

Investigation of "Smart Parts" with Embedded Sensors for Energy System Applications

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Introduction and Background

Objectives

Technical Approach

Results

Summary

Given Service Work



Motivation



- Highly efficient and environmentally benign power and fuel systems require:
 - Critical Sensing in modern power plants and energy systems
 - Higher efficiencies in energy conversion
 - Lower emission for near-zero emission power plants
 - Enhanced material systems safety









- Harsh high temperature conditions are common to the efficient conversion of fuels and processes for environmental control
- Monitoring/estimating harsh conditions in real time is needed for high system performance and assessing reliability

Gasifiers

- Up to 1600°C
- Up to 1000 PSI
- Erosive, corrosive, highly reducing

Combustion Turbines

- Up to 1350°C
- Pressure ratios of 30:1
- Thermal shock, highly oxidative
- Complex geometries



Robert Romanosky, 2013, DOE NETL Crosscutting Project Review Meeting









State-of-the-Art



- Integrated thermocouples bonded to turbine blades
- Temperature measurement enabled
- Signal is sensitive to harsh environments
- Up to 1400 °C for short time





State-of-the-Art





Hahnlen, R. M. (2009). Development and characterization of NiTi joining methods and metal matrix composite transducers with embedded NiTi by ultrasonic consolidation (Doctoral dissertation, The Ohio State University).



Overview and Rationale





Multi-material fabrication using EBM^[1]



Fabrication of electro-mechanical system^[2]

- 1. C. A. Terrazas, S. M. Gaytan, E. Rodriguez, D. Espalin, L.E. Murr, F. Medina, and R. B. Wicker, "Multi-material metallic structure fabrication using electron beam melting", Int J Adv Manuf Technol, Vol 71, Issue 1-4, pp 33-45, 2014
- 2. E. Aguilera, J. Ramos, D. Espalin, F. Cedillos, D. Muse, R. Wicker, and E. MacDonald, " 3D Printing of Electro Mechanical Systems", In: Proceedings of the 2013 Annual International Solid Freeform Fabrication Symposium, Austin, TX, USA



Overview and Rationale



- "Smart parts" with embedded sensor
 - Built-in monitoring capability
 - Accurate sensing at desired location
 - No change required post fabrication
 - Realized by 3D printing technology











Scope of Work



- Design and fabricate "smart parts" with embedded sensors.
 - EBM 3D printing technique for fabrication of "smart parts"
 - Piezoceramic sensors for temperature, strain, pressure, and structural health conditions.
- Evaluate the sensing capability of the "smart part".





Objectives



- Objective 1: Fabricate energy system related components with embedded sensors
 - Fabrication & evaluation of components without sensor by EBM
 - Manufacturing "Smart Parts" with embedded sensor by EBM
- Objective 2: Evaluate the mechanical properties and sensing functionalities of the "smart parts" with embedded piezoceramic sensors
 - Evaluation of interfacial shear properties
 - Characterization of the sensing capability
- Objective 3: Assess in-situ sensing capability of energy system parts
 - Short & long term testing to determine sensor reliability
 - Cyclic and constant loading to determine the sensing repeatability and stability





Electron Beam Melting



- Additive Manufacturing is a process for creating parts directly from a computer model based on 3D Printing technologies.
 - Builds complex, functional parts designed in a 3D CAD program
 - Eliminates variation of properties across scales
 - Wide range of applications: ceramic molds, structural ceramic parts, parts for tooling, ceramic preforms for metal matrix composites, etc





EBM Animation



by Oakridge National Laboratory





- "Stop and Go" process
- EBM fabricated manually interrupted
- Sensor embedded during fabrication at desired location





Sensing Materials



- Piezoceramic for sensing
 - Piezoelectric elements are used in smart systems due their capability of coupling energy in mechanical, thermal, and electrical domain
 - Most of applications rely on relative magnitudes of voltage, or frequency spectrum of signal modified by sensor
 - $Pb(Zr_{x}Ti_{1-x})O_{3}$, $T_{c} = 350$ °C; $LiNbO_{3}$, $T_{c} = 1200$ °C





