissolution is greatest at the bottom. This simulation does not include bubble break-up, thus the very large bubbles observed easily made it to the surface, tripling in size.



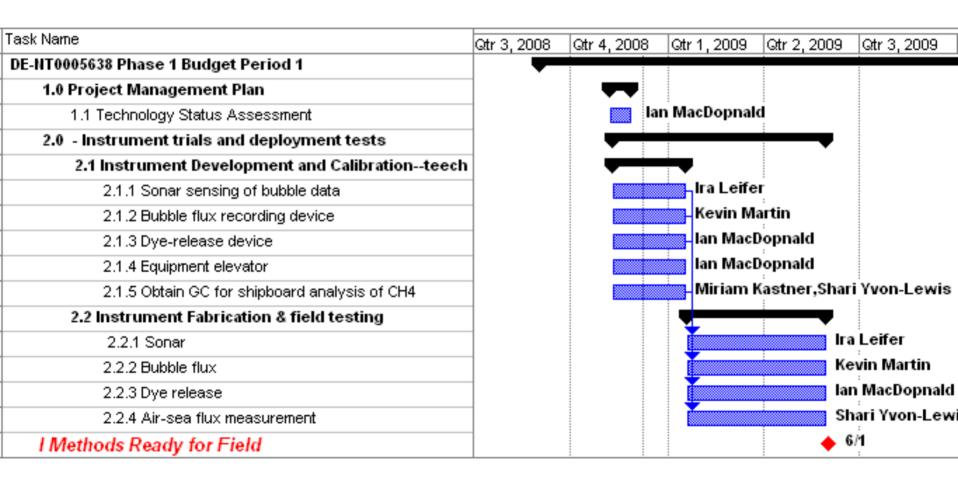




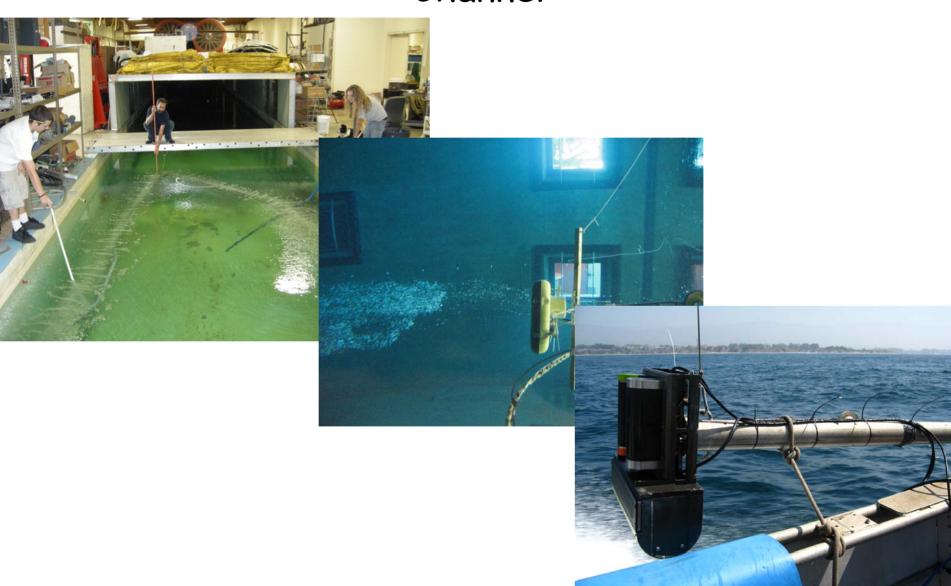
Summary

- Discharge from medium-flux seeps (e.g. gas hydrate deposits) generates perennial slicks.
- Oil and gas interact in complex ways to affect transfer to the ocean and atmosphere.
- Discharge from high-flux seeps (e.g. mud volcanoes) can be episodic and highly variable.
- Need to constrain number of GH deposits
 & cross-section of typical seep gas plumes.

