

UNIVERSITY OF **CENTRAL FLORIDA**

Ansys 17.2 Thermal Verification

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Abstract

Florida Turbine Technologies (FTT) relies on the software ANSYS Mechanical to perform structural and thermal analyses of turbine engines. It is important for FTT to upgrade ANSYS versions periodically to stay up to date and also because of ANSYS lack of support over older versions. Before upgrading, it is necessary for a verification process to take place and check that key features and capabilities are working similar if not better than older versions. Being a heat transfer engineer, the responsibility of performing thermal verification on the new 17.2 Ansys version was only practical. This project involved performing thermal analyses on a 2 stage turbine model that was modeled from scratch where conduction, convection, advection, and radiation forms of heat transfer are applied. Fictitious aerodynamic boundary conditions and rule of thumb heat transfer coefficients (HTCs) were provided to avoid use of proprietary information. The success criteria for the project was to compare metal nodal temperature of all nodes for both ANSYS versions 17.2 (New) and 14.5 (Current) and for the maximum temperature difference (max ΔT) to be no greater than 1°F. The max ΔT obtained was 0.135 °F. Oscillation limit (OSLM) was to be compared as well which expresses the stability of results and it had to be less than 1 which for the most part remained under 0.5 and was over 1 for no longer than 0.1 seconds. For this analysis, version 14.5 is taken as the baseline version and is assumed to be reliable.

