



# An Information Theoretic Framework and Self-organizing Agent-based Sensor Network Architecture for Power Plant Condition Monitoring

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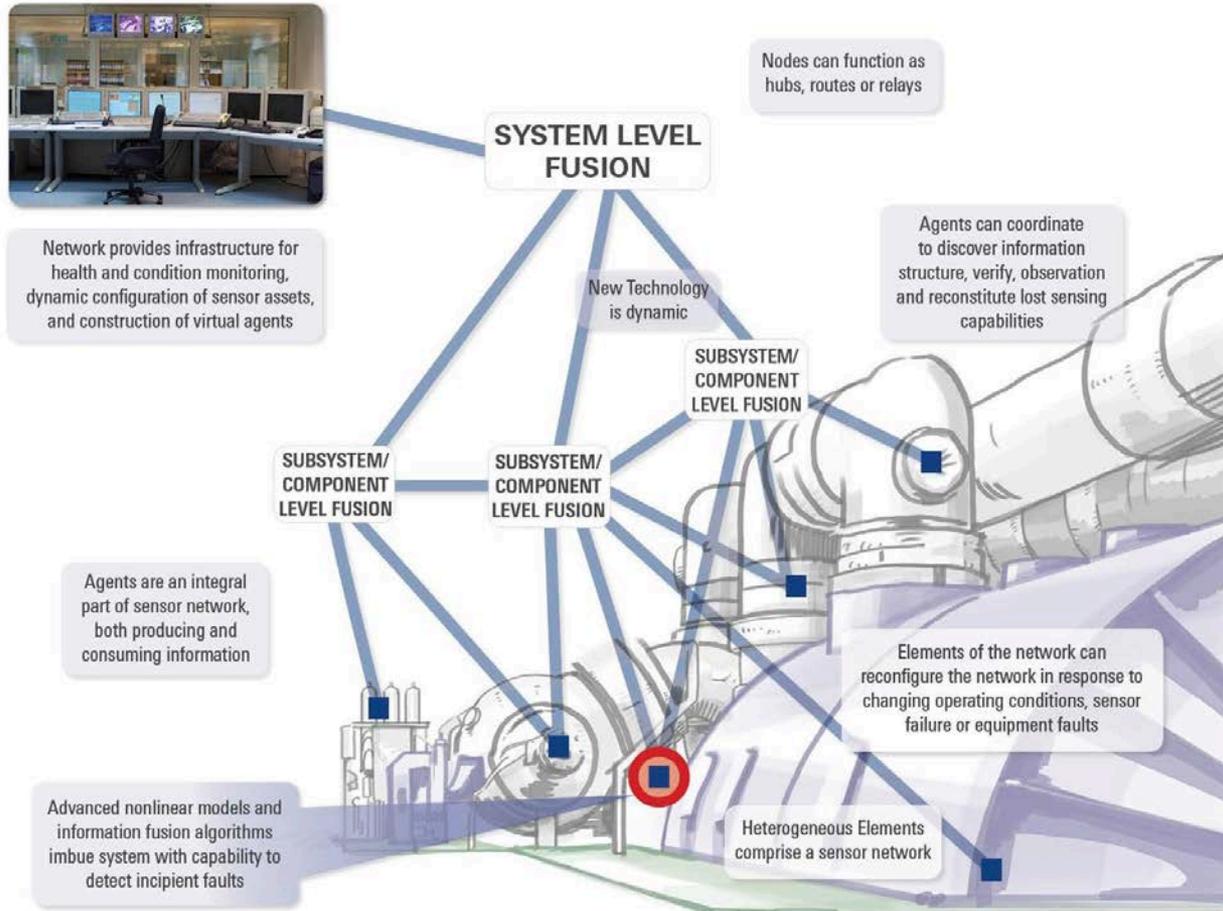
2016 Crosscutting Research Review  
April 20, 2016

# Agenda

- Introduction
  - Distributed Health and Condition Monitoring
- Information Measures
  - Entropy/Information
  - General information measures
- Information Structure of Systems
  - Properties of information
  - System decomposition
  - Computation of information measures
  - Detecting changes in system structure

# Introduction

# Production Systems



# Information Measures

# Information Theory

- **Information is the amount of surprise contained in the data;**
  - Data that tells you what you already know is not informative,
  - Not all data is created equal.
- **The fundamental measure of information is *Shannon entropy* is**

$$H(X) = - \sum_{x \in \mathcal{X}} p(x) \log_d p(x),$$

**where  $X \in \mathcal{X}$  is a discrete R.V.,  $\mathcal{X}$  is a finite set known as the alphabet, and  $p(x) = \Pr\{X = x\}$ .**

# The Multivariate Case

- For a pair of discrete R.V.'s  $(X, Y)$  with joint and conditional distributions  $p(x, y)$  and  $p(x|y)$ , the joint and conditional entropies are, respectively:

$$H(X, Y) = - \sum_{x \in \mathcal{X}} \sum_{y \in \mathcal{Y}} p(x, y) \log_2 p(x, y)$$

$$H(X|Y) = - \sum_{x \in \mathcal{X}} \sum_{y \in \mathcal{Y}} p(x, y) \log_2 p(x|y)$$

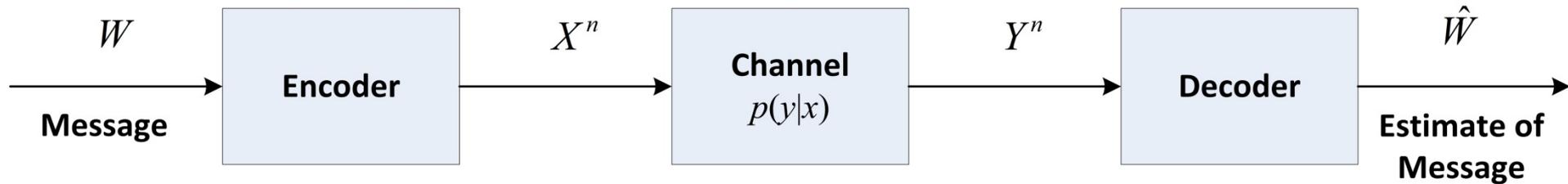
- The relationship between these R.V.'s is captured by ***Mutual Information***:

$$I(X; Y) = \sum_{x \in \mathcal{X}} \sum_{y \in \mathcal{Y}} p(x, y) \log_2 \frac{p(x, y)}{p(x)p(y)}$$

- ***Mutual Information and Shannon Entropy*** are related by:

$$I(X; Y) = H(X) - H(X|Y)$$

# Information Channels



- Let  $\mathcal{X}$  and  $\mathcal{Y}$  be the *input alphabet* and *output alphabet*, respectively, and let  $S$  be the set of channel states. An information channel is a system of probability functions:

$$p_n(\beta_1, \dots, \beta_n | \alpha_1, \dots, \alpha_n : s)$$

where  $\alpha_1, \dots, \alpha_n \in \mathcal{X}$ ,  $\beta_1, \dots, \beta_n \in \mathcal{Y}$ , and  $s \in S$  for  $n = 1, 2, \dots$

- Mutual information between the input and output provides a measure of *channel transmittance*:

$$T(\mathcal{X}; \mathcal{Y}) = H(\mathcal{X}) - H(\mathcal{X} | \mathcal{Y})$$

- The maximum over all distributions is known as the *channel capacity*.