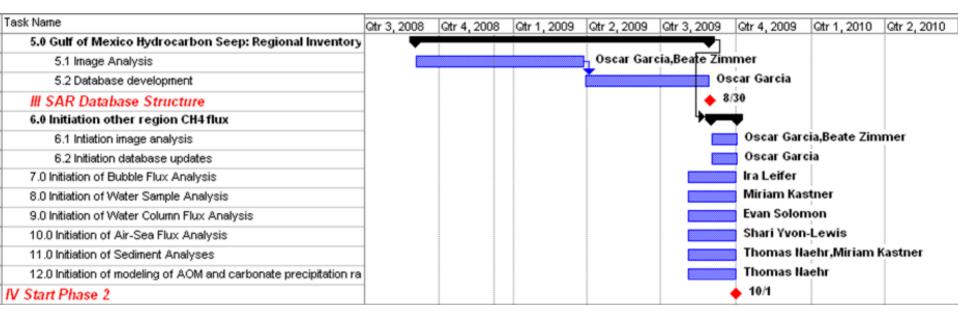
Instrument Acquistion/Calibration Q4 2008 - Q2 2009



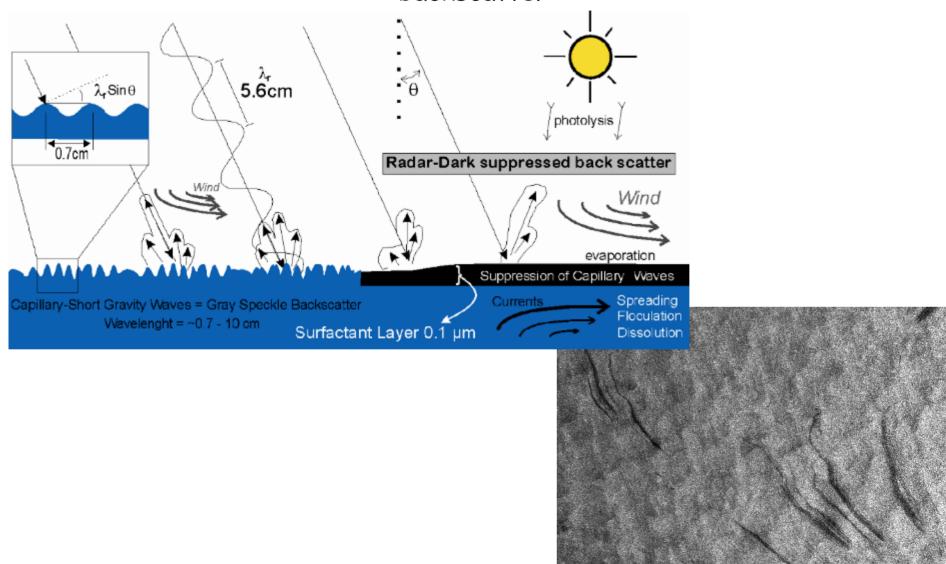
Field testing at Leifer lab & Santa Barbara Channel