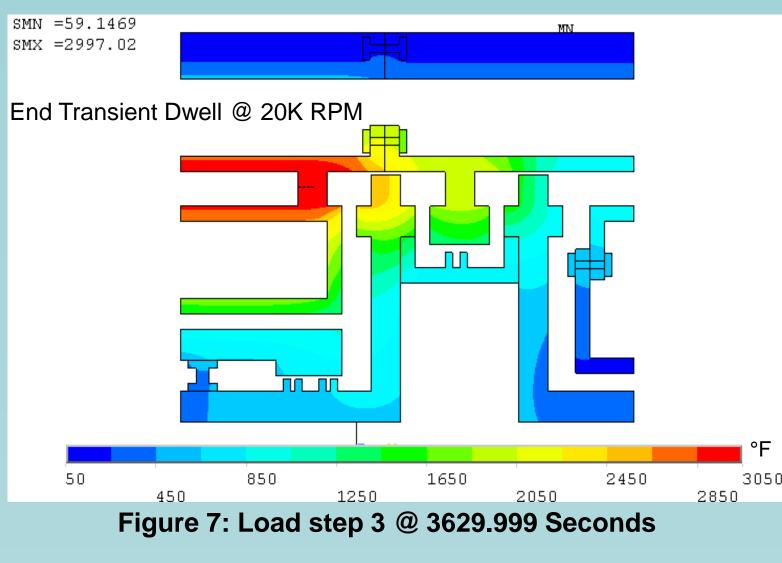
Macro for BCs

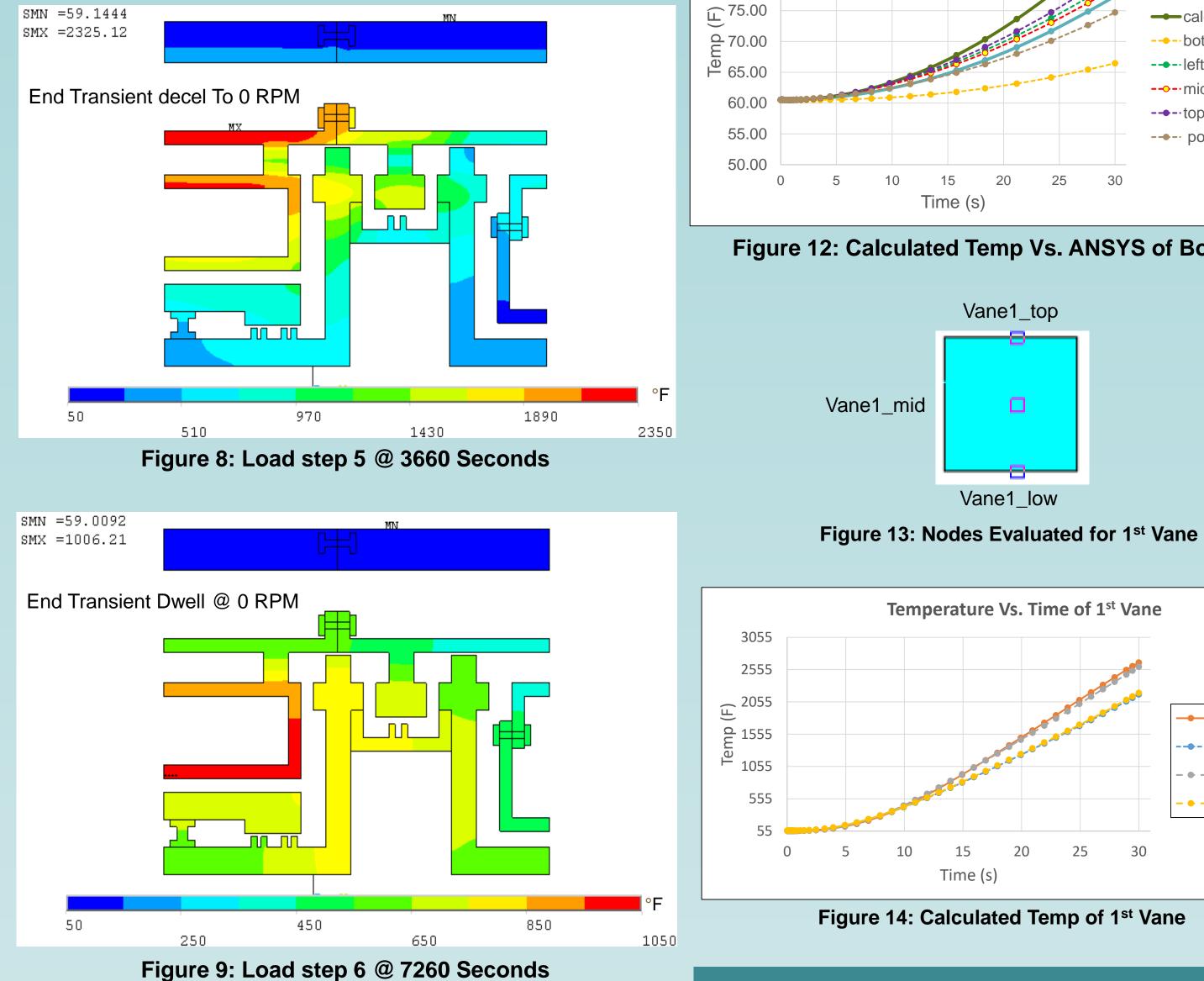
Boundary conditions have to change throughout the simulation run in order to mimic thermal behavior from the start of the engine to the end. A macro was coded in ANSYS Parametric Design Language (APDL) to change various parameters such as

- Flow rate
- Upstream temperature to all entry fluid nodes
- Heat generation on fluid nodes and bearing
- Bulk temperature and HTC values to all SURF 151 and SURF 152 elements
- Speed in rad/s

These parameters are dependent on whether to run transiently or steady state (SS) and whether the engine was at full speed 20,000 RPM or if dwelling at 0 RPM. A Do-Loop was utilized to define every BC accordingly. Figure 4 Displays the load steps that are running either at transiently or SS.