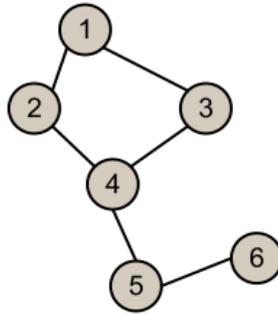
# Information Structure

# Information Structure

- **The communications topology determined by available observation processes;**
  - fusing information from multiple sensors,
  - Reconstituting lost or degraded sensing,
  - Detect system changes reflected in changing communication topology.
- **Identify “correlative” structure of sensor data;**
  - Provides means of identifying relevant (possibly abstract) subsystems,
  - Basis for mesoscopic models and “summary” variables.

# System Structure

## Undirected Graph & Adjacency Matrix



Undirected Graph

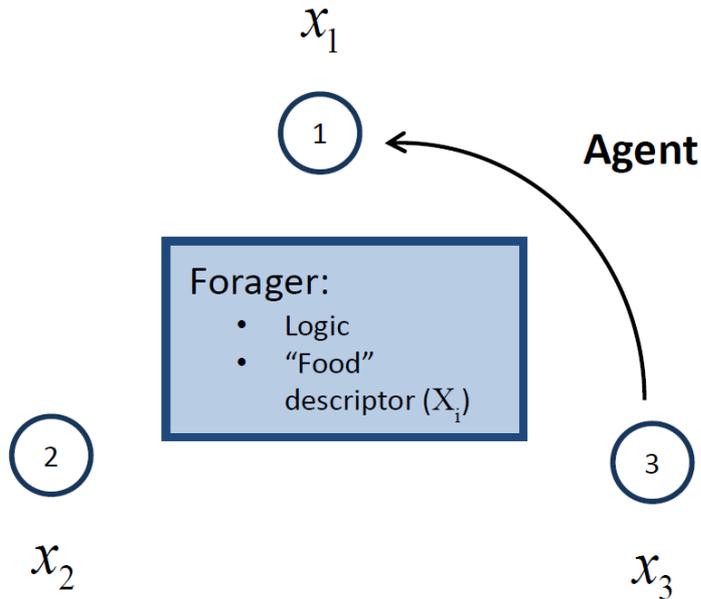
	①	②	③	④	⑤	⑥
①	0	1	1	0	0	0
②	1	0	0	1	0	0
③	1	0	0	1	0	0
④	0	1	1	0	1	0
⑤	0	0	0	1	0	1
⑥	0	0	0	0	1	0

Adjacency Matrix

$$M_I = \begin{bmatrix} \hat{I}(Z_1; Z_1) & \hat{I}(Z_1; Z_1) & \dots & \hat{I}(Z_1; Z_n) \\ \hat{I}(Z_2; Z_1) & \hat{I}(Z_1; Z_1) & & \hat{I}(Z_1; Z_1) \\ \vdots & & \ddots & \vdots \\ \hat{I}(Z_n; Z_1) & \hat{I}(Z_1; Z_1) & \dots & \hat{I}(Z_1; Z_n) \end{bmatrix}$$

Where  $Z_i$  represents  $i^{th}$  sensor in power plant

# Agents and Observations



$x_i$ : a time series which is the observations at node  $i$

$w_i$ : a time series which is the partial observations of  $x_i$  at node  $i$

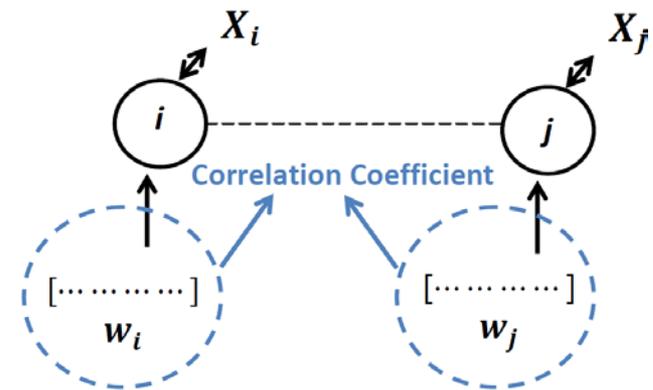
Agent going from home node 3 to node 1:

## Behavior:

The agent carries the data,  $w_3$ , from its home node to the next node.

## Food Definition:

The similarity, Correlation Coefficient, between the time series  $w_3$  and  $w_1$ .