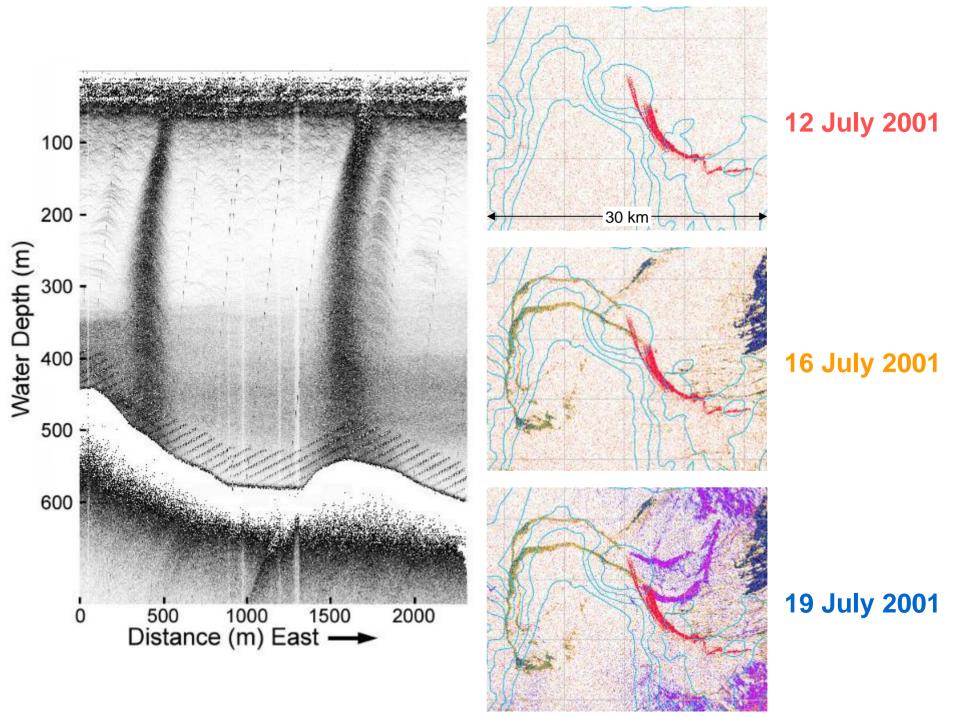


Remote-Sensing Inventory of Seeps Q3 2008 - Q3 2009

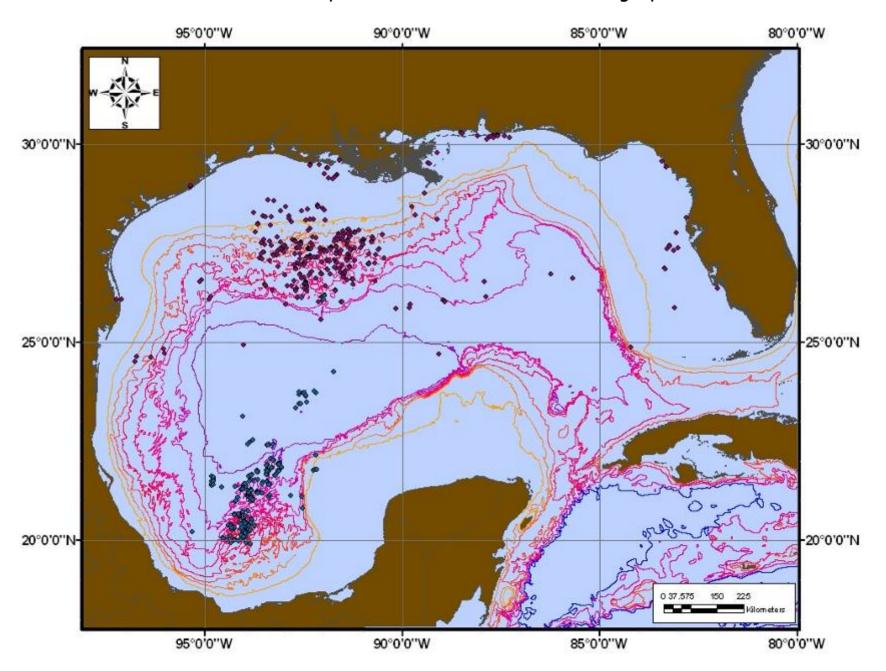


Surfactant layers (slicks) generate strong contrast with SAR backscatter