Step 1; 0.01 s SS 0 RPM Step 2; 30 s **End Transient Accel**







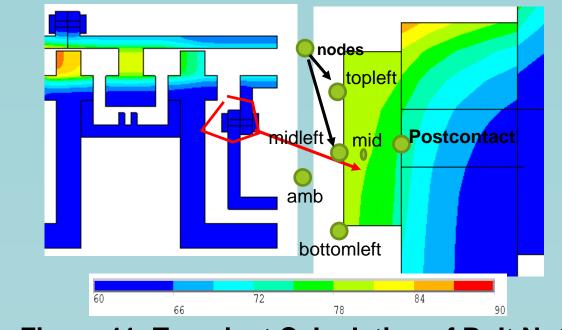


Figure 11: Transient Calculation of Bolt Nut

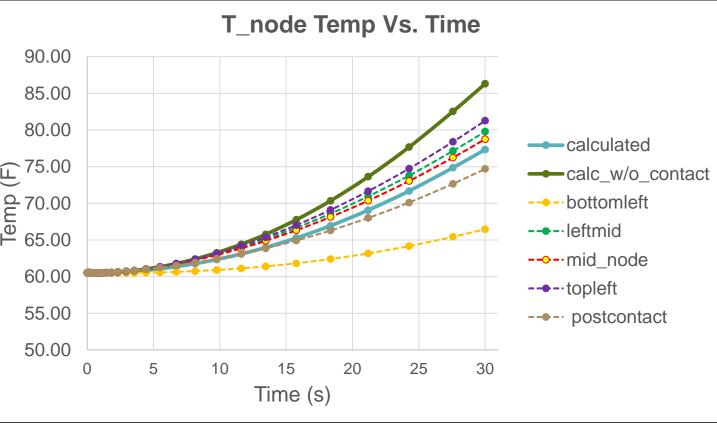


Figure 12: Calculated Temp Vs. ANSYS of Bolt Nut

---- calculated

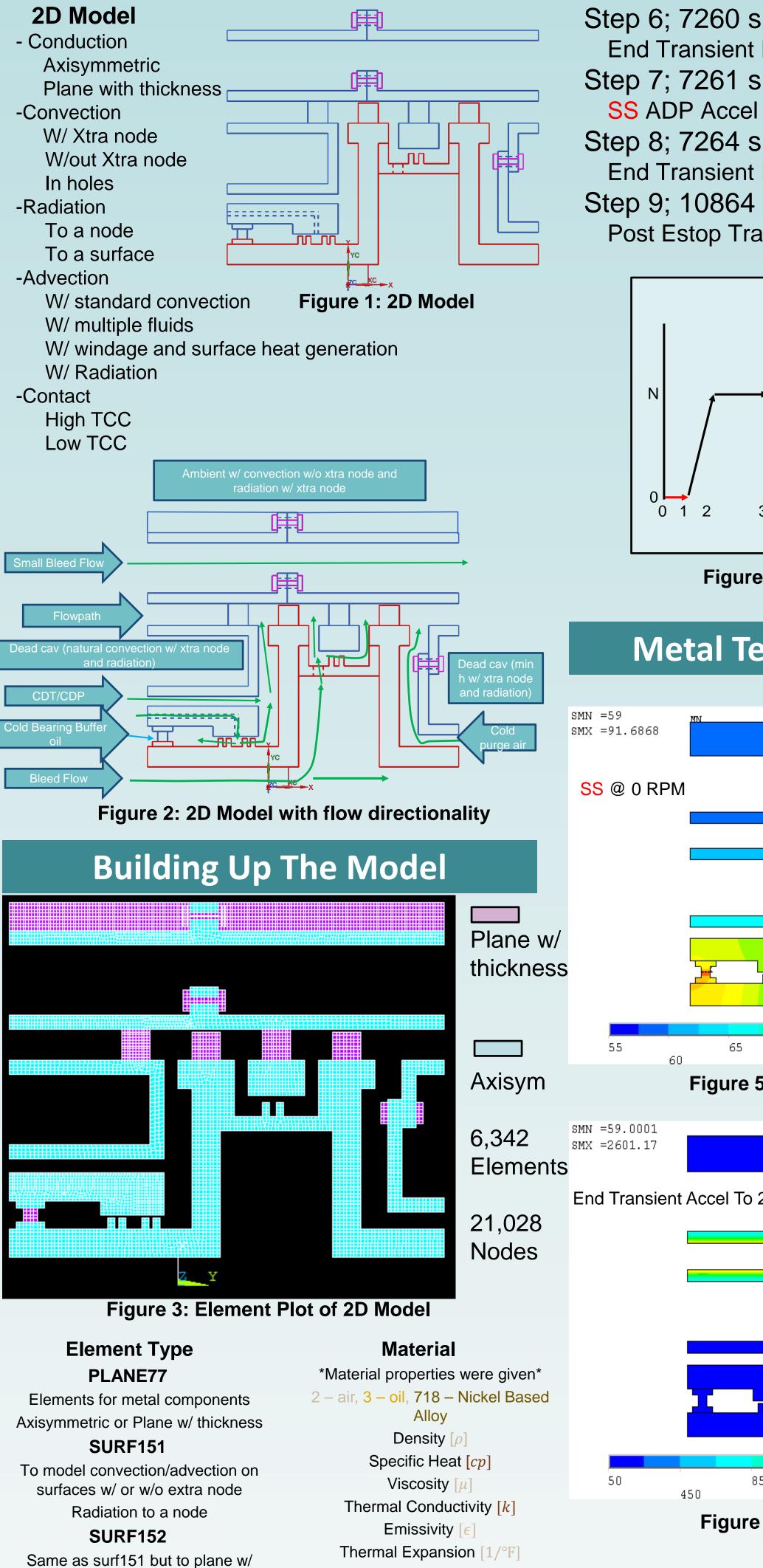
--- Vane1 top

• - Vane1_mid

- Vane1_low

30

Project Requirements & Overview



Step 3; 3629.999 s End Transient Dwell @ N RPM Step 4; 3630 s SS ADP Step 5; 3660 s **End Transient Decel** Step 6; 7260 s End Transient Dwell @ 0 RPM Step 7; 7261 s Step 8; 7264 s End Transient Estop Decel Step 9; 10864 s Post Estop Transient Dwell @ 0 RPM

