



# Investigation of “Smart Parts” with Embedded Sensors for Energy System Applications

THE UNIVERSITY OF TEXAS  
AT EL PASO

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The University of Texas at El Paso



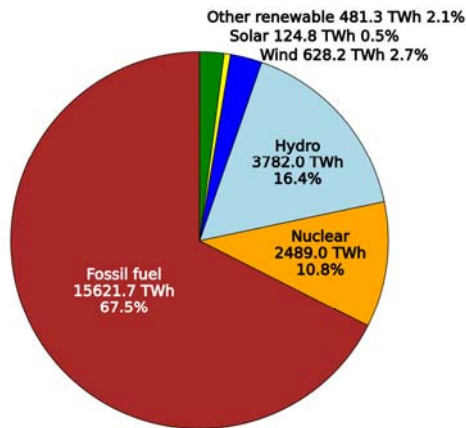
# Agenda



- Introduction and Background**
- Objectives**
- Technical Approach**
- Results**
- Summary**

# Motivation

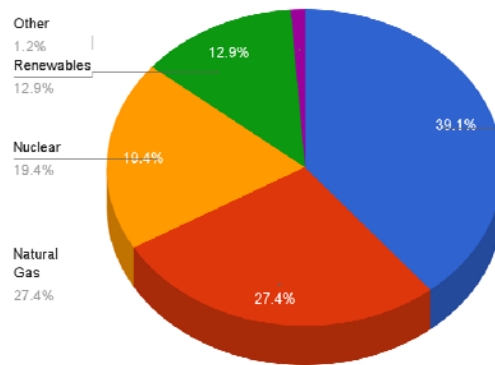
- Highly efficient and environmentally benign power and fuel systems require:
  - Critical Sensing in modern power plants and energy systems
  - Higher efficiencies in energy conversion
  - Lower emission for near-zero emission power plants
  - Enhanced material systems safety



World Electricity Generation by Source (2013)



U.S. 2013 Electricity Generation By Type



Natural Gas  
27.4%

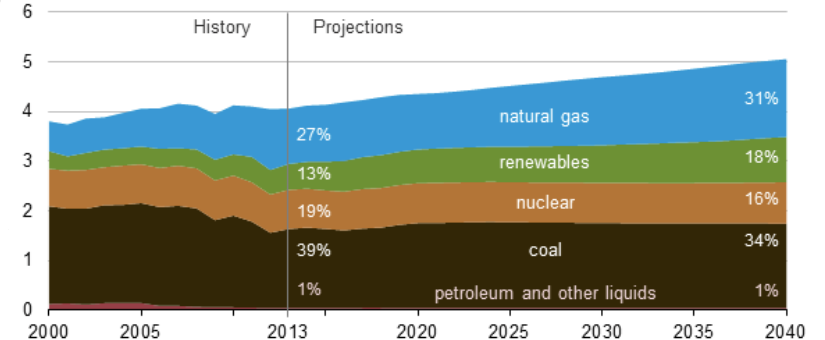
Nuclear  
19.4%

Renewables  
12.9%

Other  
1.2%



Electricity generation by fuel type in the AEO2015 Reference case, 2000-2040



# Advanced Sensing

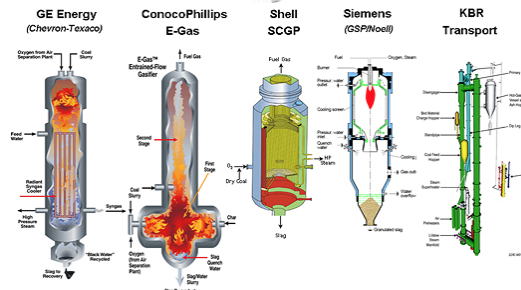
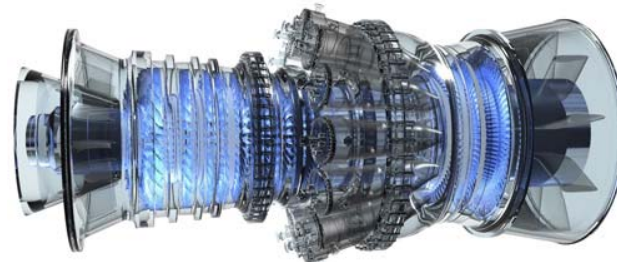
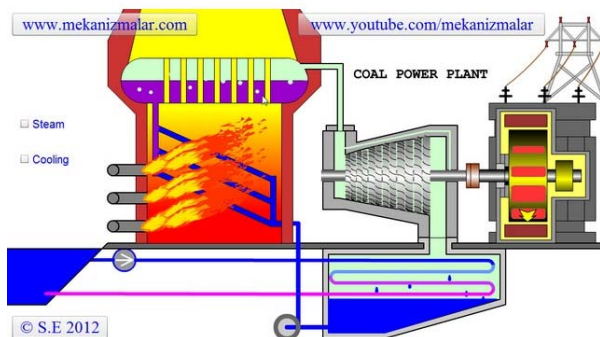
- Harsh high temperature conditions are common to the efficient conversion of fuels and processes for environmental control
- Monitoring/estimating harsh conditions in real time is needed for high system performance and assessing reliability

## Gasifiers

- Up to 1600°C
- Up to 1000 PSI
- Erosive, corrosive, highly reducing

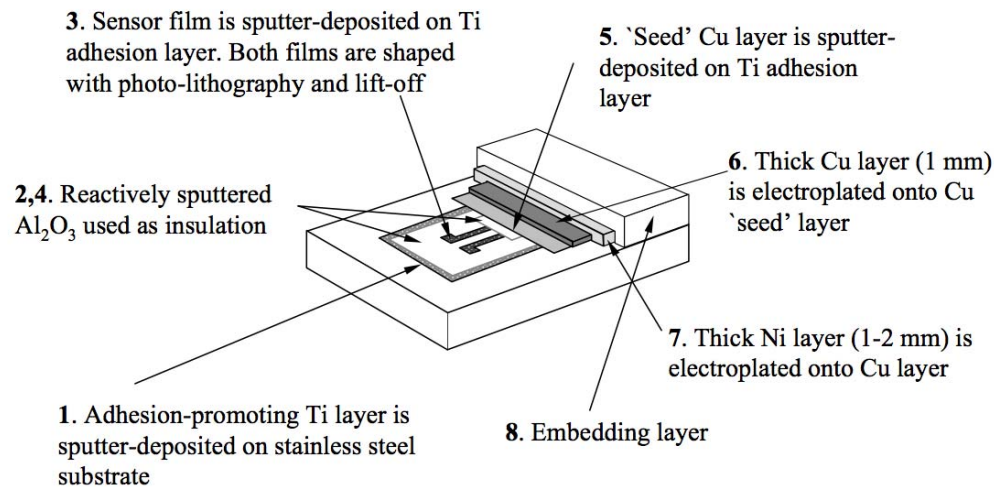
## Combustion Turbines

- Up to 1350°C
- Pressure ratios of 30:1
- Thermal shock, highly oxidative
- Complex geometries

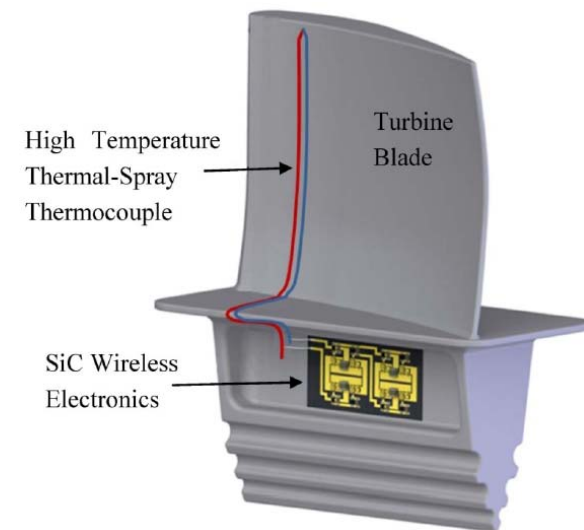


# State-of-the-Art

- Integrated thermocouples bonded to turbine blades
- Temperature measurement enabled
- Signal is sensitive to harsh environments
- Up to 1400 °C for short time

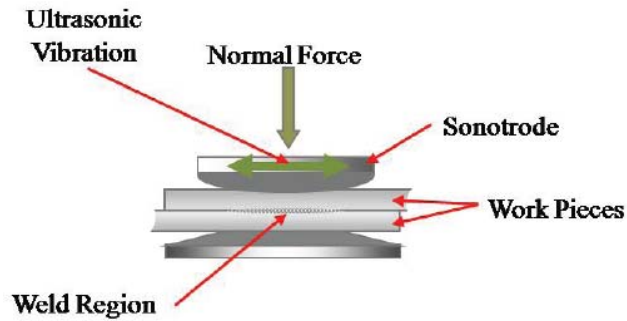


(X. Li, 2001)

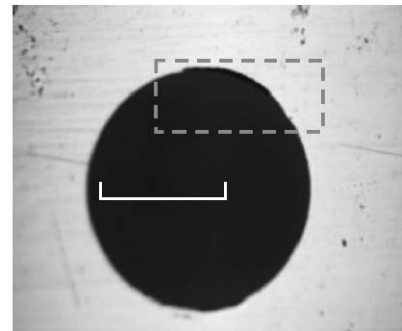
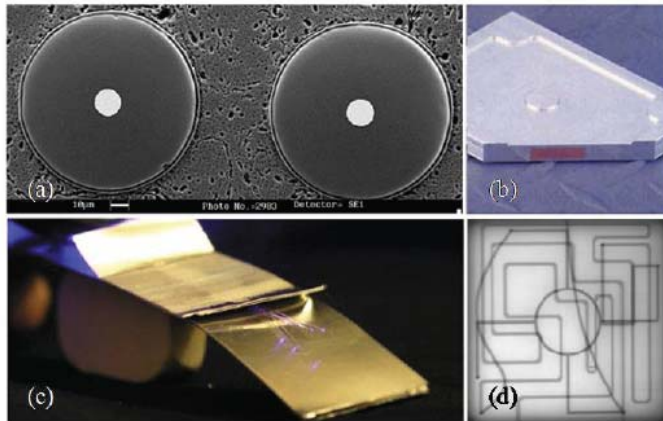


(J. Yang, 2012)