Fabrication



- Powder Material: Ti-6Al-4V
- Mask Plate and Start Plate: Stainless steel
- Layer Thickness: 50 μm







Design of "Smart parts"







Fabrication Results





Bottom part

Masking Plate

Part press fitted into the masking plate (150 mm×150 mm) Misalignment of 435 µm



Final "smart parts"



Fabrication of Design A





Assemble of parts



After 2nd Fabrication of parts (top view)



After 2nd fabrication of parts (side view)



Dissemble of the top parts





Characterization





After EBM Capping





Metallization





Element	Weight %
Aluminum	89.3
Oxygen	6.5
Titanium	4.2

Titanium detected on alumina plate



Element	Vaporization Temperature (°C) At Pressure (Torr)						
		10-4	10 ⁻³	10-2	10-1		
Copper		1035	1141	1273	1432		
Gold		1190	1316	1465	1646		
Iron		1195	1310	1447	1602		
Platinum		1744	1904	2090	2293		
Titanium		1250	1384	1546	1742		
Tungsten		2767	3016	3309			
Yttrium		1362	1494	1650	1833		
Niobium		2355	2539				
Nickel		1257	1371	1510	1679		





Sensor Packaging Design





Sensor Packaging Fabrication









Alumina Housing by ExOne





Green Body

Sintered at 1600°C for 16hrs



Particle Size	Layer Thickness	Apparent ρ	% Relative ρ	X% Shinkage	Y% Shrinkage	Z% Shrinkage
Mixed	45µm	3.81g/cm3	96.51	8.75	10.92	8.63





Ti-6Al-4V Sensor Housing

- Ti-6Al-4V sensor housing fabricated by EBM
- SiO₂ ceramic coating
- Each applied layered is air dried
- A rougher surface finish was created for better application
- Coating is furnace cured at 650°C for 30min.
- Coating Still cracked
- Primer needed before









Successfully Fabricated Smart Parts







Smart parts Fabrication (1st run)





Force Sensing







Yirong Lin – 2016 DOE NETL Project Review – Pittsburgh, PA



Compression Force sensing







Mechanical Property Testing







Interfacial Property Enhancement Experimental Setup





Fabrication was stopped at gauge's midpoint, the machine was allowed to fully cool and the process was restarted to simulation the process of sensor embedding Tensile bars were fabricated to test mechanical properties after interrupting the fabrication process





Fabricated tensile dog-bone samples





Interfacial Property Enhancement Testing Results





Fracture Surface



Single Melt

Double Melt





Joint Microstructure





technology. Journal of Additive Manufacturing, 10, pp. 58-66

(a)



Smart Tube Fabrication









Assembled Bottom Section



Top View



50 60 70 80 90 100 110 120 130 140 150 160 170 180 190 7

Masking plate



Side View





Smart Tube Force Sensing





Temperature Sensing







Ongoing Work







Ongoing Work



- Simulation
- Hot air temperature sensing





Conclusion and Future Work

- Smart part fabrication was successful
 - " "Stop and Go" process was developed for sensor embedding
 - Masking plate was needed for the second fabrication
 - Interface between first and second EBM fabrication is key in material failure
- Sensor packaging was critical for sensor protection
 - Low pressure, high temperature harsh environment in EBM
 - Metal vaporization contamination common issue in EBM
 - Further sensor size reduction is needed for better sensor integration
- Future Work
 - IR Imaging of the fabrication process for *in situ* monitoring of paused build fabrication will be performed
 - Masking plate less fabrication process for sensor embedding
 - HIPing of the fabricated parts will be performed





Publication and Patent



- Gonzalez, J., Mireles, J., Lin, Y., and Wicker, R., 2016, "Characterization of ceramic components fabricated using binder jetting additive manufacturing technology," *Ceramics International*, in press.
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- Gonzalez, Jose A., Mireles J., Lin Y., Wicker R.B., 2015, "Fabrication of Ceramic Components Using Binder Jetting Additive Manufacturing Technology." 5th Southwest Energy Science and Engineering Symposium (SESES), April 4th, El Paso, TX.
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Intel, inc





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Thank you

Questions?