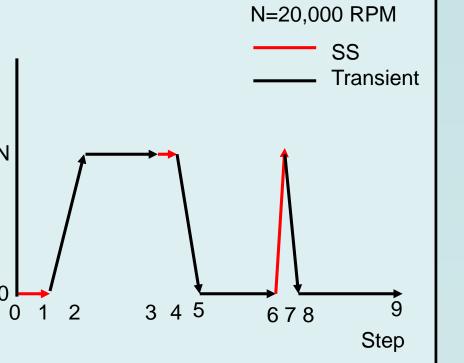
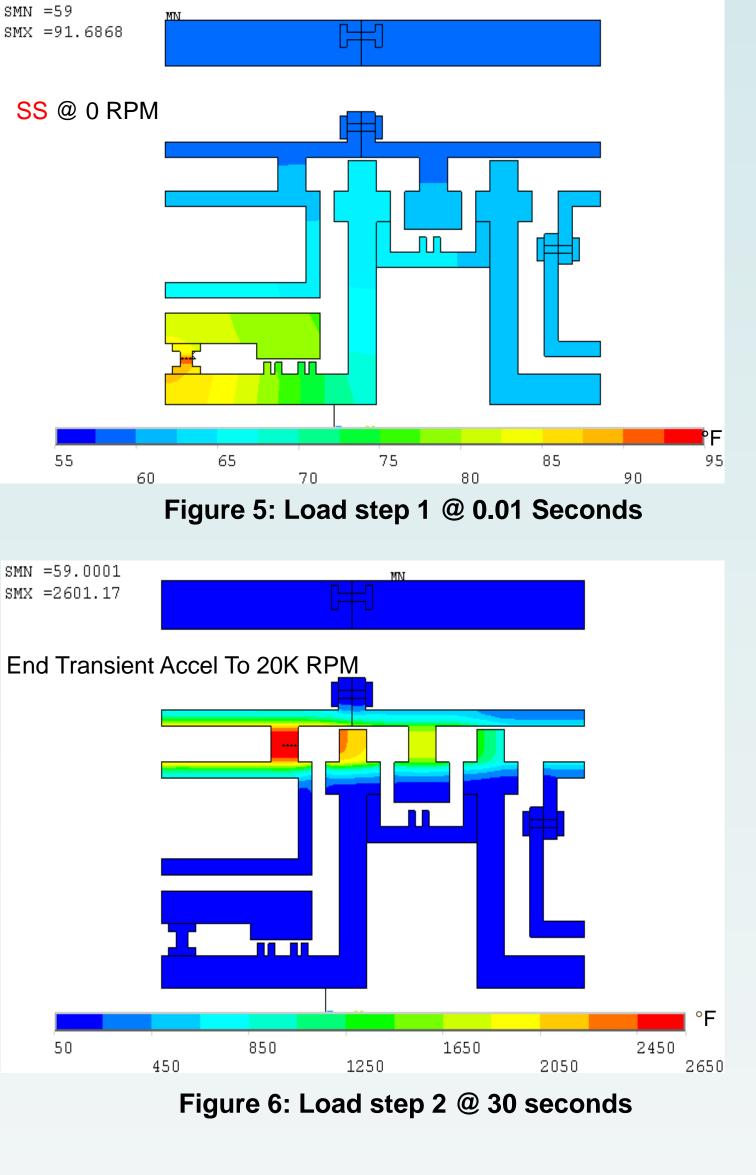


Figure 4: SS/Transient

Metal Temp at Load Steps

Post Processing & Conclusion

The post processing of the thermal analysis involved creating 2 more macros making a total of 3 macros. The 2nd macro was to obtain the nodal metal temperature of every node and create a 21,067 x 387 array outputting its respective temperature, node numbers and time sub step for each version. The 3rd macro would then take the temperature difference between both versions from the previous outputted arrays, find the max ΔT , and link that maximum to its corresponding node and time sub step. If the time sub steps are not the same between both versions, then the code would interpolate the temperature of a node in version 17.2 to match the time sub step of the baseline version 14.5. In conclusion, the maximum temperature difference obtained after comparing every nodal temperature was 0.135°F. The OSLM versus time as seen on figure 16 was obtained from within the software expressing the stability of the results. Values remained under 0.5 for most times and was greater than 1 with a duration that never exceeded 0.1 seconds. These would occur at the first sub step of a transient load step run where the previous run was at SS which is usually expected to occur. Comparing figure 15 to figure 16, it is observed that the greatest ΔT occurs when the OSLM is greater than 1. In the end, thermal verification of the 2D model was deemed successful as the success criteria were met and future verifications of ANSYS versions should now be easier for FTT to use when upgrading.



temperature distribution was more 2D than 1D as seen on figure 10. 1D Transient calculations were also performed at a bolt nut and first vane where Biot number is less than 0.1 and 1 respectively which lumped capacitance is assumed. Figure 12 calculated temperature over time for the bolt head and figure 14 for the first vane.