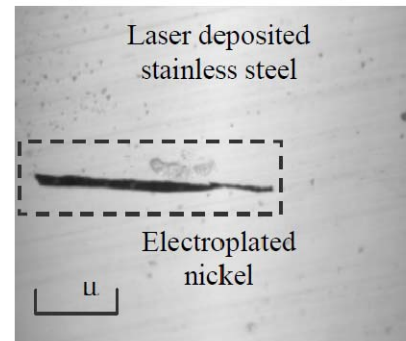
# Ultrasonic Sensor Embedding



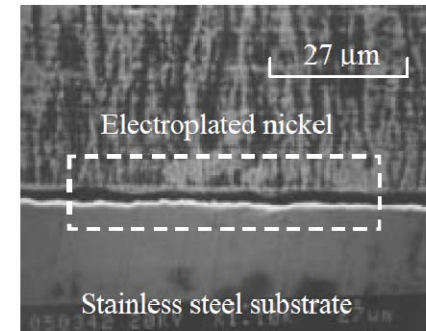
Ultrasonic Operation



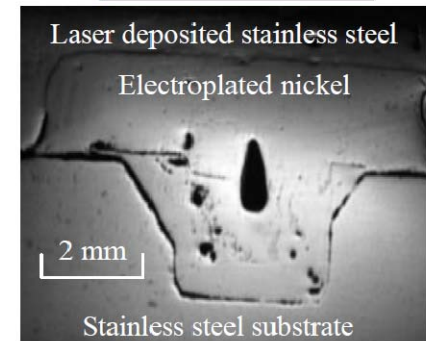
**Cracking**



**Cracking**



**Delamination**

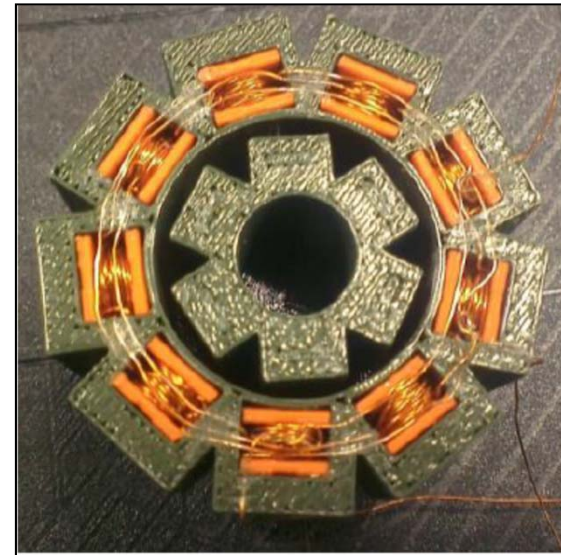


**Delamination**

# Multi-step Fabrication



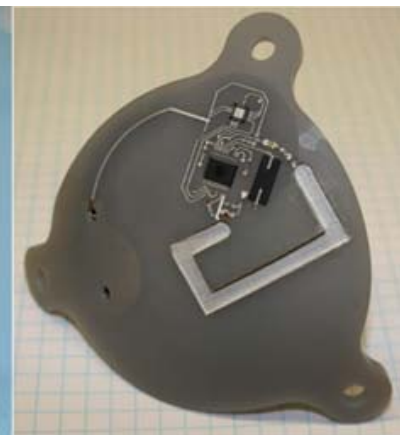
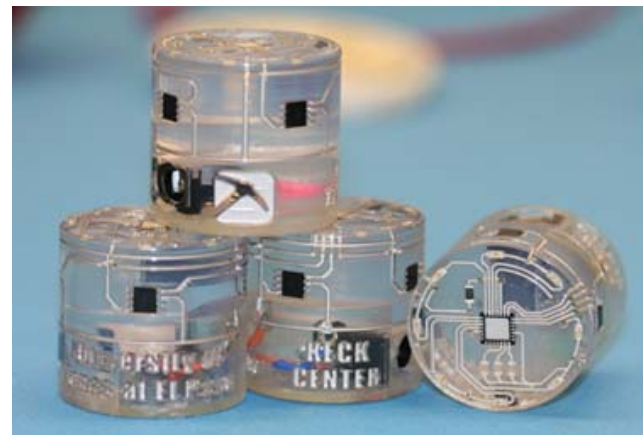
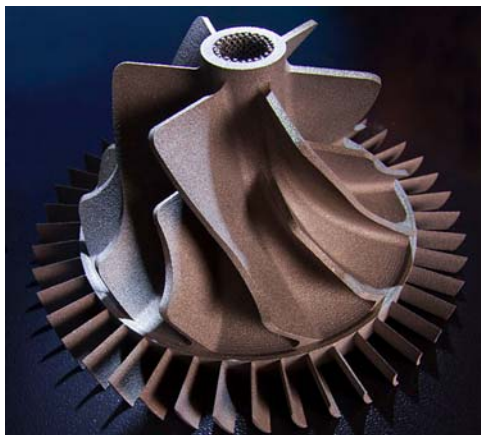
Multi-material fabrication using EBM



Fabrication of electro-mechanical system

# Overview and Rationale

- “Smart parts” with embedded sensor
  - Built-in monitoring capability
  - Accurate sensing at desired location
  - No change required post fabrication
  - Realized by 3D printing technology







# Timeline



	Year 1				Year 2				Year 3				
	Q1	Q2	Q3	Q4	Q1	Q2	Q3	Q4	Q1	Q2	Q3	Q4	
<b>Objective 1</b>													
Task 1: <i>Fabrication Characterization</i>													
Task 2: <i>"Smart Parts" Fabrication</i>													
<b>Objective 2</b>													
Task 3: <i>Mechanical Evaluation</i>													
Task 4: <i>Sensing Demonstration</i>													
<b>Objective 3</b>													
Task 5: <i>"Smart Tube" Testing</i>													
Task 6: <i>"Smart Premixer" Testing</i>													
Task 7: <i>Modification to Fabrication</i>													
<b>Progress Report</b>													
<b>Final Report</b>													

# Team Description and Assignment



- Ahsan Choudhuri/Norman Love
  - Smart Parts testing
  - Smart Parts case study
  - High temperature assessment



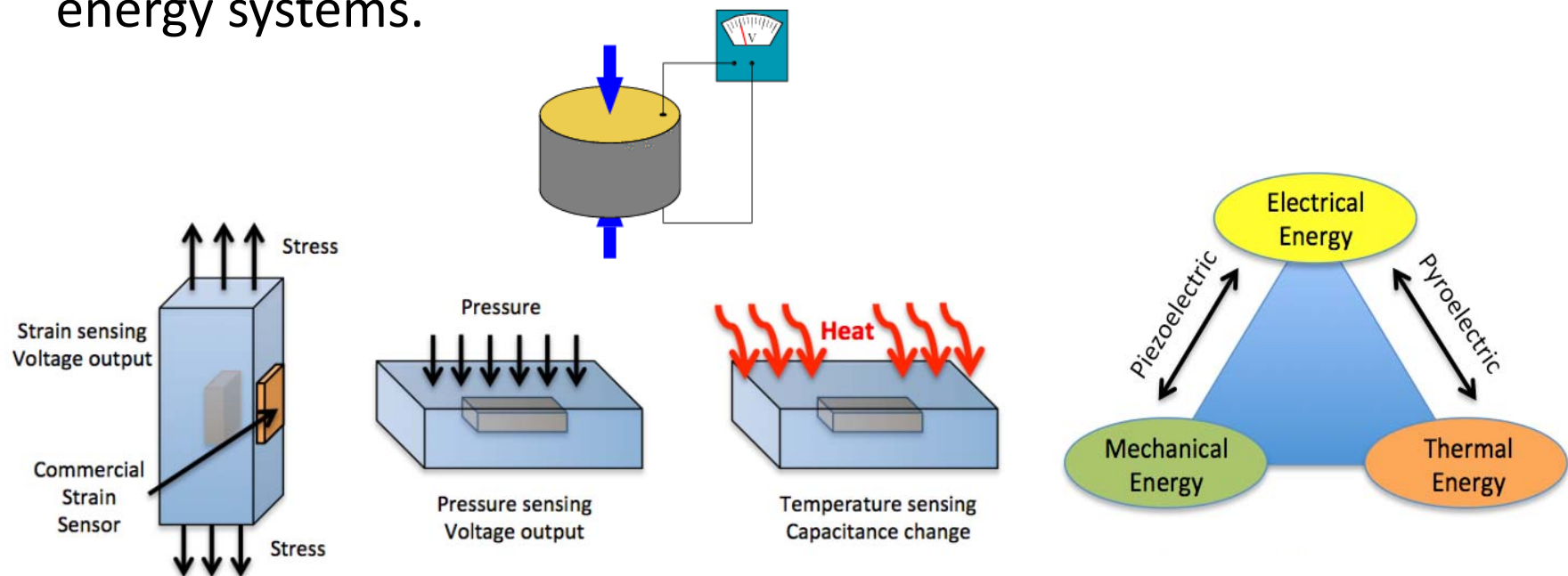
- Ryan Wicker/Jorge Mireles
  - Smart Parts 3D printing
  - Sensor embedding processing



- Yirong Lin
  - Materials characterization
  - Sensing demonstration
  - Smart Parts testing

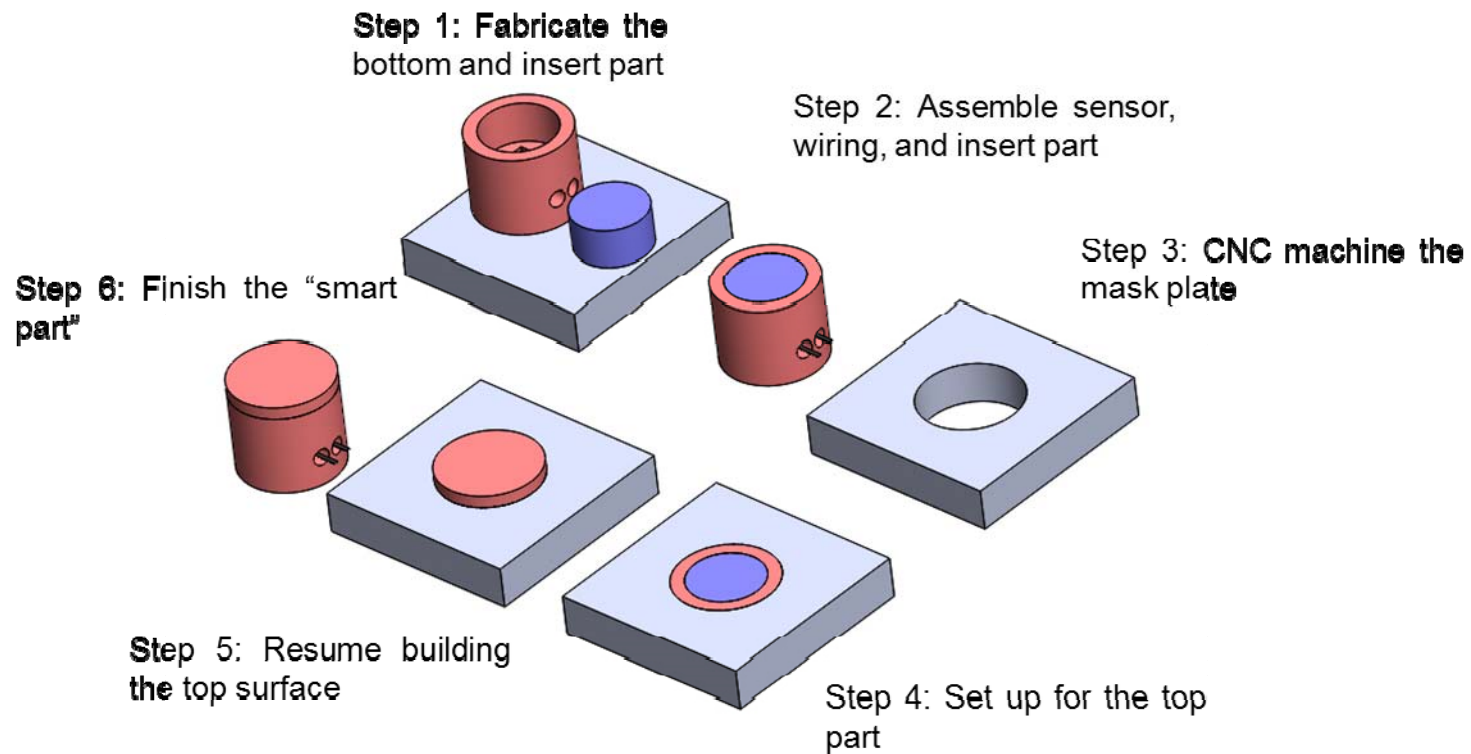
# Scope of Work

- Design and fabricate “smart parts” with embedded sensors.
  - EBM 3D printing technique for fabrication of “smart parts”
  - Piezoceramic sensors for temperature, strain, pressure sensing.
- Evaluate the sensing capability of the “smart part” in realistic energy systems.



$$i_p = \frac{dQ}{dt} = Ap \frac{dT}{dt}$$

- “Stop and Go” process, first of its kind
- 3D Printing manually interrupted
- Sensor embedded during fabrication at desired location



# Objectives

- **Objective 1: Fabricate energy system related components with embedded sensors**
  - Fabrication & evaluation of components without sensor by EBM
  - Manufacturing “Smart Parts” with embedded sensor by EBM
- **Objective 2: Evaluate the mechanical properties and sensing functionalities of the “smart parts” with embedded piezoceramic sensors**
  - Evaluation of interfacial shear properties
  - Characterization of the sensing capability
- **Objective 3: Assess in-situ sensing capability of energy system parts**
  - Short & long term testing to determine sensor reliability
  - Cyclic and constant loading to determine the sensing repeatability and stability

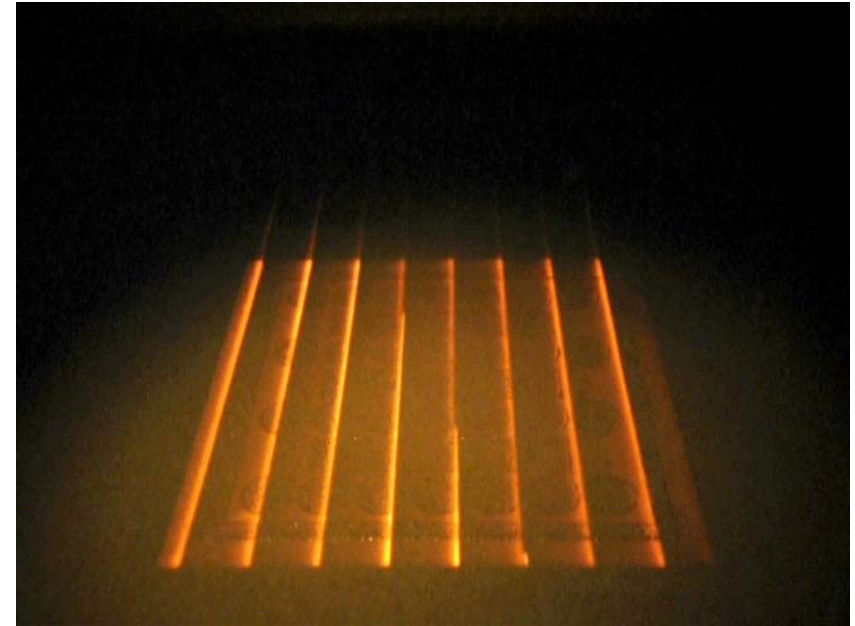
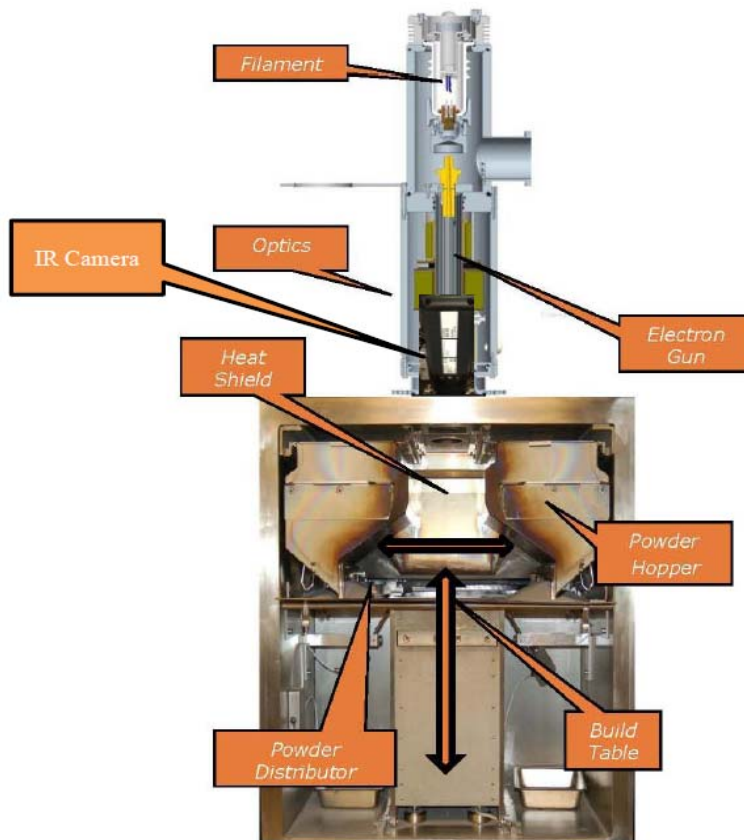
# Electron Beam Melting