# Initialization

**Time Duration at this Iteration = [0:T]**

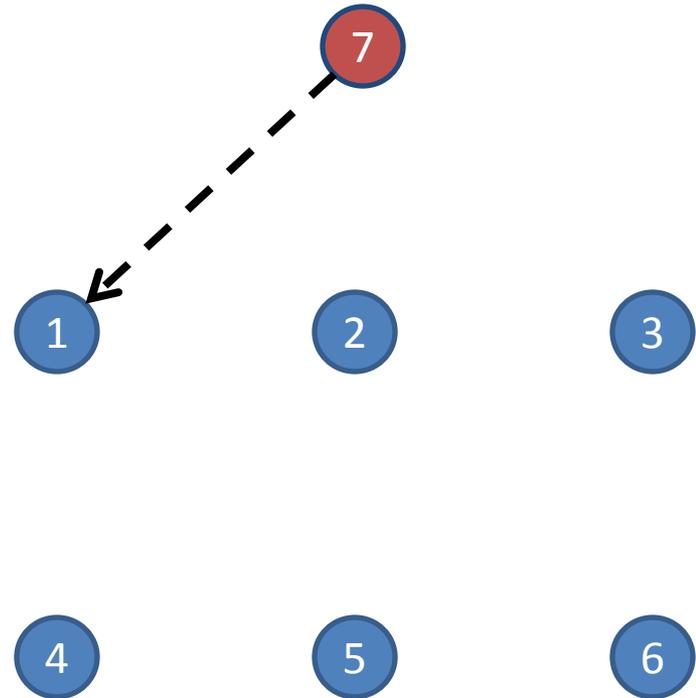
**Home Node = 7**

**Current Node = 7**

**Carrying Data =  $X_7$  ([0:T])**

**Forward Flag = 1**

**Selected Next Node = 1**



# Iteration 1

**Time Duration at this Iteration = [0:T]**

**Home Node = 7**

**Current Node = 1**

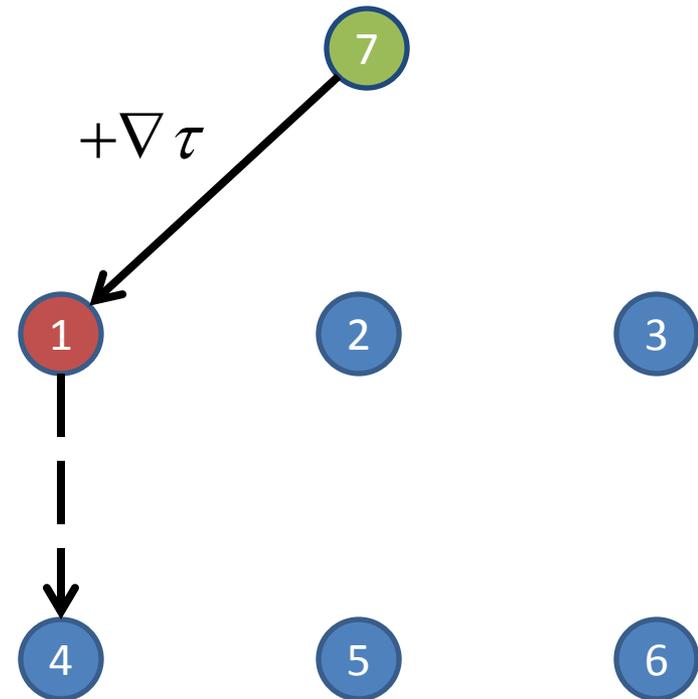
**Carrying Data =  $X_7$  ([0:T])**

**Correlation Coefficient to Calculate is  
between:  $\{ X_7$  ([0:T]) ,  $X_1$  ([0:T])  $\}$**

**Correlation = Not High**

**Forward Flag = 1**

**Selected Next Node = 4**



# Iteration 3

**Time Duration at this Iteration = [T:2T]**

**Home Node = 7**

**Current Node = 4**

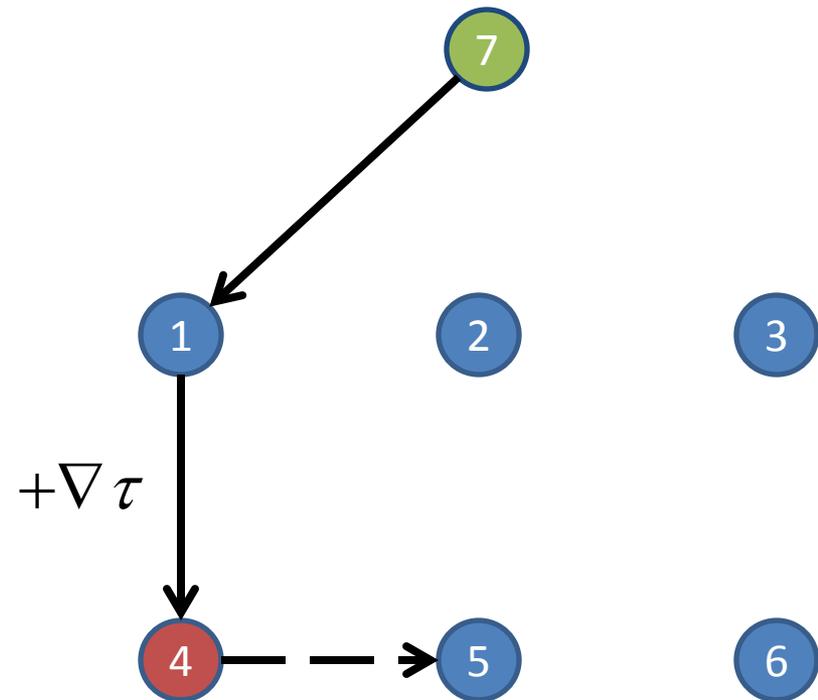
**Carrying Data =  $X_7$  ([0:T])**

**Correlation Coefficient to Calculate is between:  $\{ X_7$  ([0:T]) ,  $X_4$  ([T:2T]) }**

**Correlation = Not High**

**Forward Flag = 1**

**Selected Next Node = 5**



# Iteration 4

Time Duration at this Iteration =  $[2T:3T]$

Home Node = 7

Current Node = 5

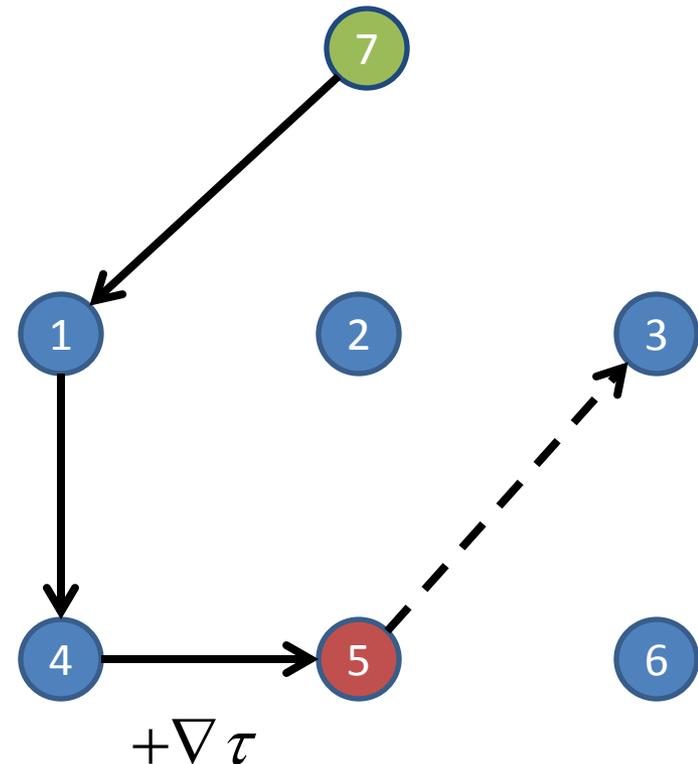
Carrying Data =  $X_7 ([0:T])$

Correlation Coefficient to Calculate is  
between:  $\{ X_7 ([0:T]) , X_5 ([2T:3T]) \}$