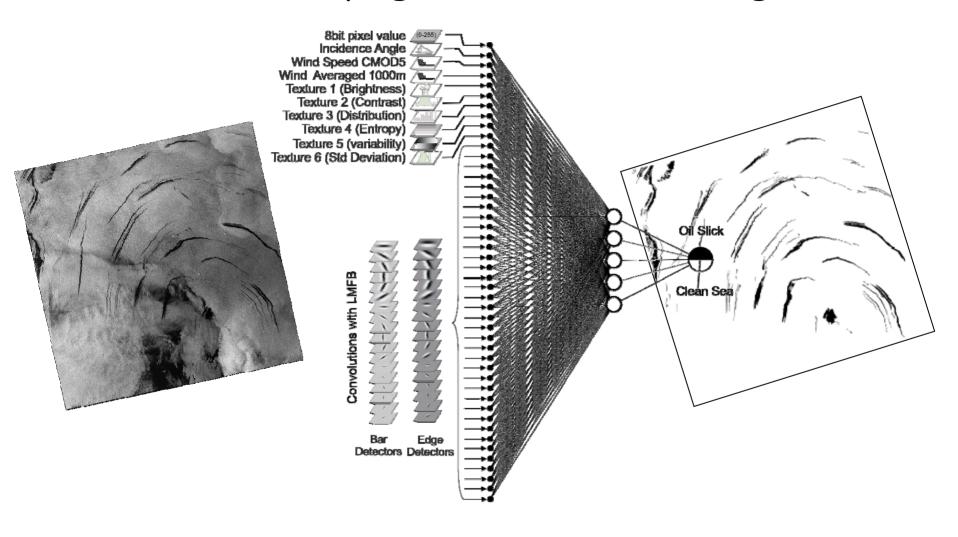




Historic Seep Sites Detected in Satellite Imagery



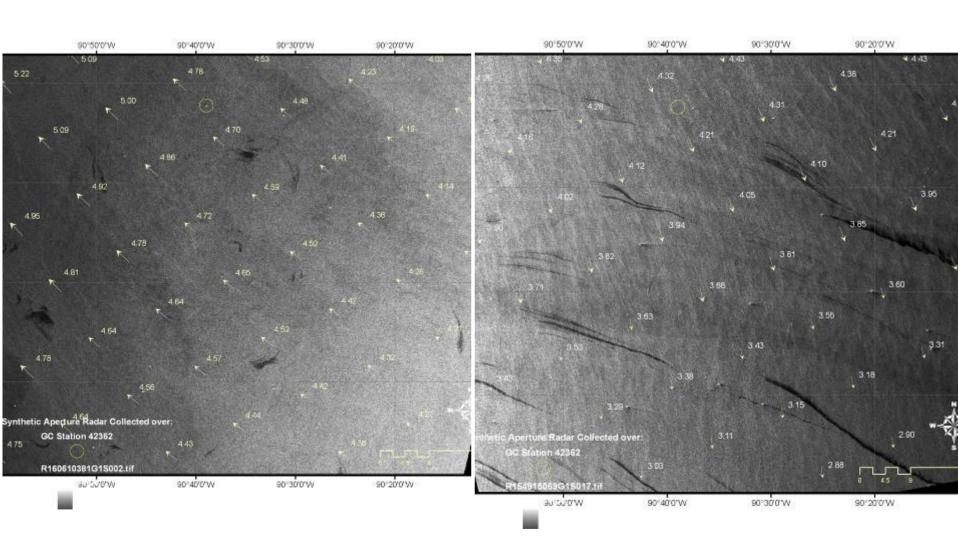
Texture Classifying Neural Network Algorithm