by Oakridge National Lab



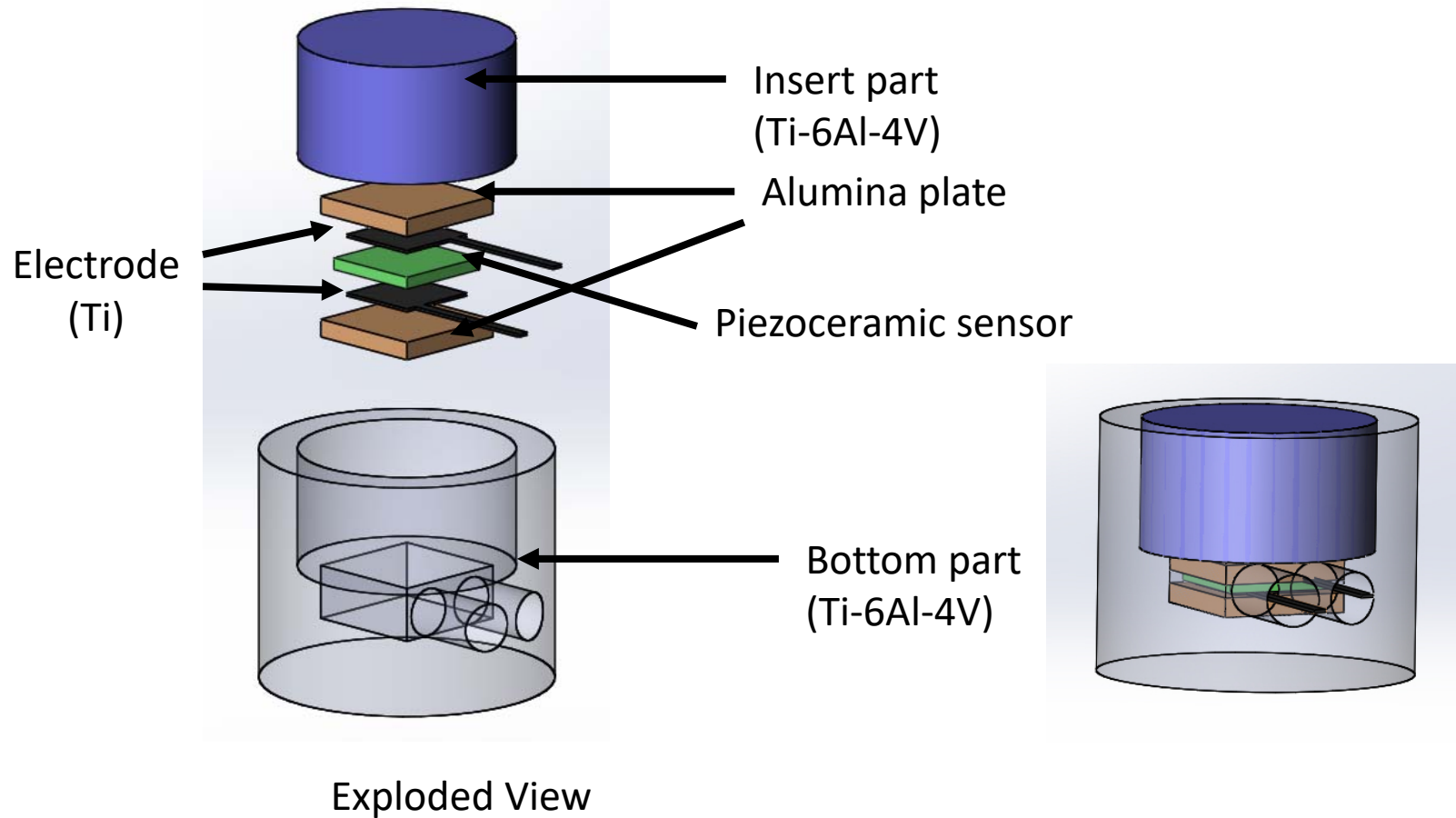
# Fabrication

- Powder Material: Ti-6Al-4V
- Mask Plate and Start Plate: Stainless steel
- Layer Thickness: 50  $\mu\text{m}$



Powder Material:  
Ti-6Al-4V  
Mask Plate and Start Plate:  
Stainless steel  
Layer Thickness:  
50 $\mu\text{m}$

# Sensor assembly in “Smart parts”

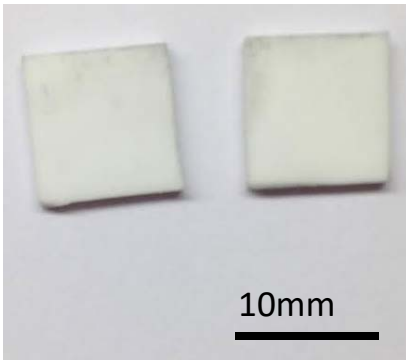




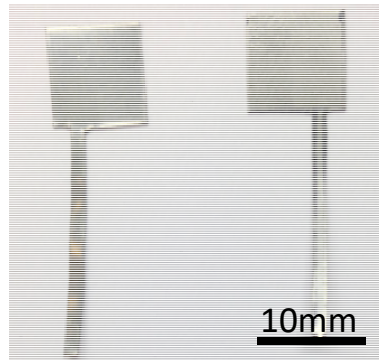
# Characterization

## Before EBM

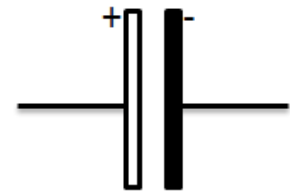
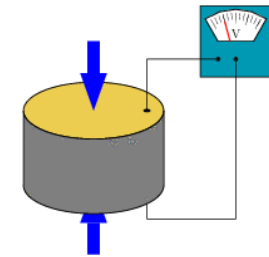
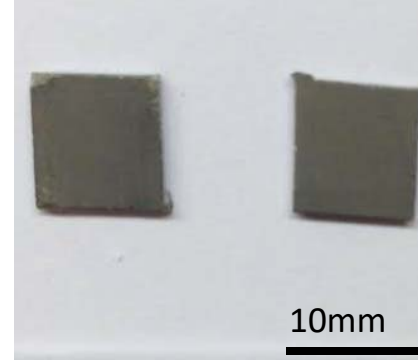
*Alumina Plate*



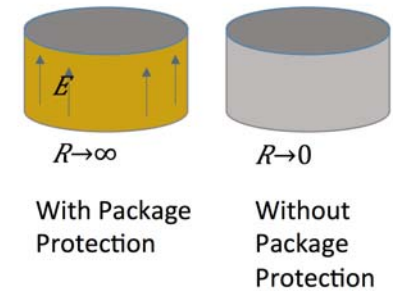
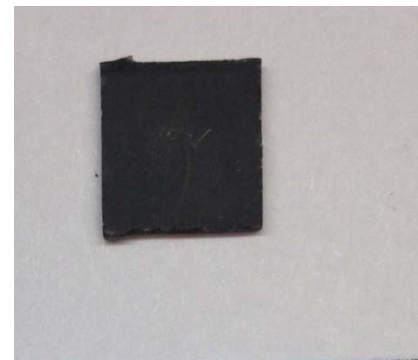
*Ti Electrodes*



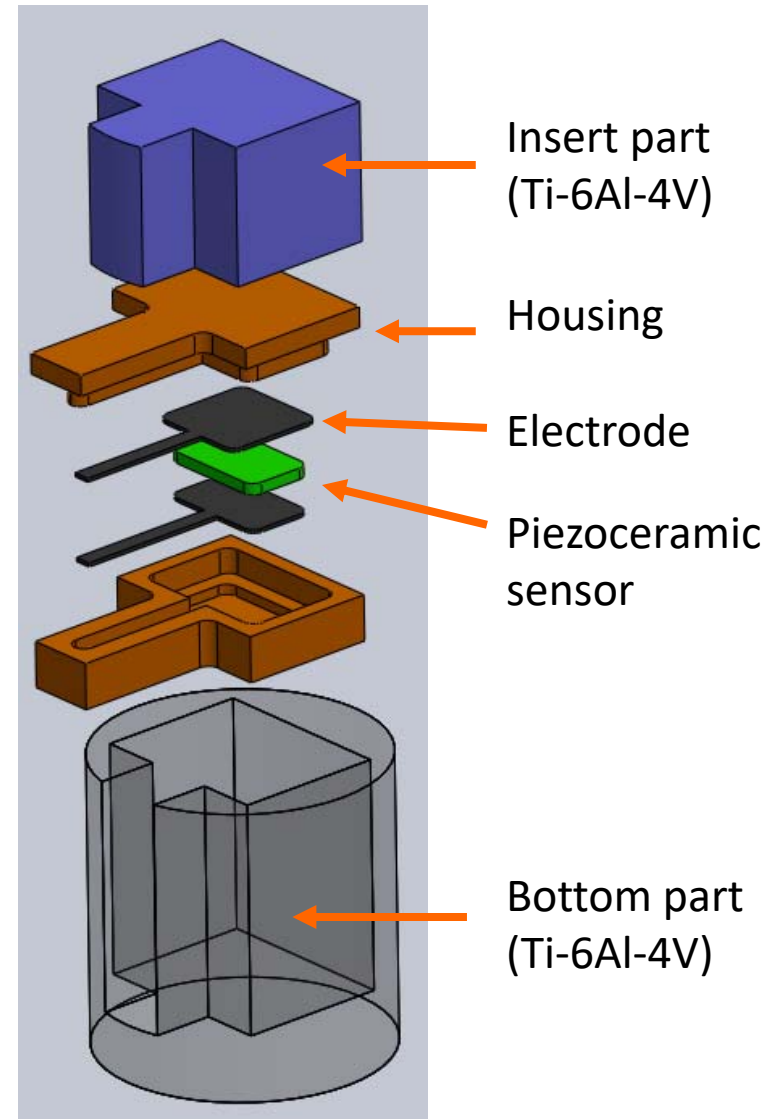
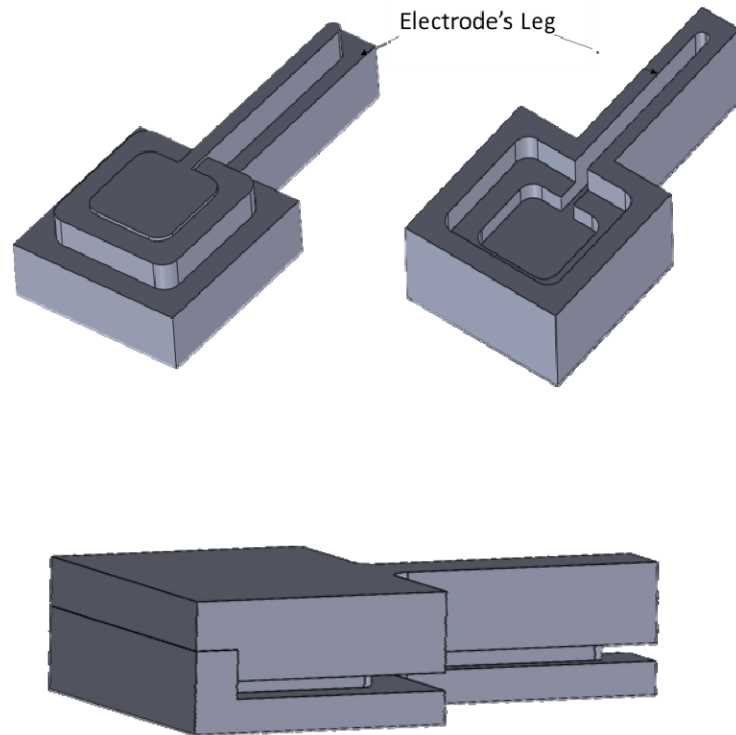
*Piezoelectric Sensor*