Hand Calculations

temperatures are correct in the sense that the software

ANSYS is performing correct heat transfer calculations

and applying the correct boundary conditions, hand

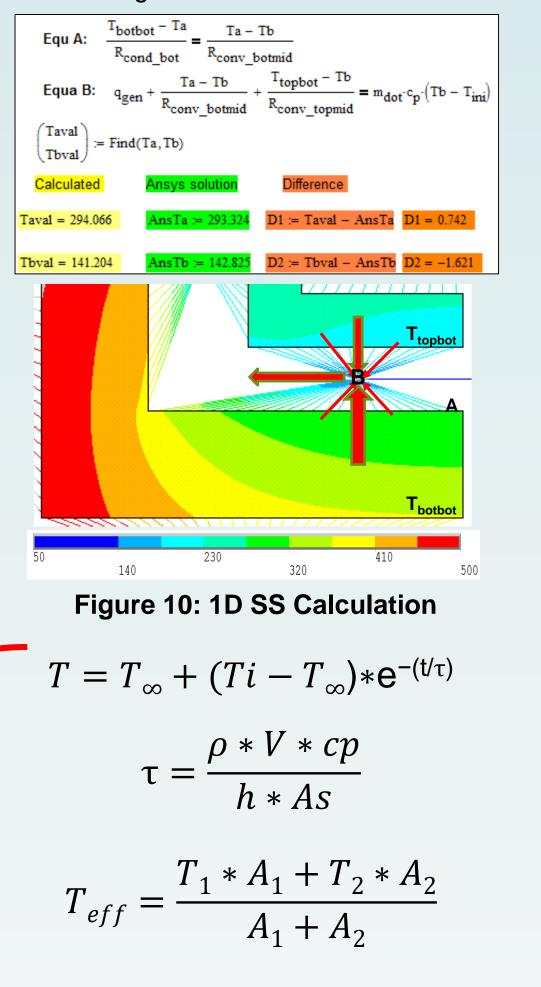
calculations were done in different locations of the model

for verification purposes. 1D SS hand calculation was

investigated between the 2nd rotor and right cavity to get

temperatures close to what ANSYS got even though the

In order to ensure that the output metal nodal



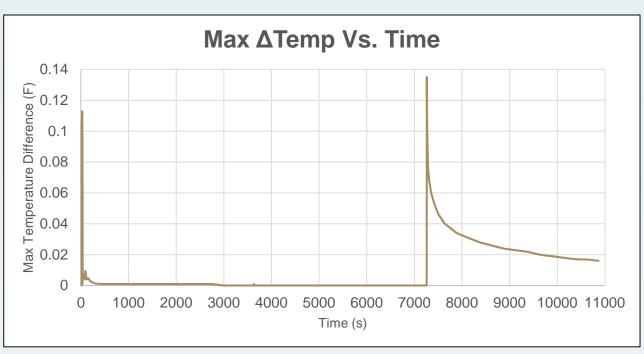
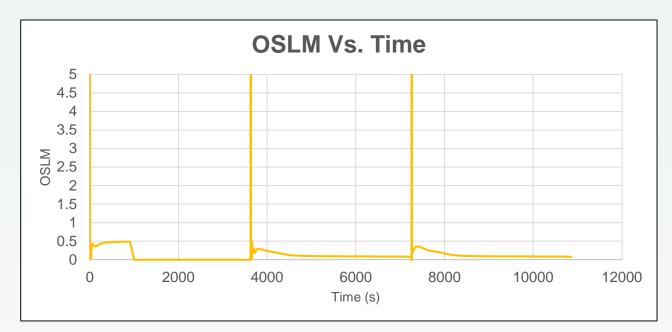


Figure 15: Max ΔTemp Vs. Time





To model fluid flow

thickness elements

TARGE169 & CONTACT172

To specify contact resistance b/w

parts





To model radiation in an enclosure



Swirl factor

Thickness

Real Constants

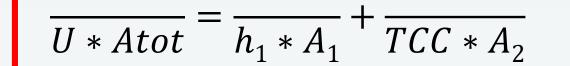




Stephan Boltzmann constant

View/Form factor

Etc....



TCC = thermal contact conductance