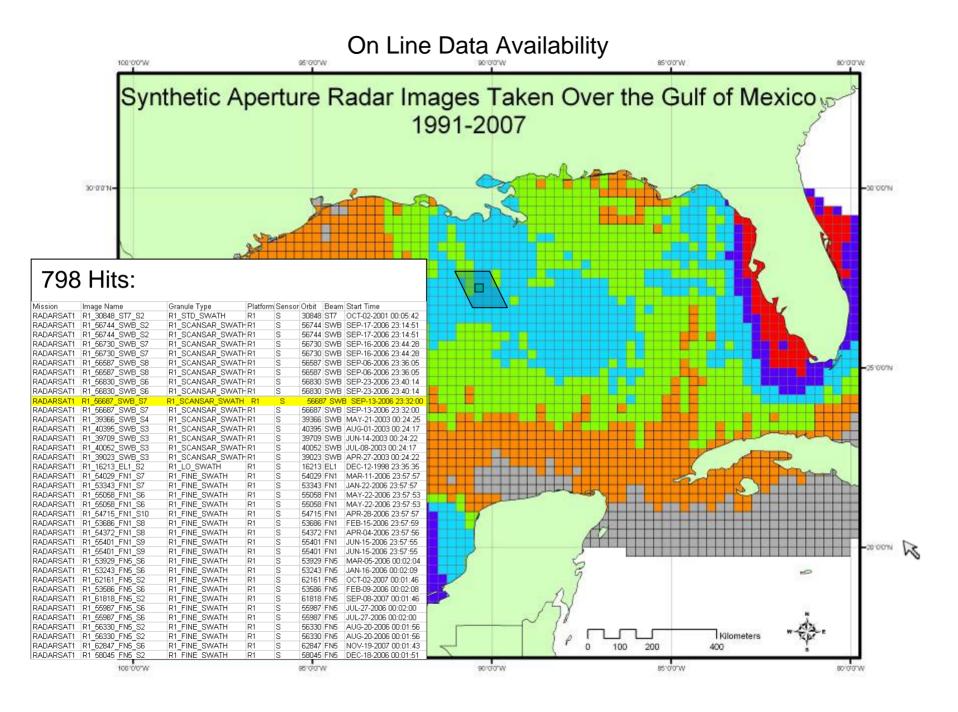


File size ~100 Mbyte

File size ~1 Mbyte

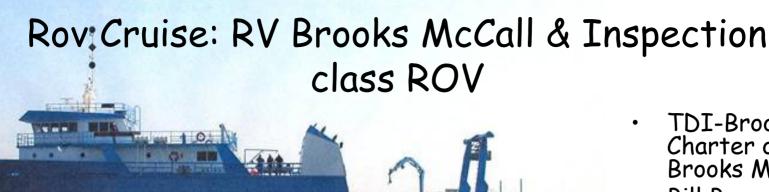
Similar Wind Conditions





Sea-Truth Cruise Q1 2009 - Q3 2009

Task Name	Qtr 3, 2008	Qtr 4, 2008	Qtr 1, 2009	Qtr 2, 2009 Qtr 3	, 2009		
3.0 Research Cruise Planning and Preparation							
3.1 Charter of research vessel				lan Macl	Oopnald		
3.2 Charter of ROV				lan MacD	opnald		
3.3 Procurement of other equipment				<u>k</u>			
3.3 Cruise plan				ALL.			
4.0 Sea-Truth Cruise					•		
4.1 Research field activities					ALL		
Il Field observations and samples collected				•	7/31		



- TDI-Brooks Int. Charter of RV Brooks McCAll
- Bill Bryant ROV group (TAMU)
- Veolia Services (ROV piloting)



LWH: 48 inches, 37 inches, 48 inches

Frame: Anodized Aluminum

2 x electronic pressure bottles Housing:

Weight in air: 1300 lbs

Lights:

Camera (2):

Viewing P/T:

20 lbs. (approx) Payload:

4,921 feet (1500 meters) Depth: Solid cell syntactic foam Buoyancy:

Power input: 1000 VAC, 3 phase, 7kW Thrusters: 5 thrusters, 2 Hp, pressure compensated

Hydro-lek 5 function, Hydro-lek Jaw Manipulators:

Speed (approx): Horizontal 2.8 knots

> Vertical 1.2 knots Lateral 1.3 knots Turn 50 deg/sec 4 x 250W halogen

4 channel light dimmer

Camera 1, color zoom CCD 0.1 lux

Camera 2, color, 1 lux Pan angle 0-90 degrees Tilt angle 0-120 degrees

TAMU Sub-Fighter ROV





LWH: 48 inches. 37 inches, 48 inches Frame: Anodized Aluminum 2 x electronic pressure bottles Housing: Weight in air: 1300 lbs Payload: 20 lbs. (approx) Depth: 4.921 feet (1500 meters) Solid cell syntactic foam Buoyancy: Power input: 1000 VAC. 3

phase, 7kW **Thrusters:**5 thrusters, 2 Hp, pressure compensated

Manipulators: Hydro-lek 5 function. Hydro-lek Jaw

Speed (approx): Horizontal 2.8 knots

Vertical 1.2 knots Lateral 1.3 knots Turn 50 deg/sec 4 x 250W halogen 4 channel light

dimmer

Camera 1, color zoom CCD HR, 480

Camera (2): Camera 1, col TV lines, 0.1 lux Camera 2, color, 460 lines, 1 lux

Viewing P/T: Pan angle 0-90 degrees

Tilt angle 0-120

degrees **Telemetry**:

Lights:

Fiber MUX 907

3 video channels

2 x RS 485 channels 2 x RS 232 channels

10 Mbit Ethernet

Sensors: Depth sensor, accurate .15%

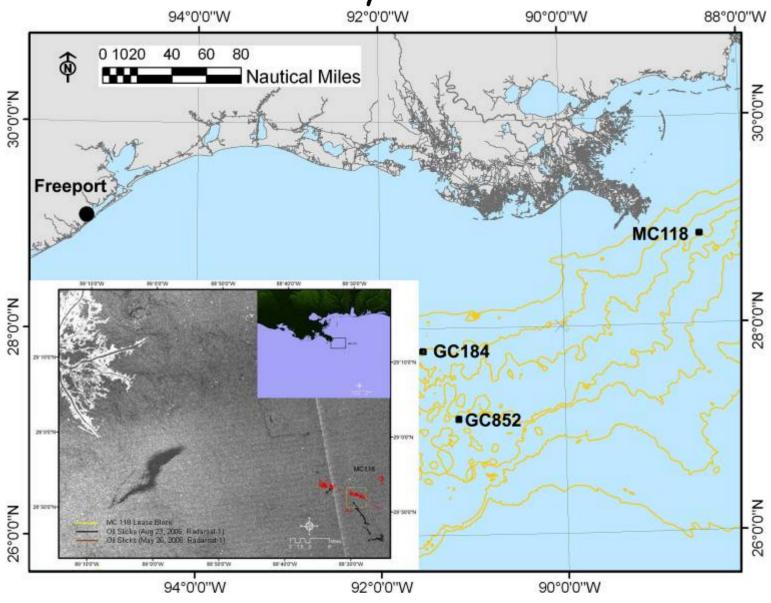
Kongsberg MS1000 sector scanning sonar

Other: Auto depth

Auto heading

Digital control of thrusters and lights

Study Sites



Cruise activities at each station

Activ	ity	time required	time on station
1	Deploy ROV with bubble meter	2	2
2	Locate active vents fix position & depth	3	5
3	Deploy Bubble meter at active vent	3	8
4	Recover ROV	3	11
5	Deploy sonar mooring from surface ship	4	15
6	Collect CTD cast	2	17
7	Collect fine-scale grid of surface samples	6	23

Deploy ROV

Recover ROV

Collect push cores near vent

Collect replicate CTD cast

Recover Sonar Mooring

Collect piston cores (2)

Locate active vents & verify location of sonar array

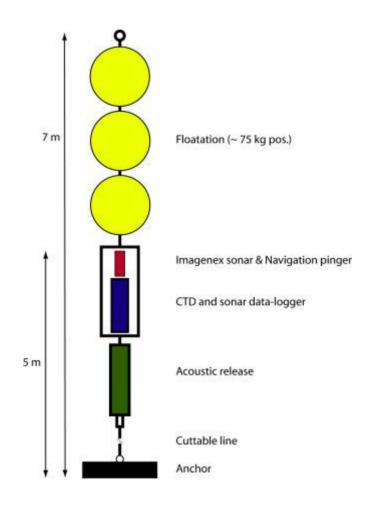
Collect coarse-scale grid of surface samples

Collect background CTD cast away from site

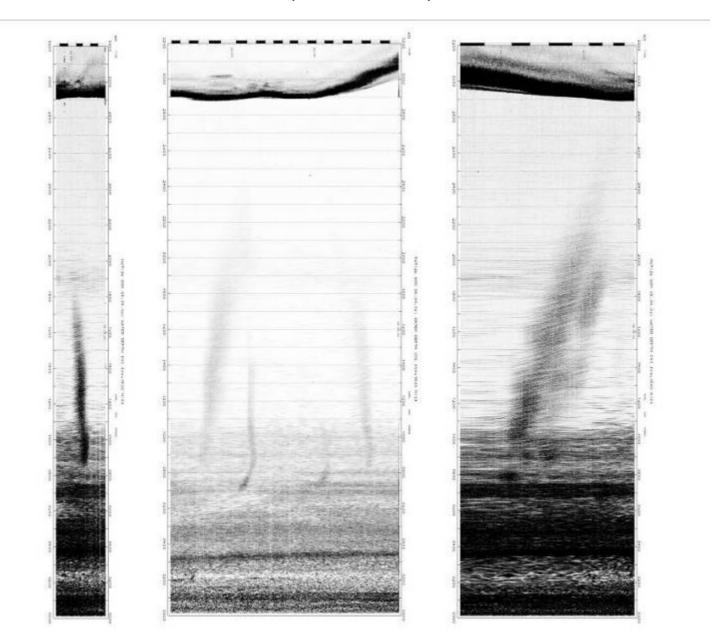
Collect additional visual measurments of bubble stream