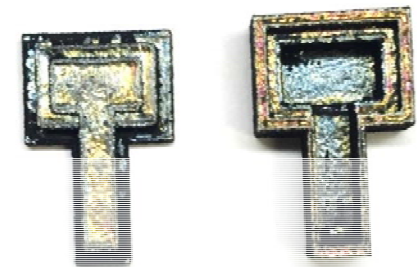
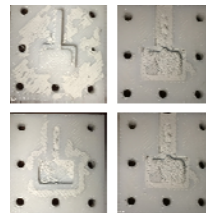
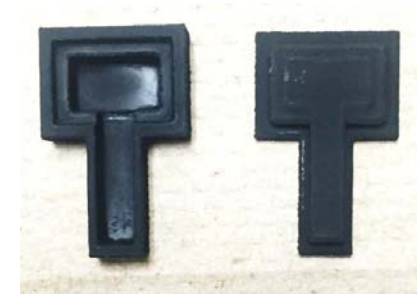
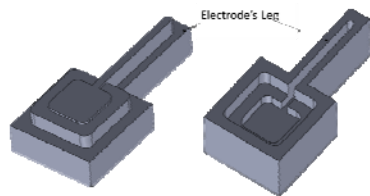
## After EBM



# Sensor Packaging Design



# Sensor Packaging Fabrication



Machinable  
Alumina

Injection  
Modeling

3D printing

3D printing  
+  
Ceramic spray

# Smart parts Fabrication (1<sup>st</sup> run)

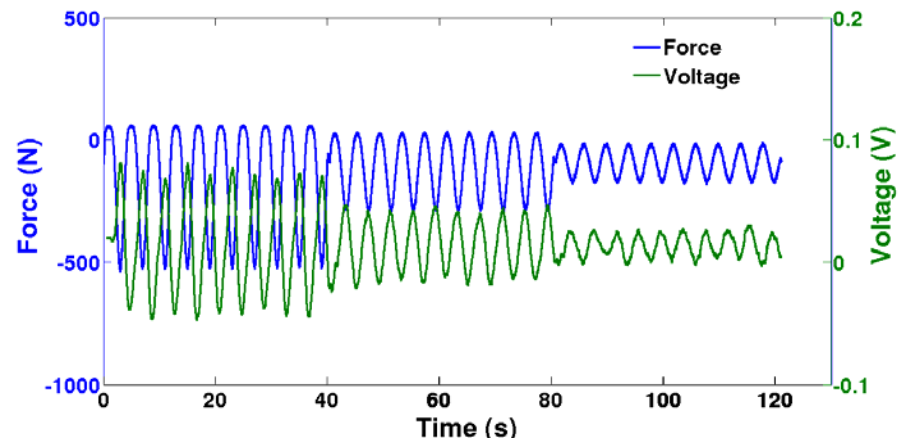
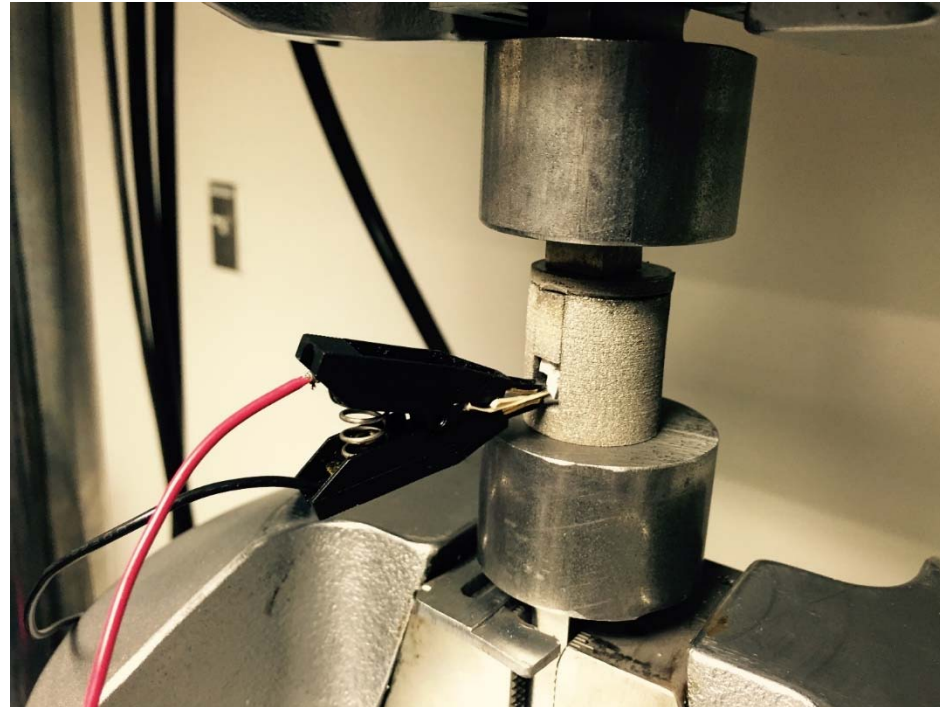


Before  
Fabrication

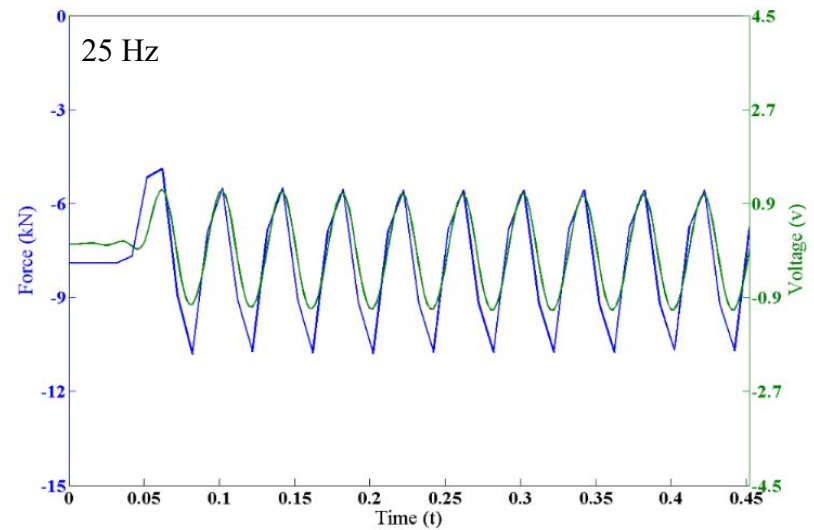
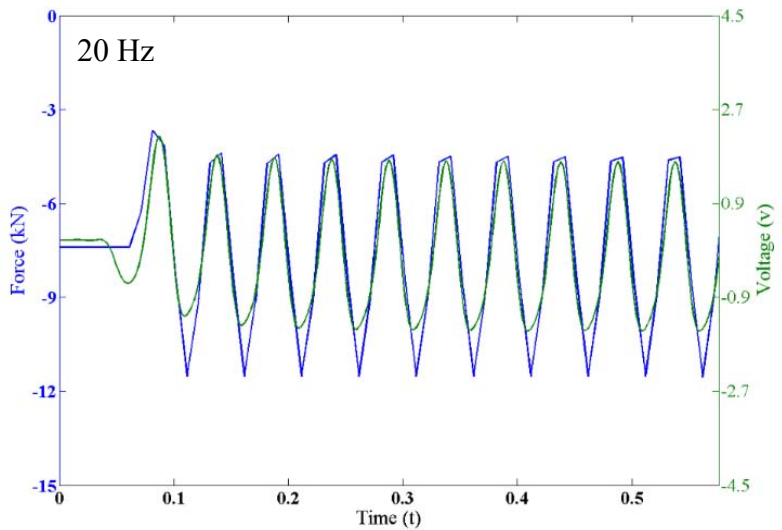
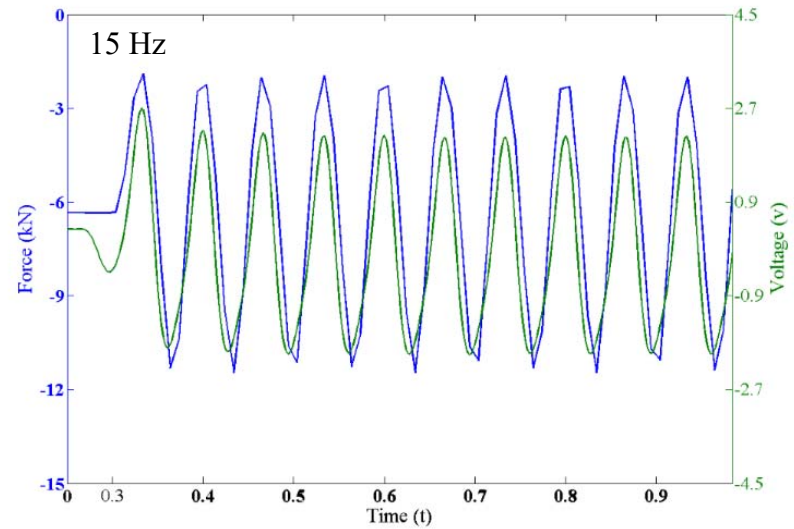
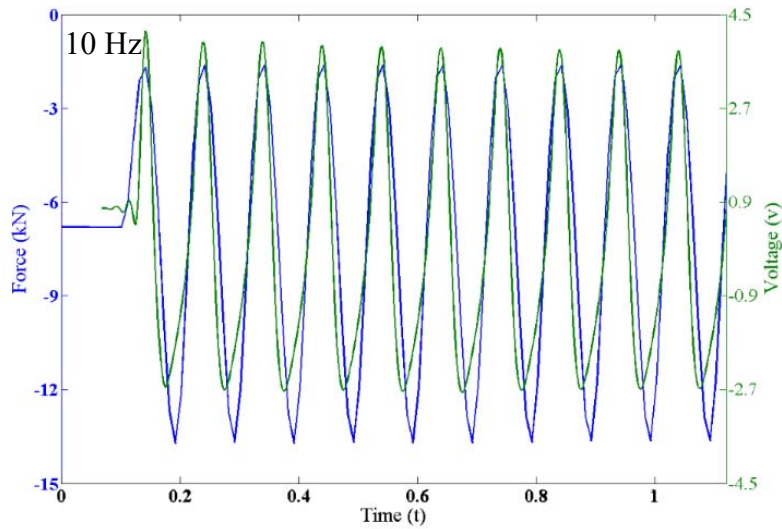


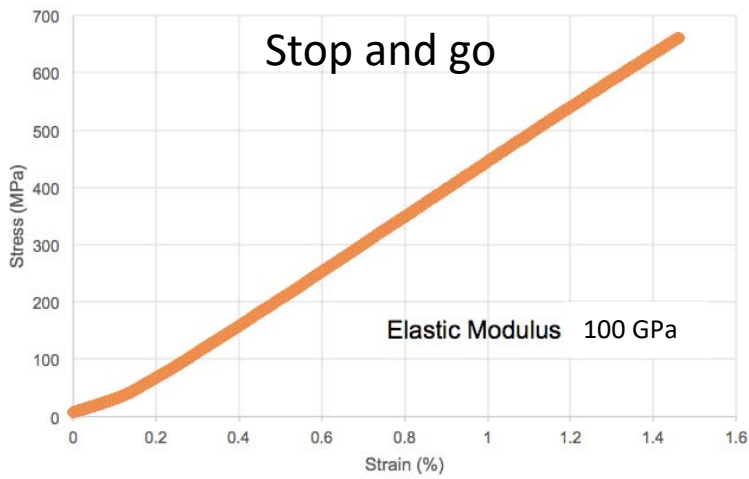
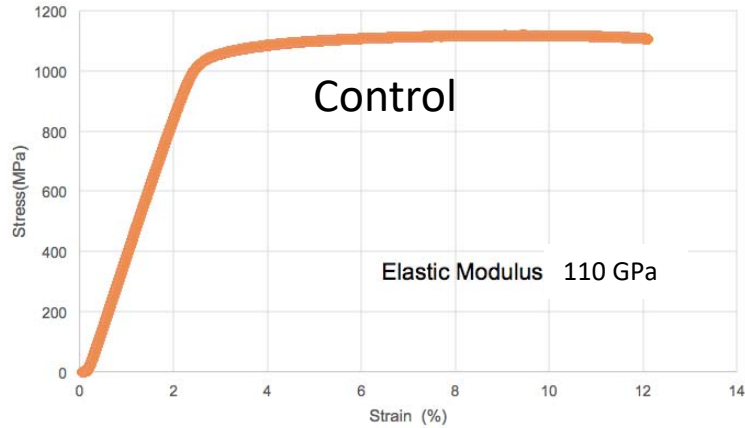
Final Part