Correlation = Not High

Forward Flag = 1

Selected Next Node = 3



# Iteration 5

**Time Duration at this Iteration = [3T:4T]**

**Home Node = 7**

**Current Node = 3**

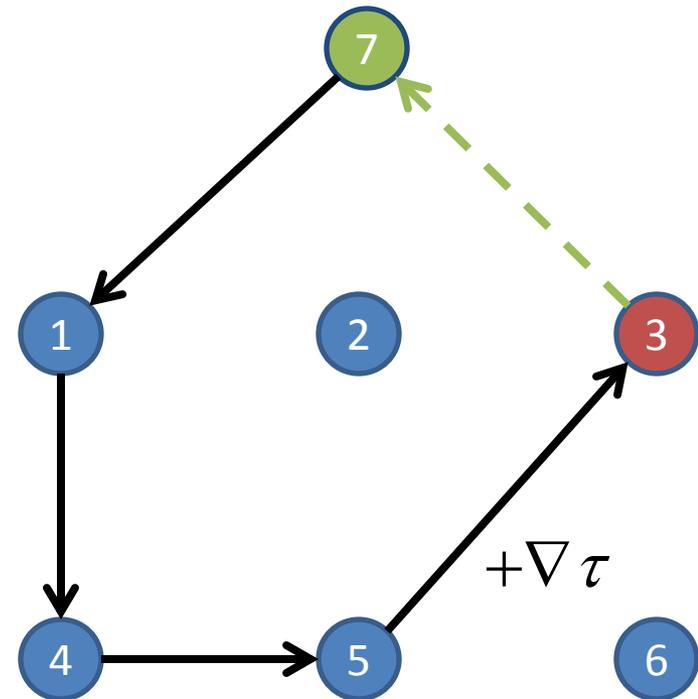
**Carrying Data =  $X_7$  ([0:T])**

**Correlation Coefficient to Calculate is between:  $\{ X_7$  ([0:T]) ,  $X_3$  ([3T:4T])  $\}$**

**Correlation = High**

**Forward Flag = 0**

**Selected Next Node = 7 (Home Node)**



# Iteration 6

Time Duration at this Iteration = [4T:5T]

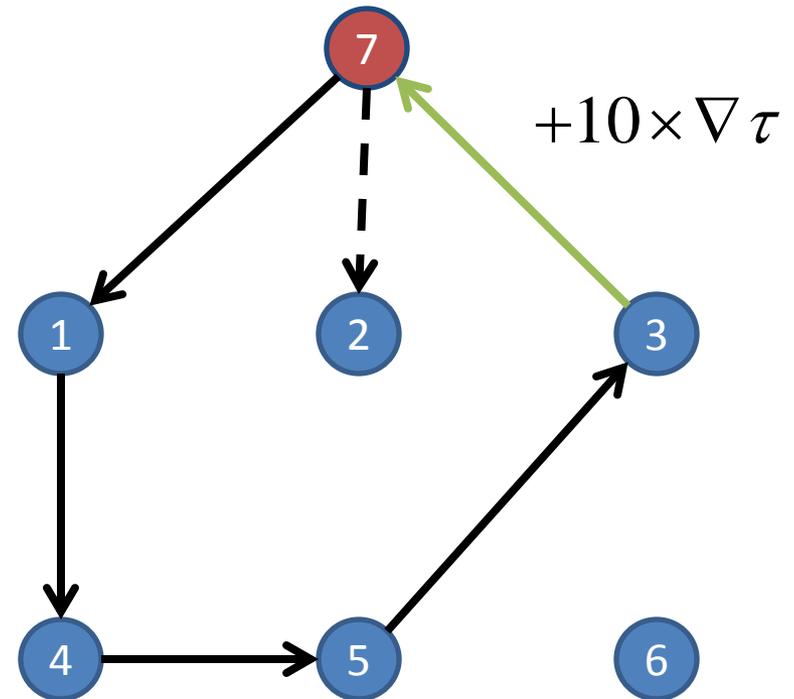
Home Node = 7

Current Node = 7

Carrying Data =  $X_7$  ([0:T])

Forward Flag = 1

Selected Next Node = 2



# Graph Similarity

- Our graphs are weighted bidirectional graphs where  $w_{ij} \neq w_{ji}$ .
- In this case the Laplacian matrix is not symmetric and therefore its eigenvalues are not necessarily real positive numbers. This makes some problems in calculating the spectral distance with complex numbers.
- Use symmetrized Laplacian

$$L(G) = D(G) - \left( A(G) + A(G)^T \right)$$

# Spectral Distance Formula

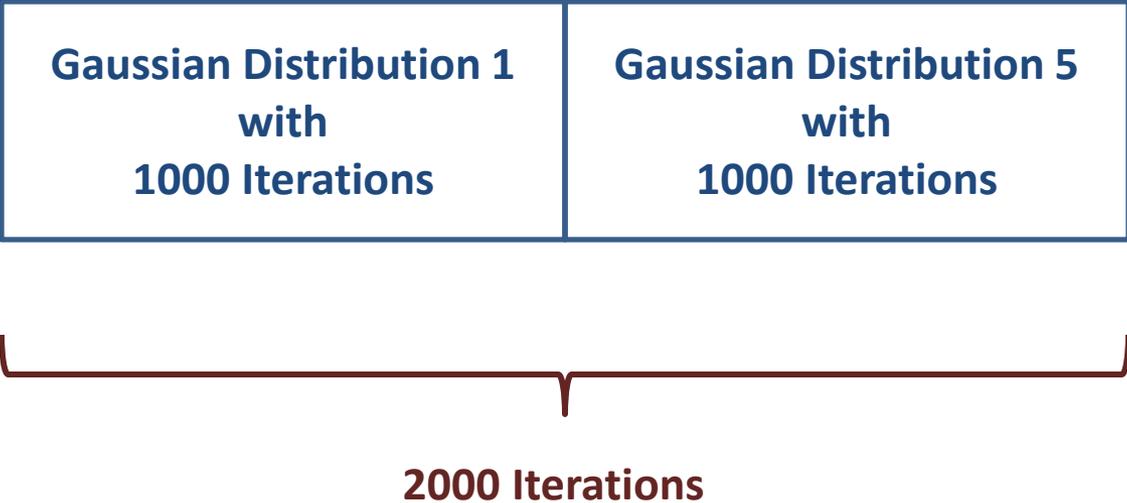
$$d_k(G, H) = \begin{cases} \sqrt{\frac{\sum_{i=N-k}^{N-1} (\lambda_i - \mu_i)^2}{\sum_{i=N-k}^{N-1} \lambda_i^2}} & \text{if } \sum_{i=N-k}^{N-1} \lambda_i^2 \leq \sum_{i=N-k}^{N-1} \mu_i^2 \\ \sqrt{\frac{\sum_{i=N-k}^{N-1} (\lambda_i - \mu_i)^2}{\sum_{i=N-k}^{N-1} \mu_i^2}} & \text{if } \sum_{i=N-k}^{N-1} \lambda_i^2 > \sum_{i=N-k}^{N-1} \mu_i^2 \end{cases}$$