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- 1. Hahnlen, R. M. (2009). Development and characterization of NiTi joining methods and metal matrix composite transducers with embedded niti by ultrasonic consolidation (Doctoral dissertation, The Ohio State University).
- 2. C. A. Terrazas, S. M. Gaytan, E. Rodriguez, D. Espalin, L.E. Murr, F. Medina, and R. B. Wicker, "Multimaterial metallic structure fabrication using electron beam melting", Int J Adv Manuf Technol, Vol 71, Issue 1-4, pp 33-45, 2014
- 3. E. Aguilera, J. Ramos, D. Espalin, F. Cedillos, D. Muse, R. Wicker, and E. MacDonald, " 3D Printing of Electro Mechanical Systems", In: Proceedings of the 2013 Annual International Solid Freeform Fabrication Symposium, Austin, TX, USA
- 4. Rodriguez, Emmanuel, et al. "Integration of a Thermal Imaging Feedback Control System in Electron Beam Melting." *WM Keck Center for 3D Innovation, University of Texas at El Paso* (2012).





Schedule

	Year 1			Year 2			Year 3					
	Q 1	Q 2	Q 3	Q 4	Q1	Q 2	Q 3	Q 4	Q1	Q 2	Q 3	Q 4
Objective 1												
Task 1: Fabrication Characterization												
Task 2: "Smart Parts" Fabrication												
Objective 2												
Task 3: Mechanical Evaluation												
Task 4: Sensing Demonstration												
Objective 3												
Task 5: "Smart Tube" Testing												
Task 6: "Smart Premixer" Testing												
Task 7: Modification to Fabrication												
Progress Report												
Final Report												



Hardness Testing Results

- Vickers Hardness Test was performed on the completed smart part
- No large change in Hardness value throughout the smart part
- EBM Ti-6Al-4V = **40** HRC
- Annealed Ti-6Al-4V = **36** HRC









Backup

- Add Shojib slides
- Simulation results
- Premix Fabrication
- Alternative sensor materials
- Hipping process
- Sensor packaging size reduction





Milestones

	Mile- stone	Title	Description	Relation	Validation	Date
Budget F	Period 1					
	M1	Updated Project Management Plan	Complete plans for Facility, Resources, Quality, Safety, Documentation Management, etc.	Predecessor of all following tasks	Report Plan delivered to DOE PM	12/31/13
	M2	Kickoff Meeting	Review of objectives, technical and managerial approach and other facets of project	Predecessor for tasks	Presentation delivered to DOE PM	01/31/14
	M3	Embedded Sensor Parts Fabrication	Selection of High Temperature Piezoelectric Material, determination of fabrication technique for embedded sensors	Data set for 1st Decision Point	Summarized in nearest Quarterly Report	09/30/14

Budget P	eriod 2					
	M4	Mechanical strength evaluation and sensing demonstration	Interfacial shear strength and strain, temperature, and pressure sensing demonstration	Predecessor for subsequent tasks	Summarize results in Quarterly Report	12/31/14
	M5	Calibration of Sensor performance	Calibration of sensor, determine the sensitivities of strain, temperature, and pressure sensing	Predecessor for subsequent tasks	Summarize results in Quarterly Report	03/30/15
	M6	Reliability Testing	Sensor reliability, repeatability, and stability testing	Data set for 2nd Decision Point	Summarize results in Quarterly Report	09/30/15

Budget Period 3

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	M7	Case study 1: "smart tube"	Demonstration of embedded sensing capability for its usage in a combustion system	Predecessor for subsequent tasks	Summarize results in Quarterly Report	12/31/15
	M8	Case study 2: "smart premixer"	Demonstration of embedded sensing of a premixer for turbine system	Data set for 3rd Decision Point	Summarized in Quarterly Report	06/30/16
	M9	Modification to fabrication process	Fabrication parameter optimization based on Case study testing results	Predecessor for subsequent tasks	Summarize results in Quarterly Report	09/30/16





Facility

Additive Manufacturing