In situ instruments

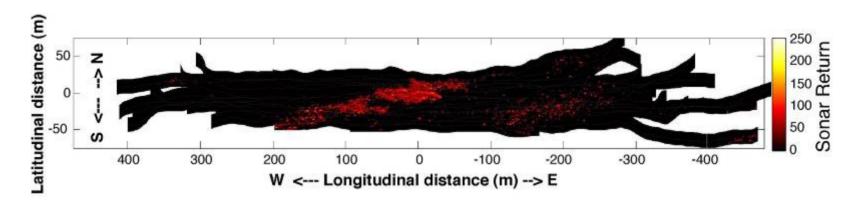


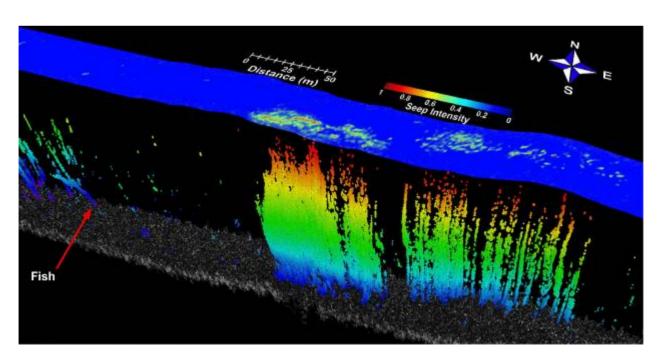


Gas Plumes from Chapopote courtesy of Volkhard Speiss



Side-scan Sonar Bubble Survey





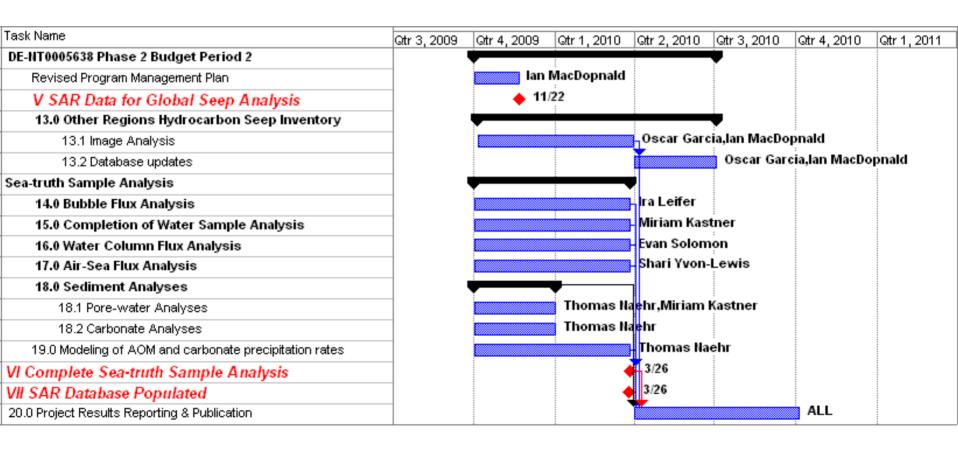
Surface Sampling Grid

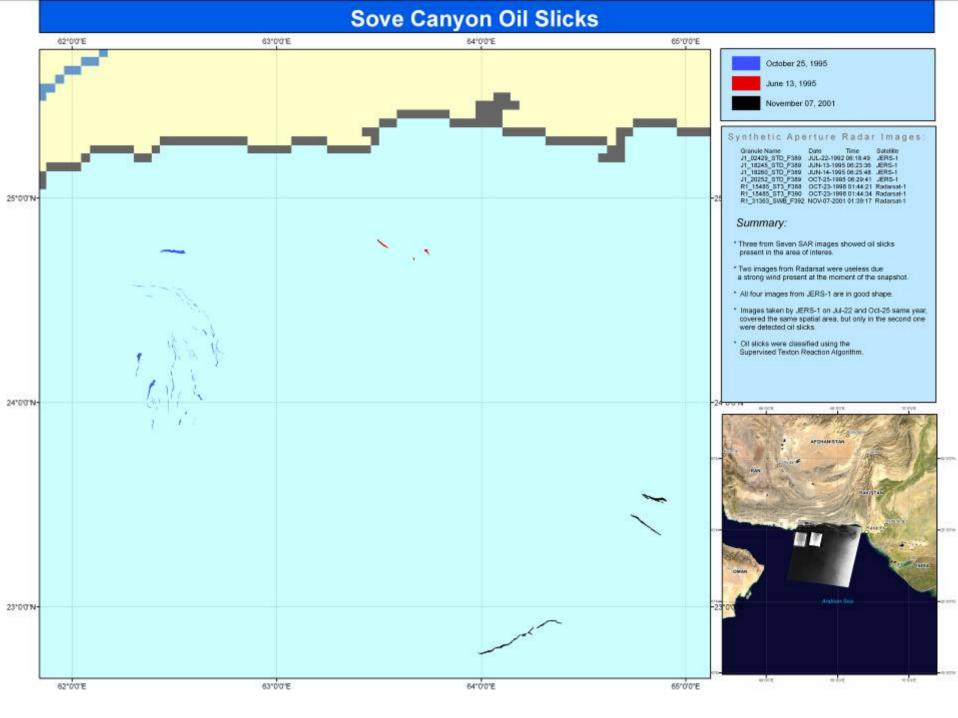
400 m 1000 m

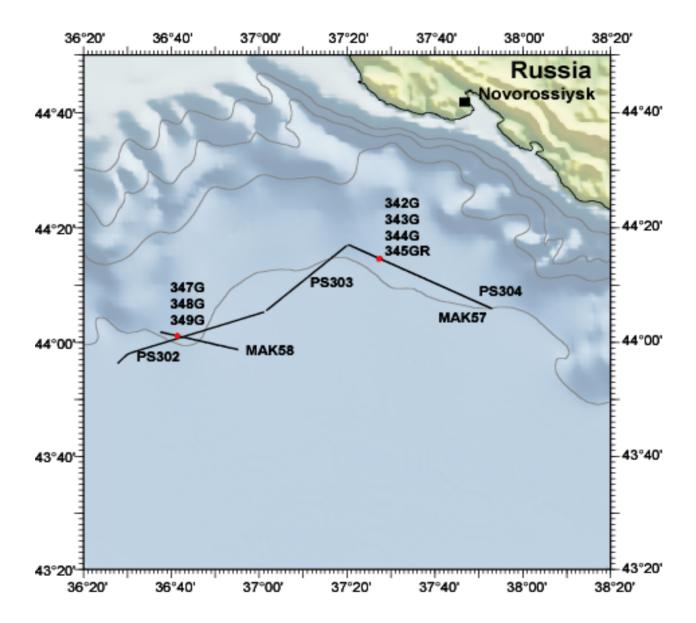
Water Column Sample in Plume