- $\lambda_i$  represents the eigenvalues of the Laplac matrix for graph G
- $\mu_i$  represents the eigenvalues of the Laplac matrix for graph H
- use  $\lfloor \frac{N}{2} \rfloor$  largest eigenvalues

# Synthetic Test Data

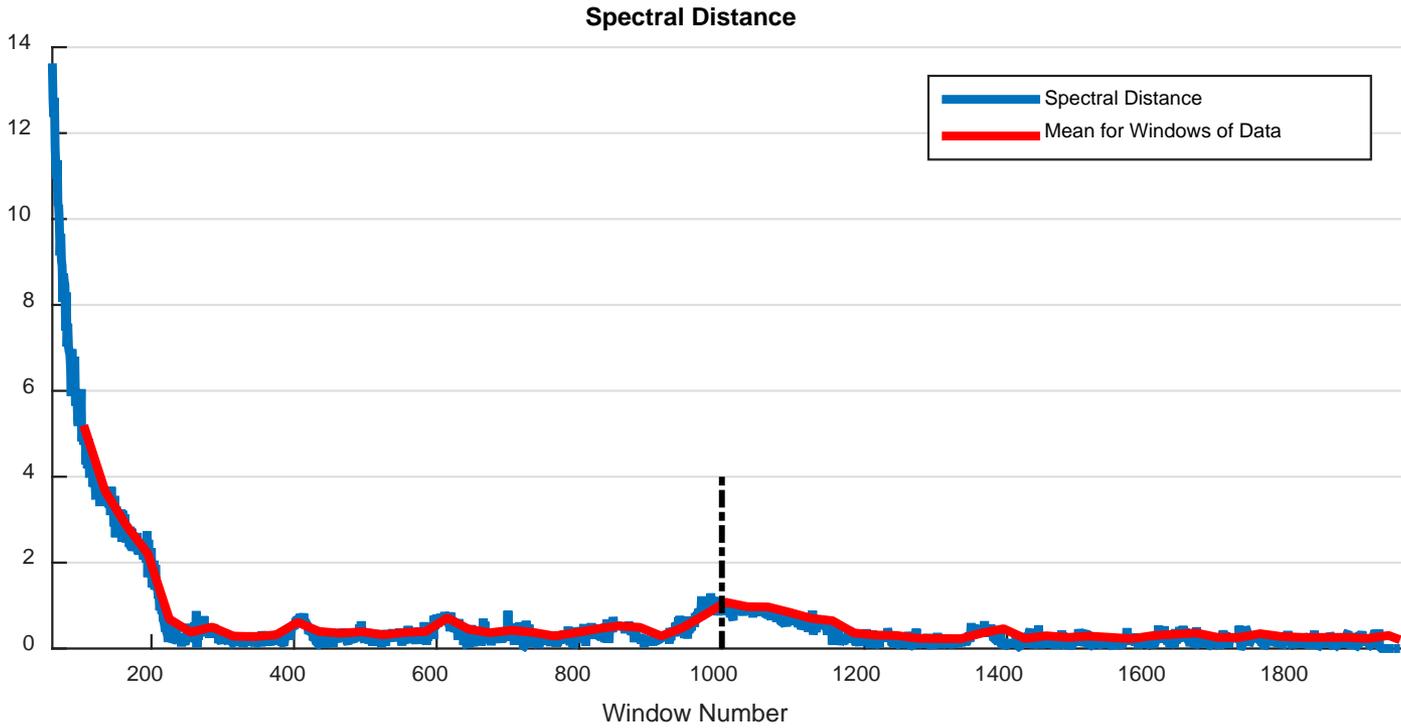
**Gaussian Distribution 1  
with  
1000 Iterations**