# Force Sensing



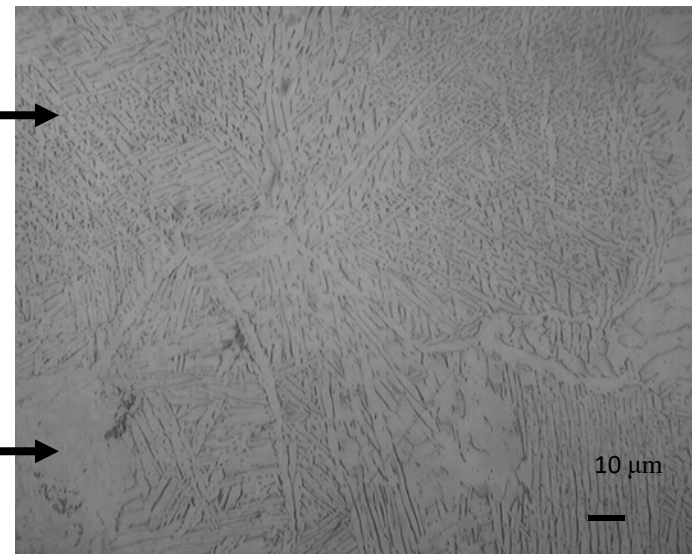
# Compression Force sensing



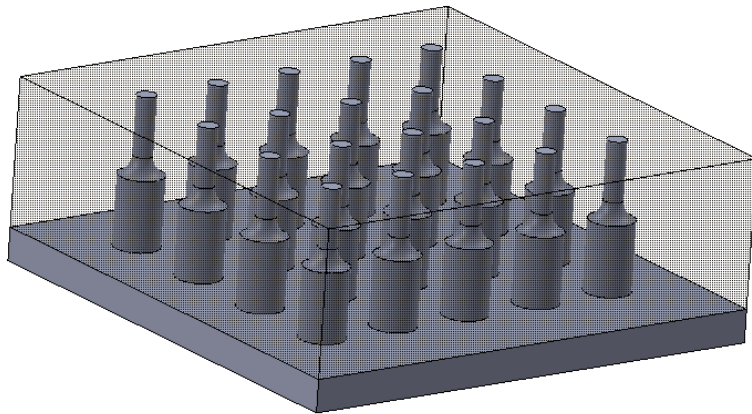


2<sup>nd</sup> built

1<sup>st</sup> built

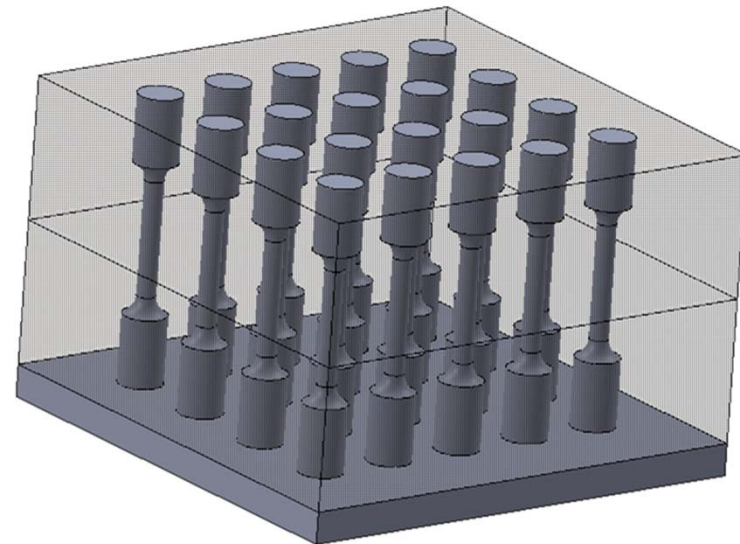


# Interfacial Property Enhancement Experimental Setup



Tensile bars were fabricated to test mechanical properties after interrupting the fabrication process

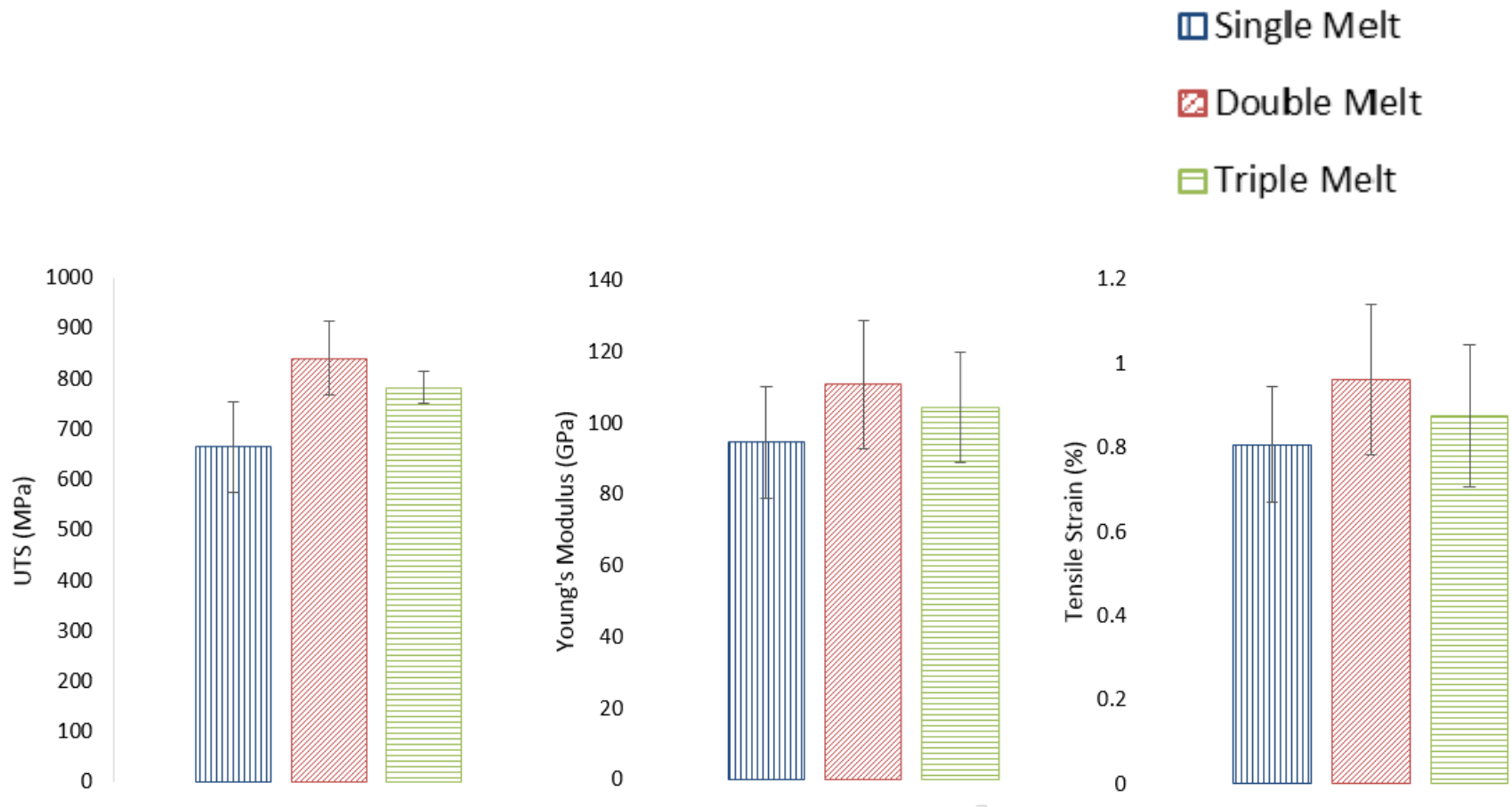
Fabrication was stopped at gauge's midpoint, the machine was allowed to fully cool and the process was restarted