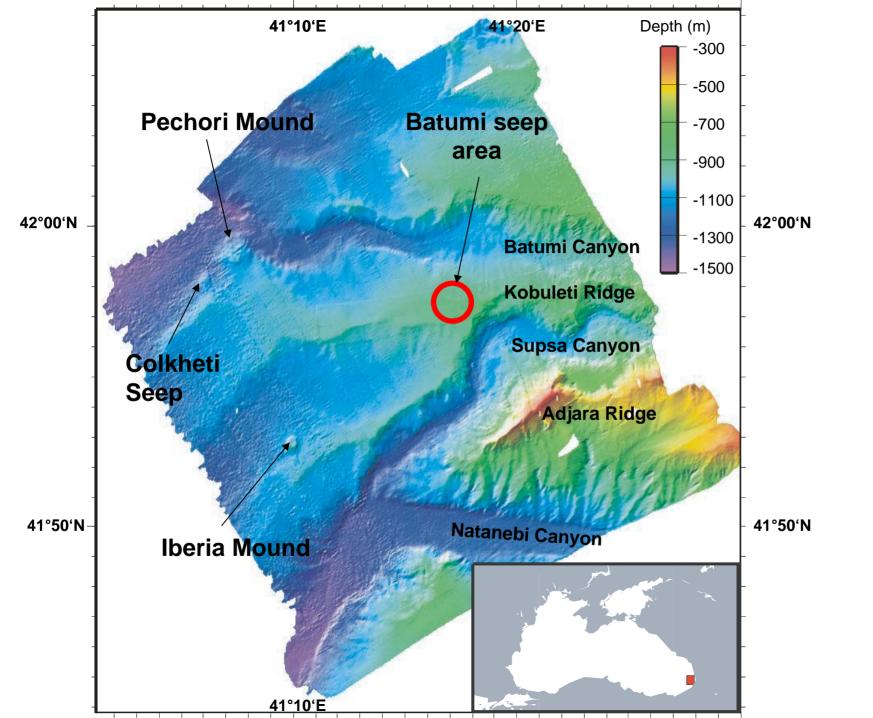


Analysis and Reporting Phase Q3 2009 - Q3 2010









Risk Management

- Technical risk
 - Short-comings in performance of sampling and monitoring equipment
 - Mitigation by field-testing methodology in Santa Barbara Channel
- Weather risk
 - Gulf of Mexico hurricane / tropical storm could cancel cruise
 - Mitigation by scheduling in July