**Gaussian Distribution 5  
with  
1000 Iterations**



**2000 Iterations**

# Results

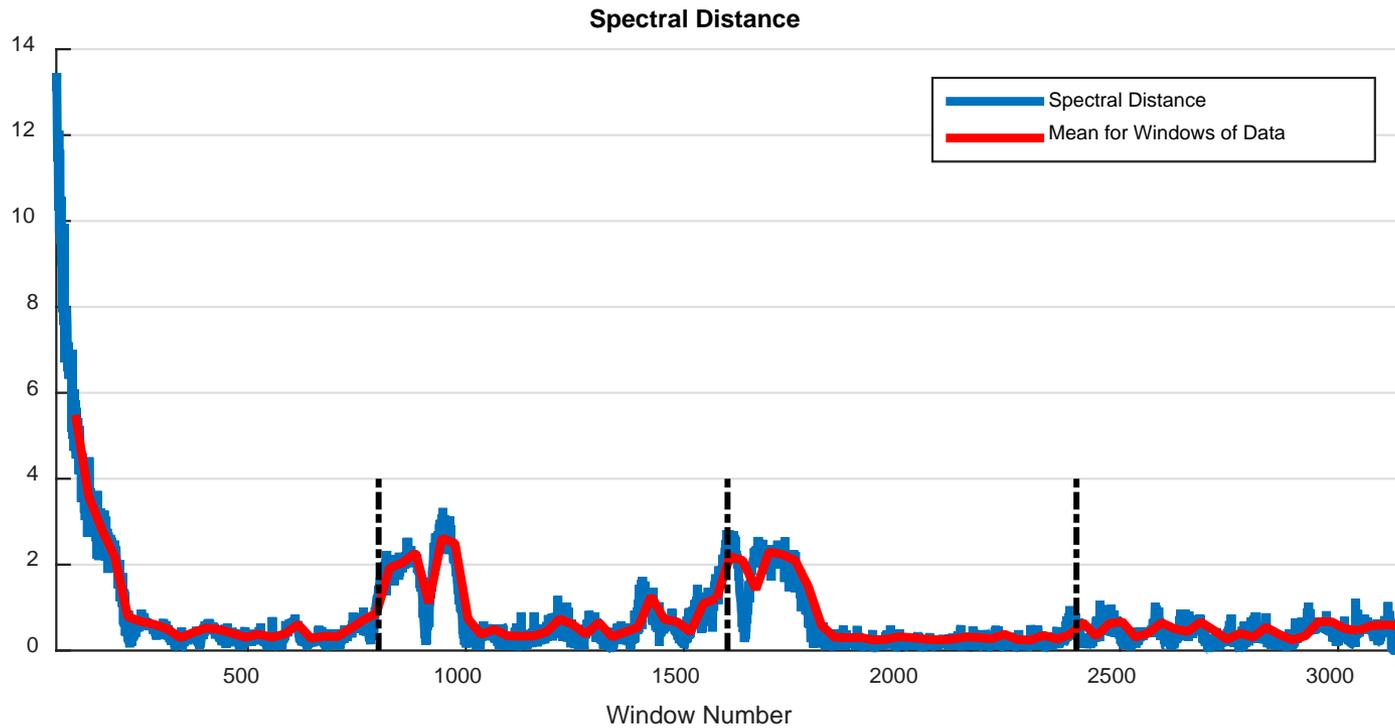


# Test Data

<b>Gaussian Distribution 3 with 800 Iterations</b>	<b>Gaussian Distribution 4 with 800 Iterations</b>	<b>Gaussian Distribution 5 with 800 Iterations</b>	<b>Gaussian Distribution 3 with 800 Iterations</b>
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**3200 Iterations**