Fabricated  
tensile bars

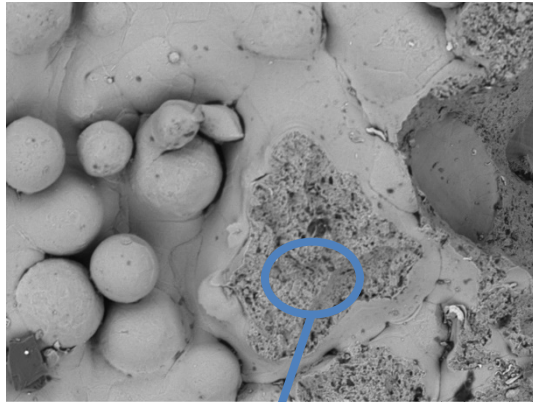


# Interfacial Property Enhancement Experimental Setup

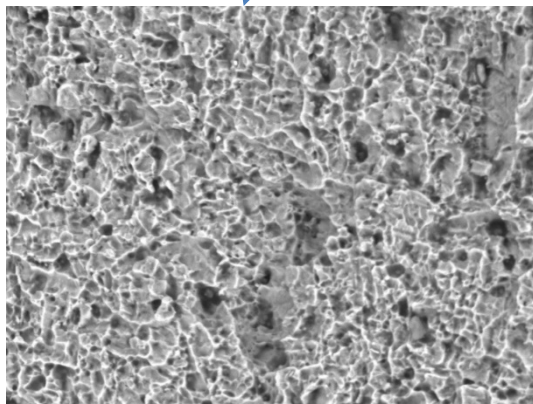


# Fracture Surface

### Single Melt

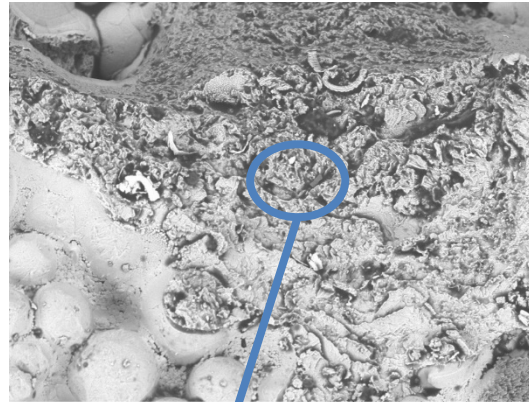


TM-1000\_0021 2016/02/25 17:32 200 um

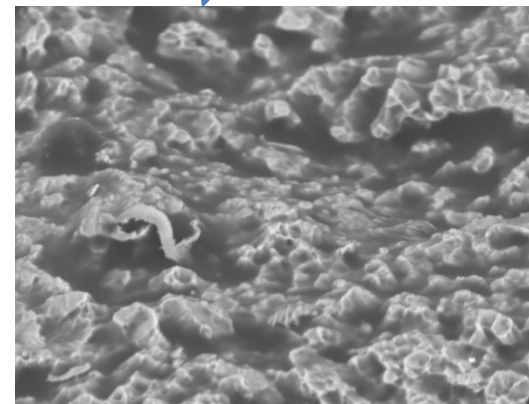


TM-1000\_0024 2016/02/25 17:39 30 um

### Double Melt

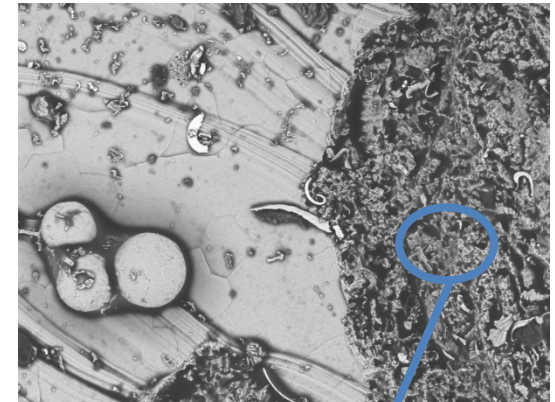


TM-1000\_0028 2016/02/25 17:57 200 um

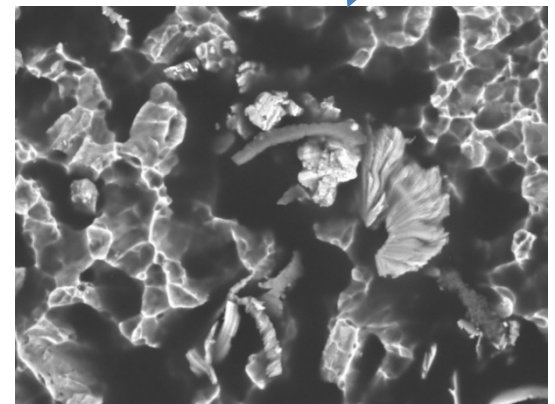


TM-1000\_0030 2016/02/25 18:05 30 um

### Triple Melt

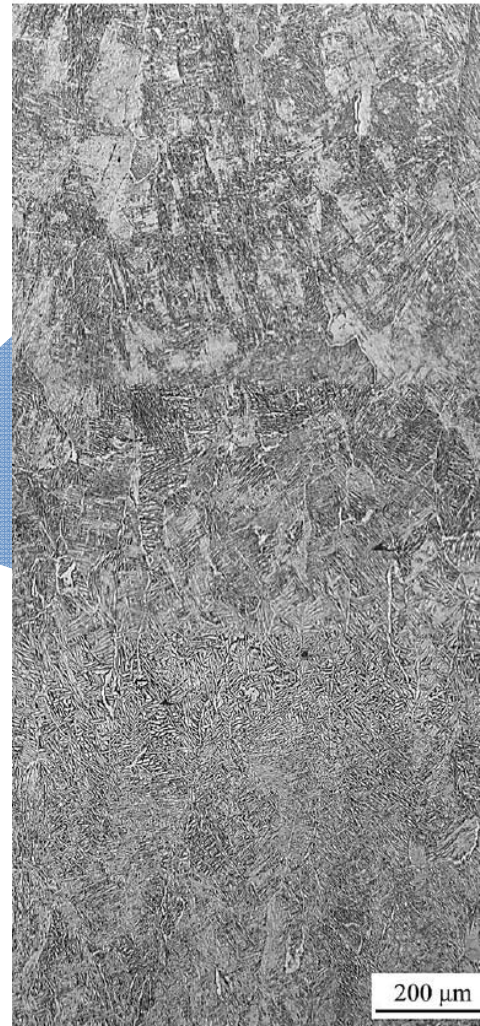
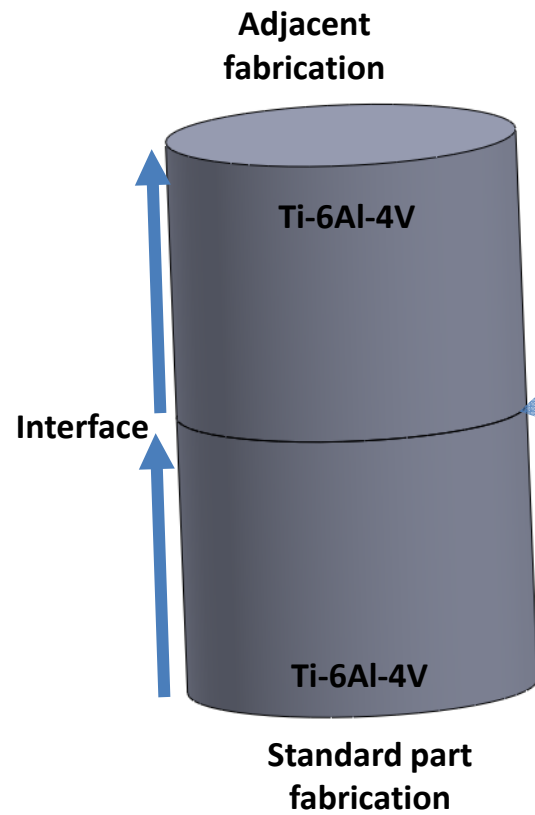


TM-1000\_0035 2016/02/25 18:29 200 um

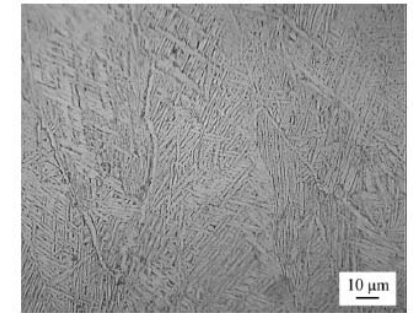


TM-1000\_0033 2016/02/25 18:25 30 um

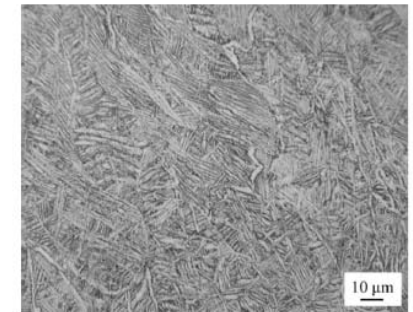
# Joint Microstructure



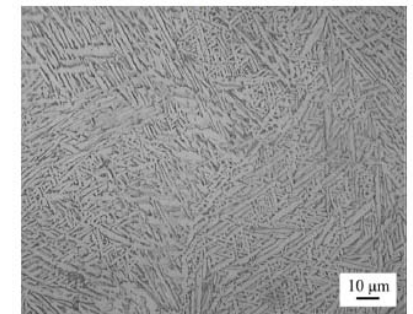
(a)



(b)



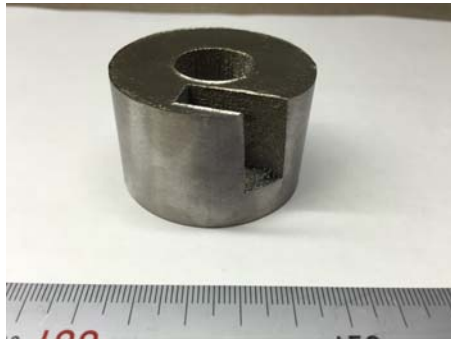
(c)



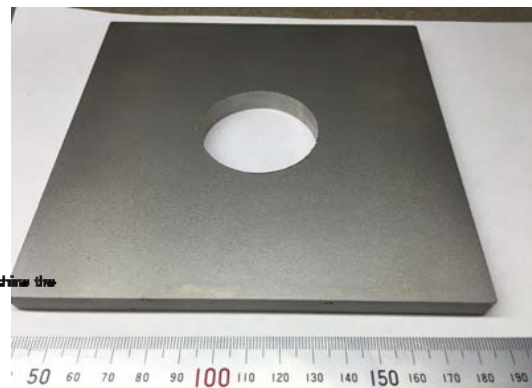
(d)

Hossain, M.S., Gonzalez, J.A., Martinez-Hernandez, R., Shuvo, M.A., Mireles, J., Choudhuri, A., Lin, Y., Wicker, R.B., (2016). *Fabrication of smart parts using powder bed fusion additive manufacturing technology*. *Journal of Additive Manufacturing*, 10, pp. 58-66

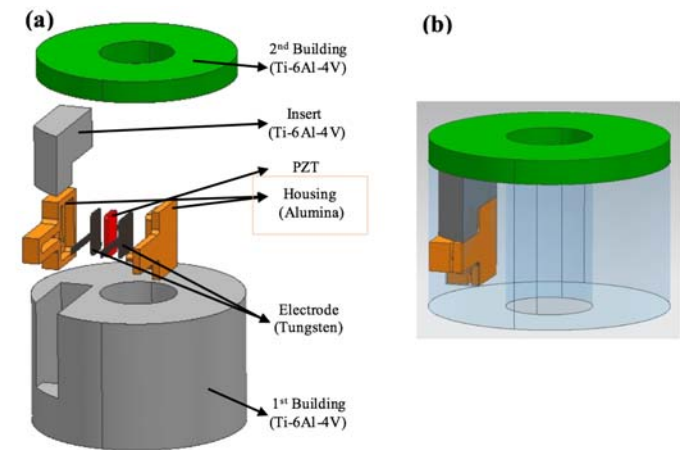
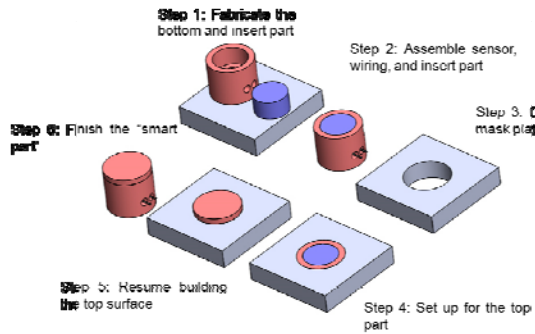
# Smart Tube Fabrication



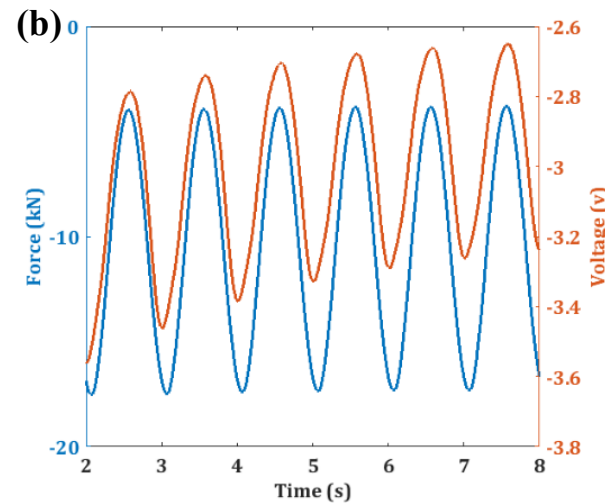
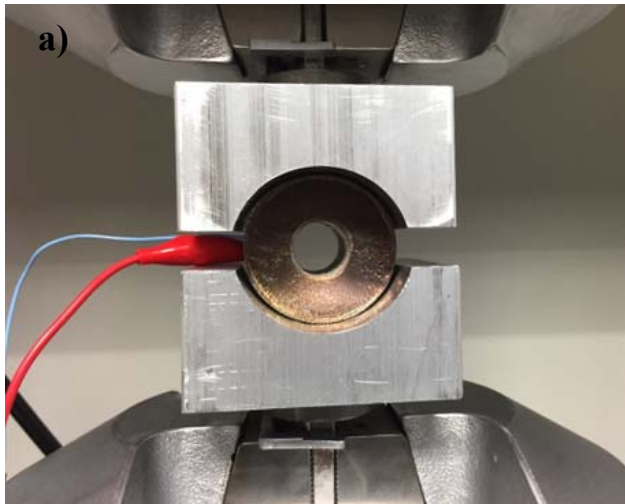
Assembled Bottom Section



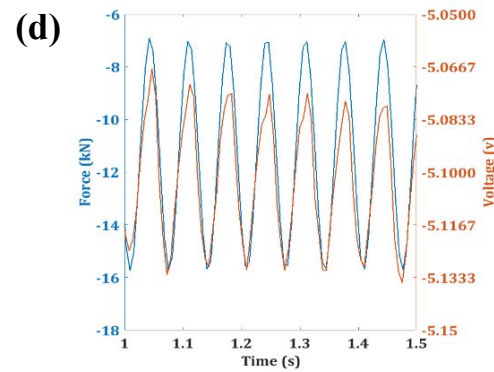
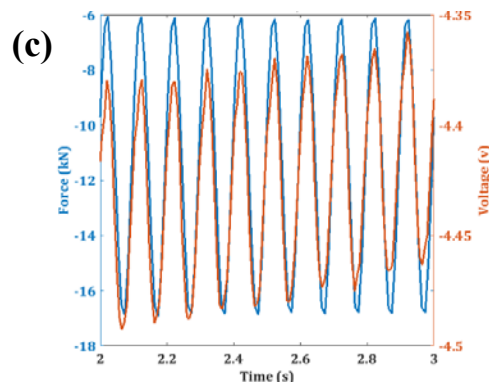
Masking plate



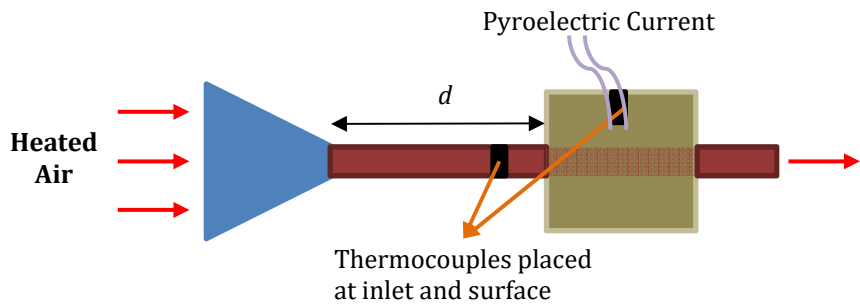
# Pressure Sensing



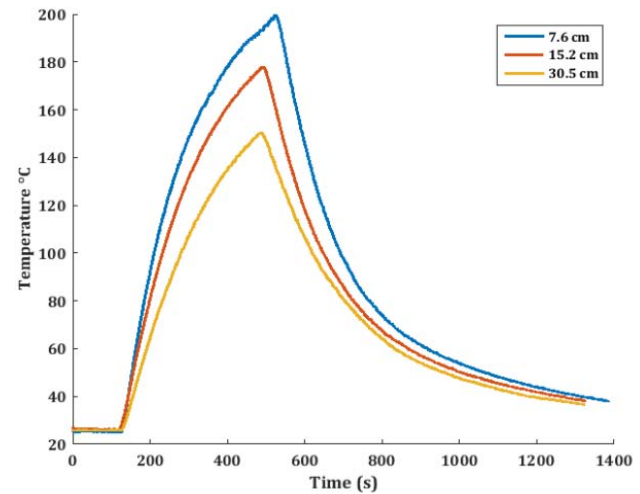
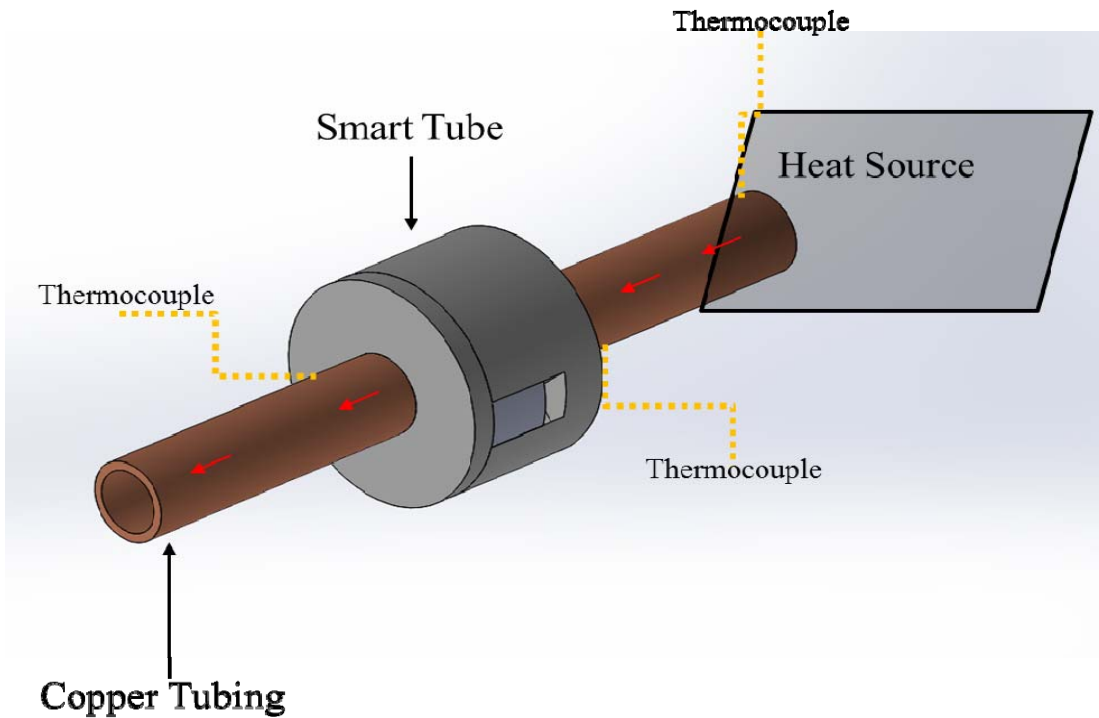
- Force sensing with embedded sensor demonstrated
- 1,5,10 Hz of dynamic force was used
- 0.04, 0.011 and 0.0064 (V/kN) of sensitivity was achieved
- Lower sensitivity caused by sensor packaging clearance and force loading directions



