

Distributed fiber sensing systems for 3D combustion temperature field monitoring in coal-fired boilers using optically generated acoustic waves

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---Increase

OBJECTIVES

- 1. This poster presents a novel distributed optical fiber sensing system for the real-time monitoring of spatial and temporal distributions of high temperature profiles in the boiler of fossil fueled power plants.
- 2. According to the principle of pyrometer system, speed of the acoustic waves depends on the temperature of gaseous medium.
- 3. Photoacoustic material coated optical fiber sidewalls will generate acoustic waves. Fiber Bragg gratings (FBG) which can be multiplexed within one optical fiber will be used to detect acoustic waves. A 3D temperature distribution profile will be reconstructed using Gaussian Radial Basis Functions (GRBF) based on the sparse measurement data.
- 4. At this point, a simulation model for furnace temperature profile has been built, a sidewall ultrasound probe has been fabricated and tested, and a water temperature test has been performed.

Significance

1.Distributed fiber sensors utilizing optical-acoustic measurement techniques.

2.Allow for never before seen

measurement of the boiler



Fig.1 Distributed fiber sensor

PRINCIPLE

temperature field.



Fig.3 Reconstruct the 3D high temperature distribution within a

boiler via a novel fiber optic distributed temperature sensing system

□ Speed of acoustic waves depend on the temperature of gaseous medium.

Fig.2 Survive high temperature

□ The TOF (time-of-flight) of an acoustic signal over a propagation path can be calculated as:

 $TOF(l_j) = \int \frac{1}{C(x, y, z)} dl_j = \int \frac{1}{Z \sqrt{T(x, y, z)}} dl_j$

C(x, y, z) the velocity of sound at position (x, y, z)the heats ratio Z

- d(x, y, z) the reciprocal of velocity
 - the number of paths;

RELATED ACHIEVEMENTS

using optically generated acoustic waves.

1. Support 1 Postdoc, 1 PhD student, 1 REU student.

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Unimodal Symmetric $T(x, y) = 1000 + 600 \sin(\pi x / length) \sin(\pi y / height)$

Real temperature field Reconstructed temperature field



Fig. 9 In the simulation, 10 sensors are evenly distributed, 10 basis functiones are used and 24 paths are chosen. The matching error is 1.95%.



Fig. 10 In the simulation, 10 sensors are evenly distributed, 10 basis functions

are used and 24 paths are chosen. The matching error is 0.8%.

Unimodal Deflection $T(x, y) = 600 \exp((-(x-4)^2) / length - ((y-3)^2) / (2*height)) + 1000$

Real temperature field

Reconstructed

temperature field

- 1. Establish a boiler furnace temperature distribution model and guide the design of the sensing system;
- 2. Develop the sensors with one active sensing element on each fiber as well as a temperature distribution reconstruction algorithm for proof-of-concept;
- 3. Develop the distributed sensing system to integrate multiple active sensing elements on a single optical fiber.