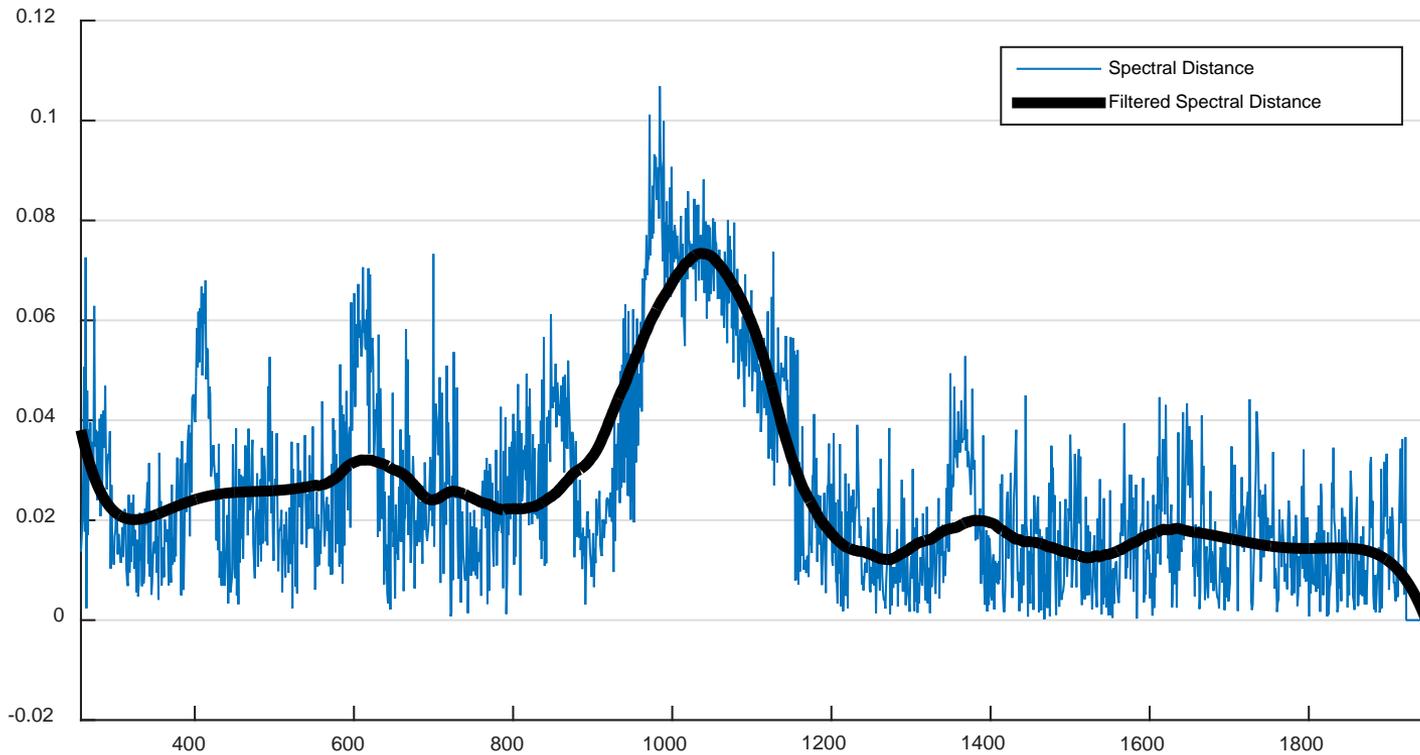
# Results



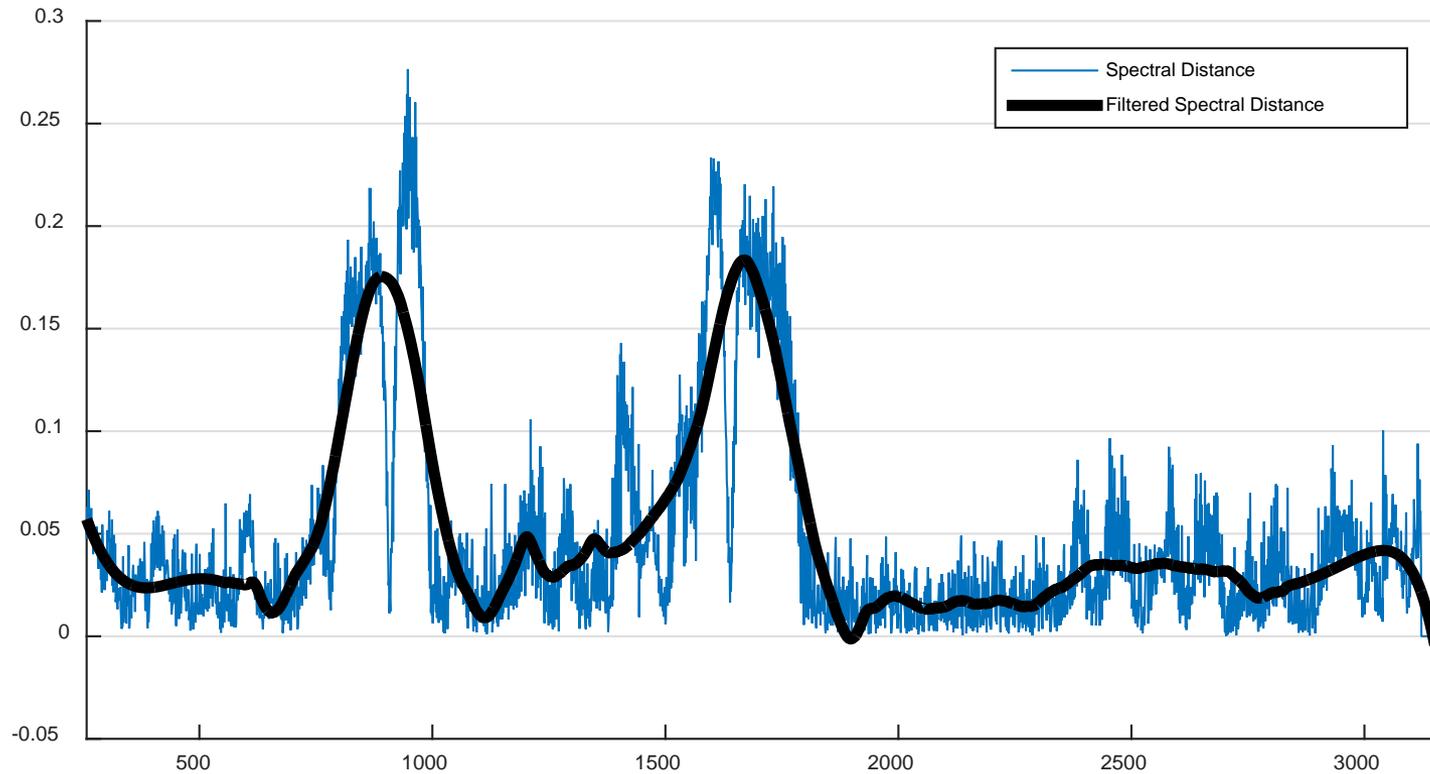
# Change Point Detection

- **Before calculating the change points, smoothing the distance vector eliminates small fluctuations.**
- **Filtered instead of Averaging is recommended.**
- **We suggest using “Savitzky-Golay FIR Smoothing Filter”.**

# Results: First Data Set



# Results-Second Data Set



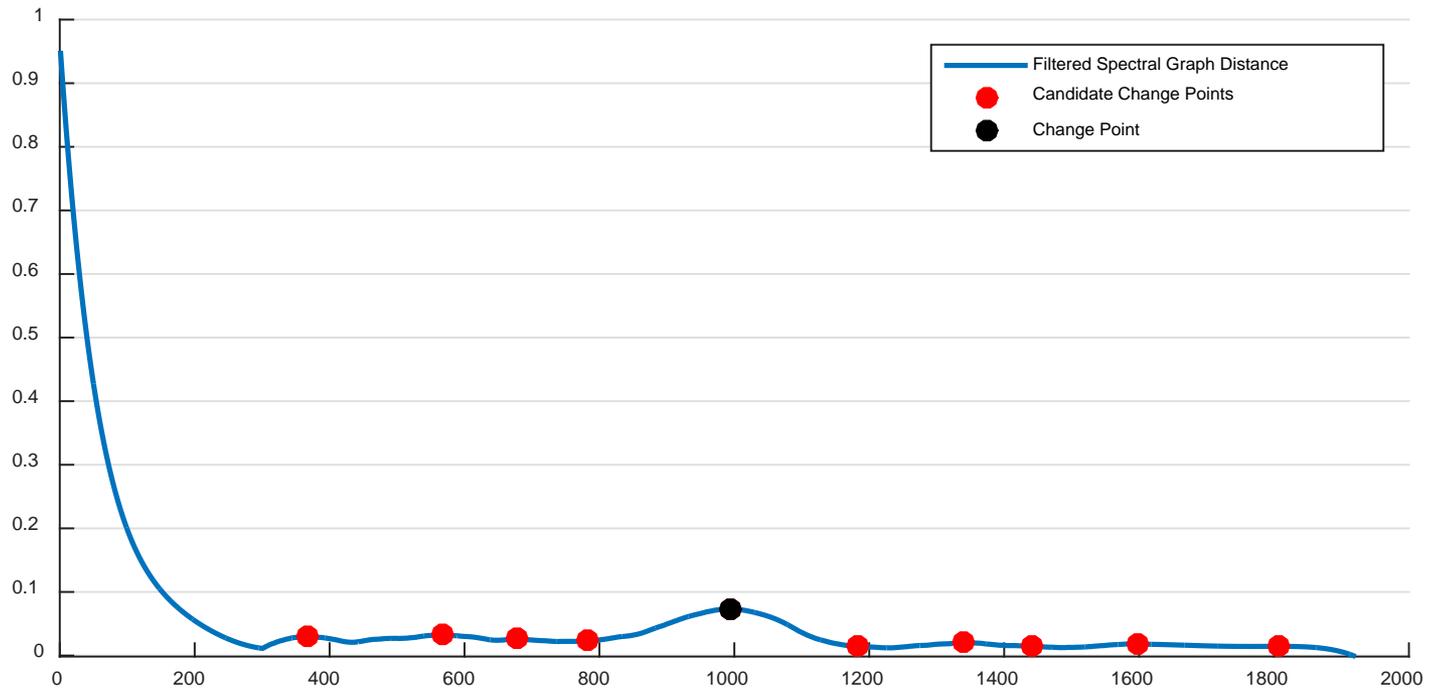
# Change Point Detection Methods

- **Minimum Mean Square Error (MMSE)**
- **Cumulative Summation (CUSUM)**
  
- **Combine above methods using bootstrapping and with confidence level calculations to eliminate false change points.**