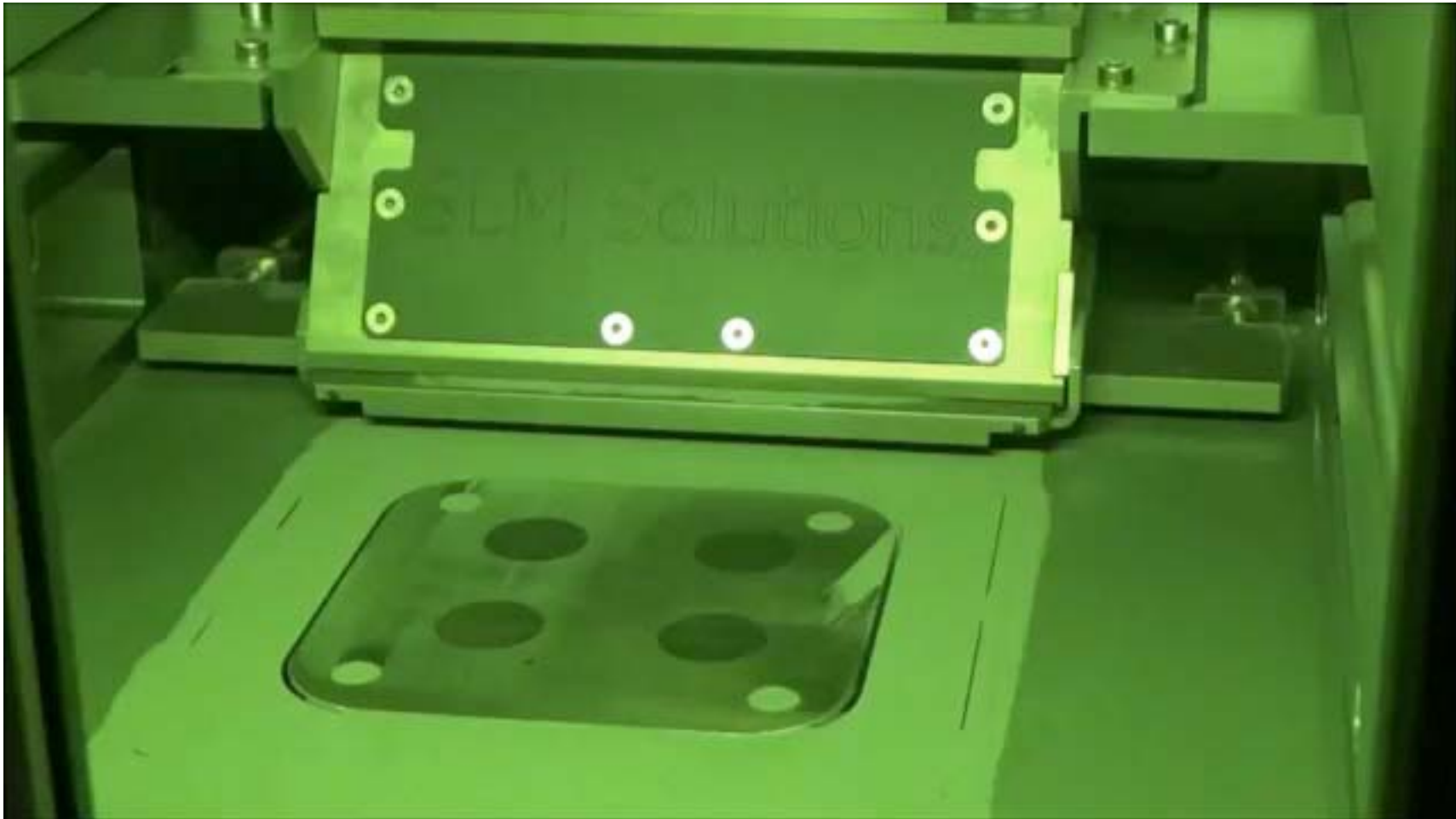
# Temperature Sensing

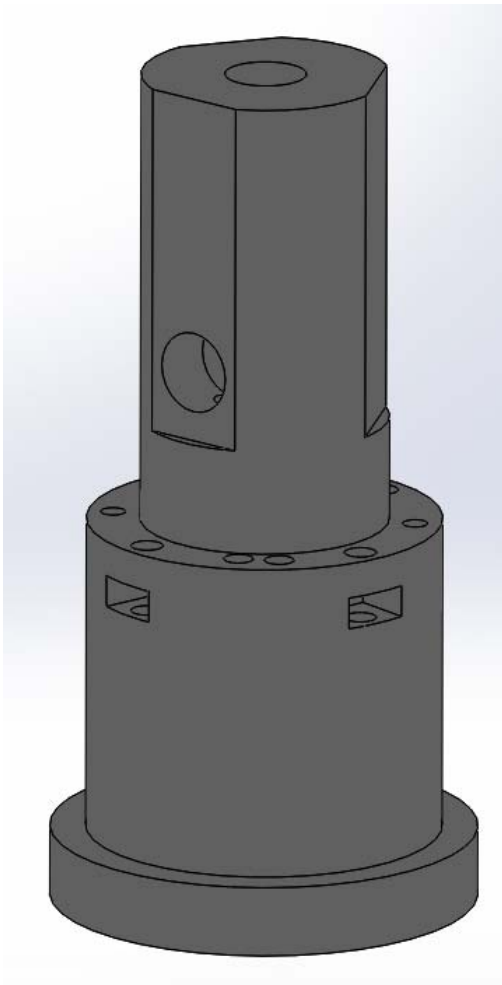


Sensed temperatures of 198 °C, 178 °C, and 150 °C for 7.6 cm, 15.2 cm and 30.5 cm long tube sections

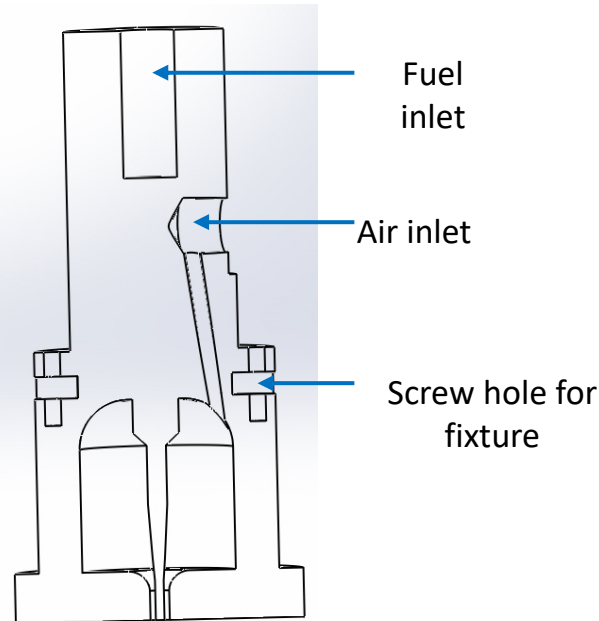
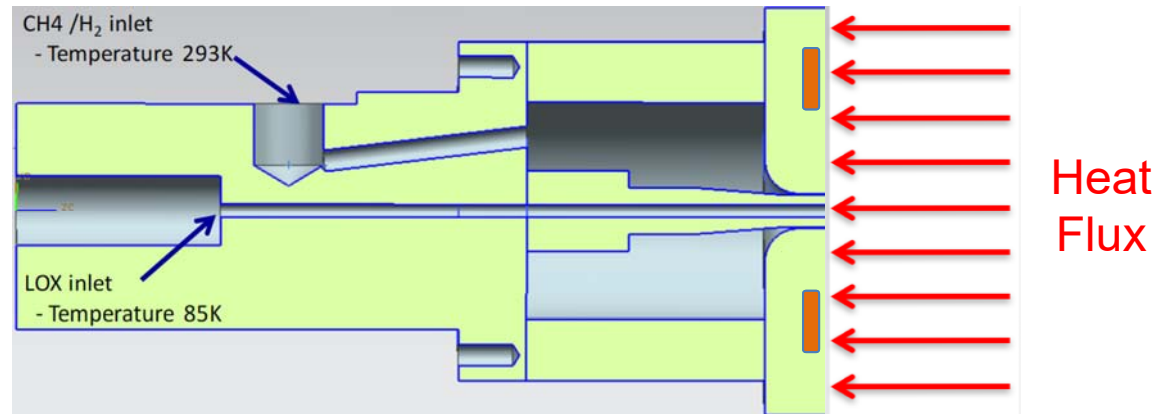


# Selective Laser Melting Demo





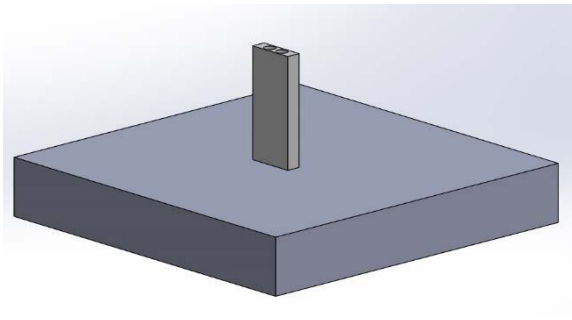
3D View



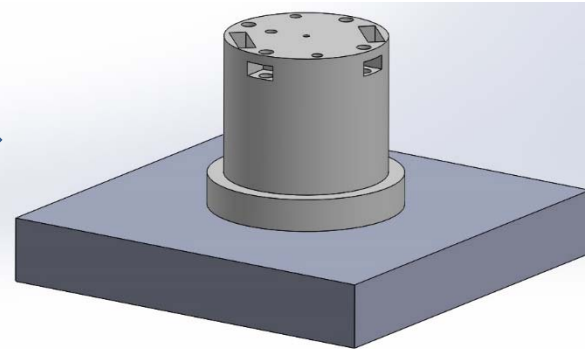
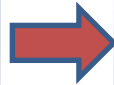
- Thermal soak-back sensing
- Allows for operation at lower safety factors
- Higher temperatures and higher efficiencies