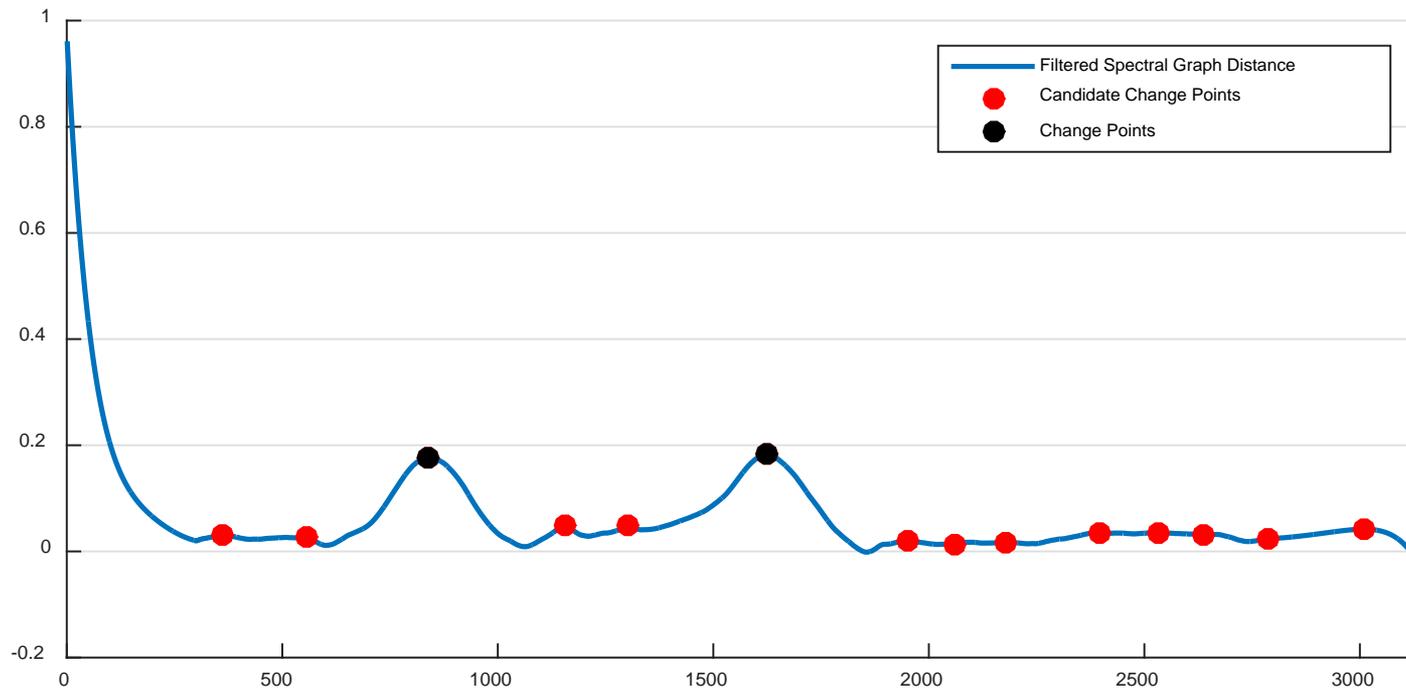
# Two Simple Methods

- 1. Check the average of candidate change points**
    - Change point is the point with a value 30% higher than the average.
  - 2. Calculate the angle between the line connecting two consequent candidate change points**
    - Change point is the point with angle above 70 degrees.
- **Both methods give similar results**

# Results: First Dataset

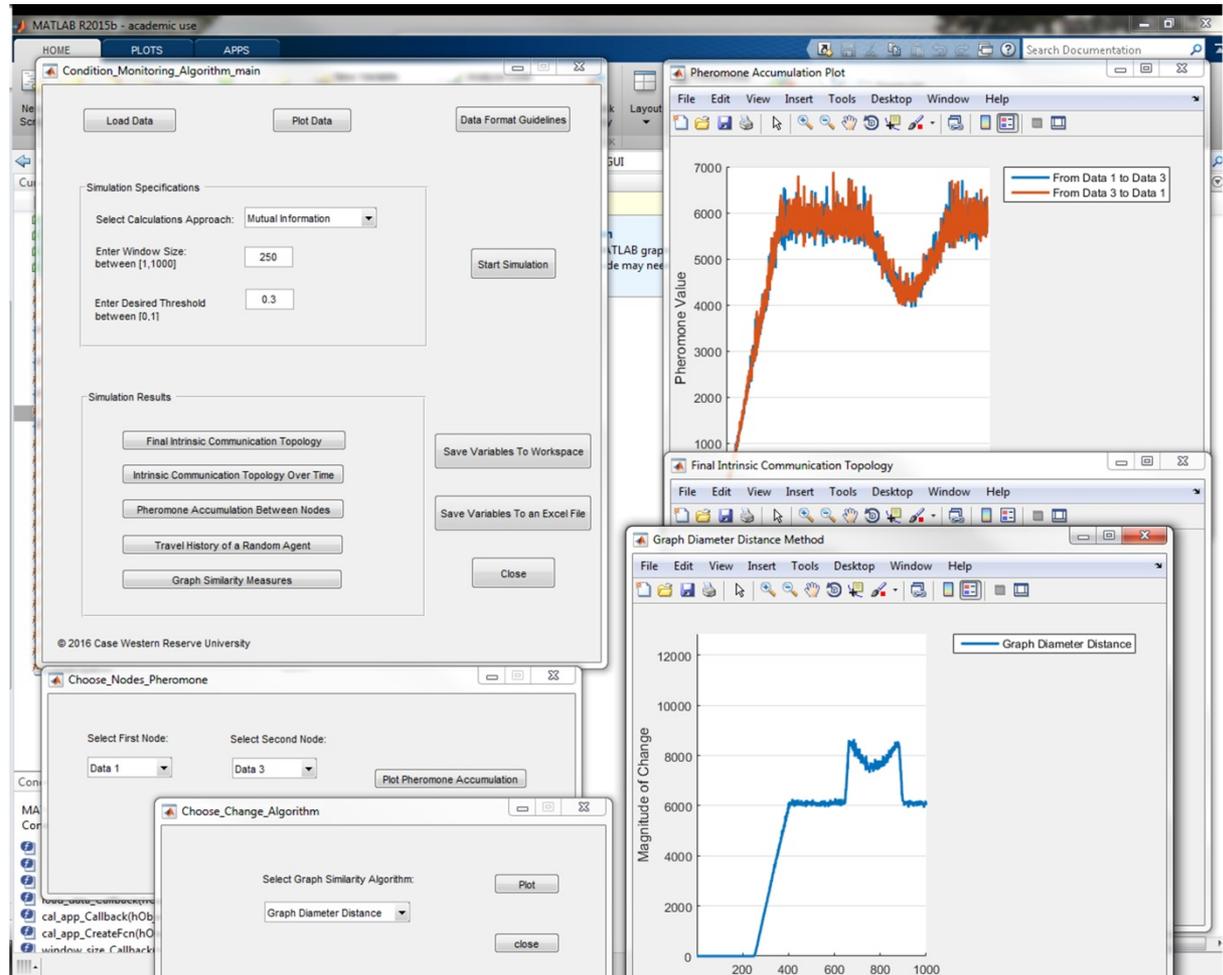


# Results: Second Dataset



# Interactive Network Detection Tool

- Data analytics GUI
- Takes file inputs
- User driven analysis
  - *Context driven options*
  - *Context menus for simulation and visualization*
- Integrates all tools
  - *Mutual information*
  - *Self-organizing network discovery*
  - *Change detection*
- Basis for future demonstration efforts



# Future Application: Ultra-Supercritical Steam Plant



- Simulation of a 1000 Mwe Steam Power Plant
  - Main steam flow: 600°C at 58 bar g
  - Net heat rate: 9,045 kJ/kWh

# Questions?



"Say ... what's a mountain goat doing way up here in a cloud bank?"