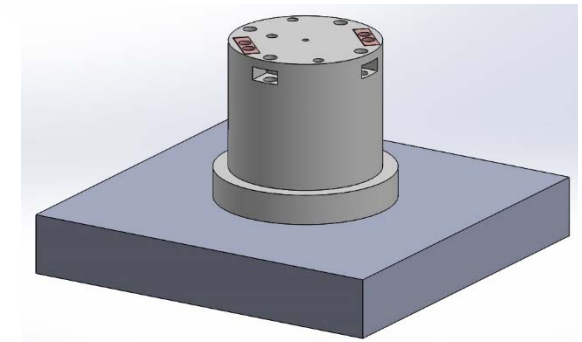
# Design of Smart Injector Fabrication



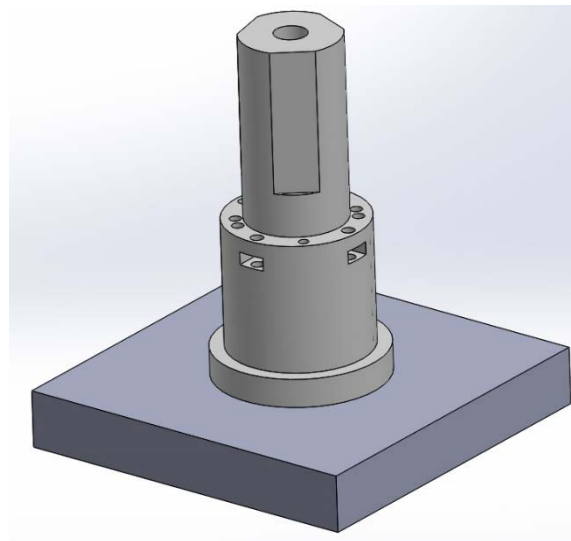
Fabrication of insert part



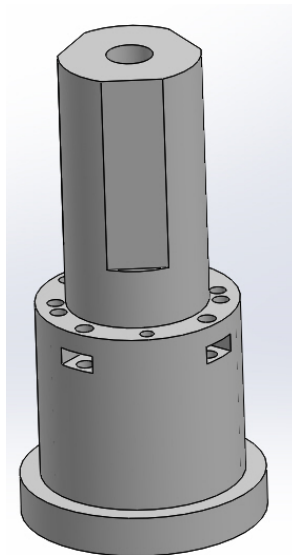
Fabrication of bottom part



Sensor assembly



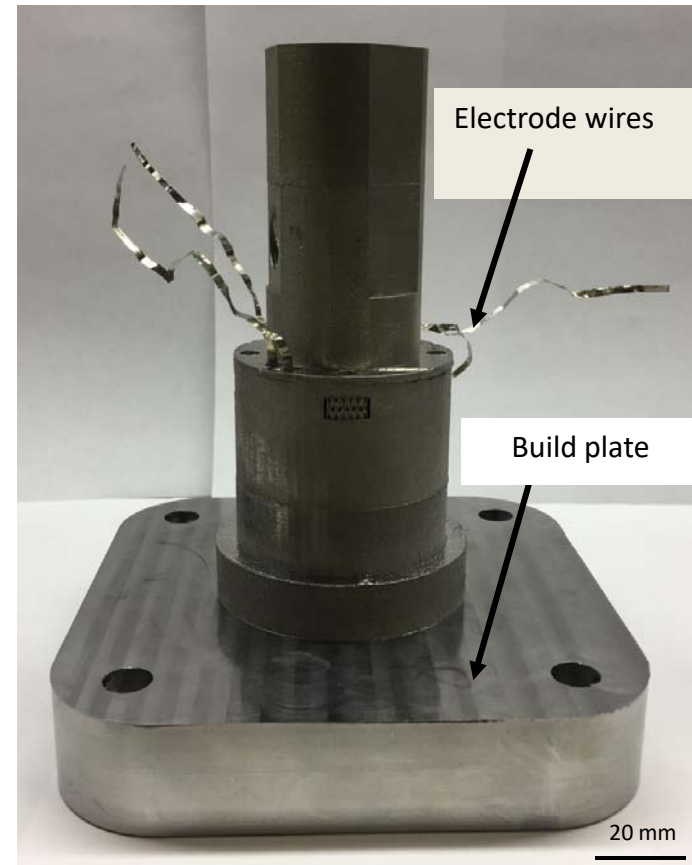
Fabrication of entire part



Final smart part

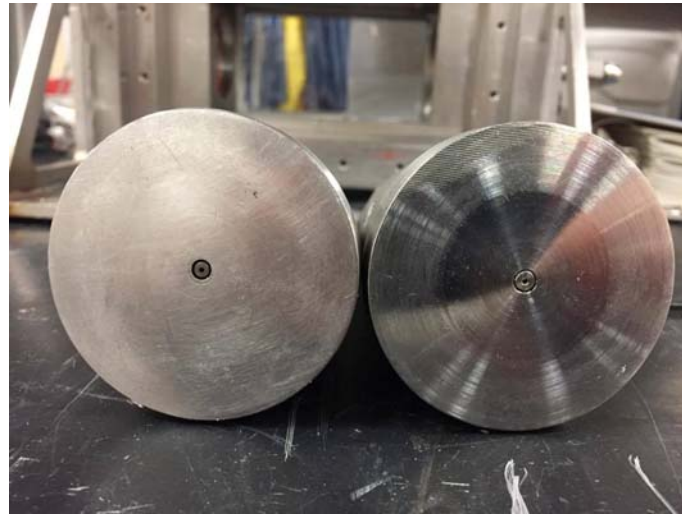
# Fabricated Smart Injector

- The smart injector was fabricated using selective laser melting (SLM) technology
- The electrode wires are visible in the injector
- PZT and LiNbO<sub>3</sub> sensor material is embedded inside the injector
- The injector was cut off from the build plate after finishing preliminary sensor testing





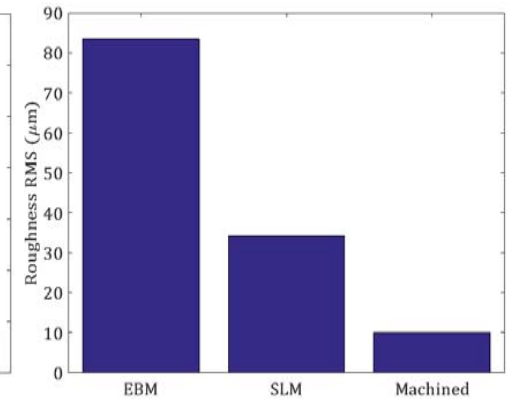
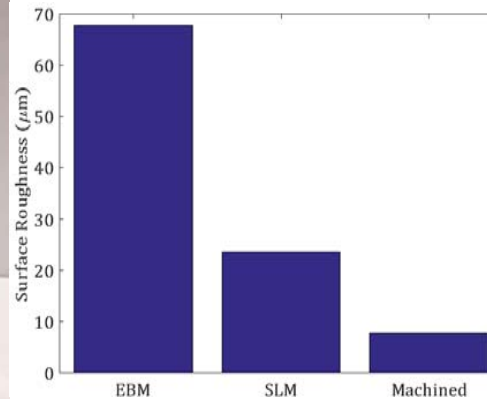
# Surface Roughness Comparison between SLM, EBM, and Machining



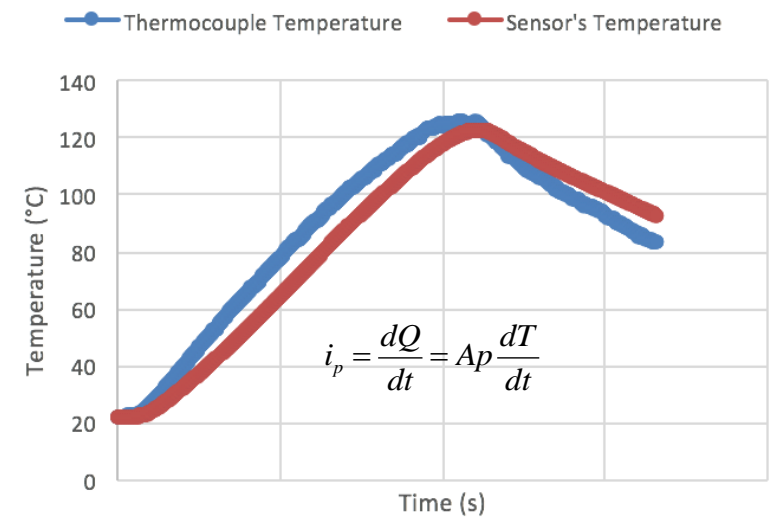
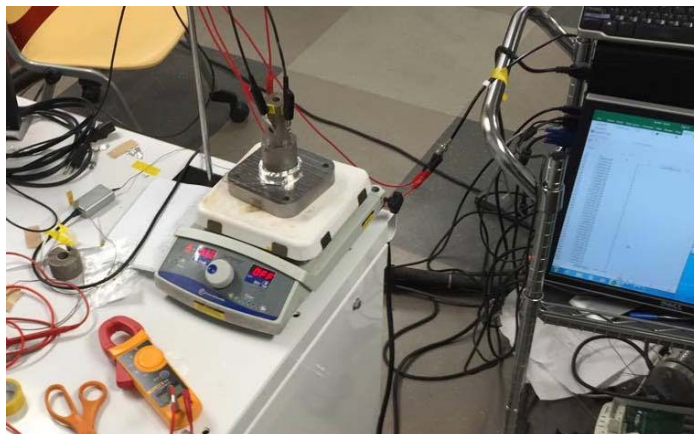
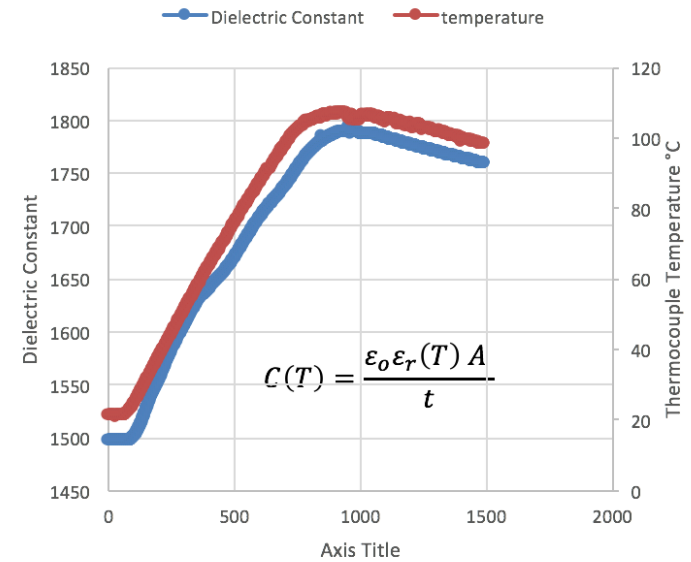
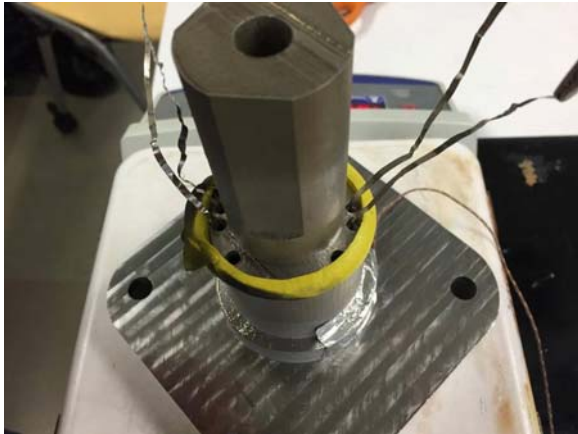
Cost:

EDM Machined: \$6,000, 2 months

SLM 3D printing: \$1,500, 2 days



# Preliminary Temperature Sensing Setup of the 3D printed injector



## Pre-test

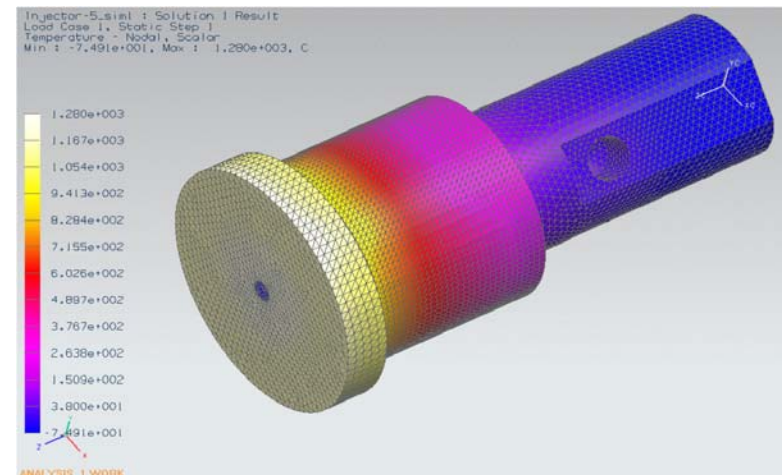
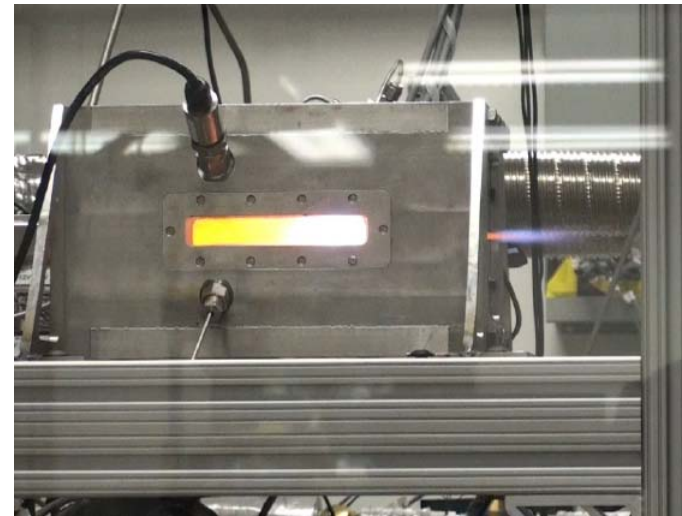
- Prove that each valve is working properly
- Make sure all readings are correct from pressure and temperature transducers and flow meters (ambient or zero)
- The line will be pressurized and Snoop will be used on each connection to check for leaks.

## Measuring pressure drop across the system (Cold flow testing)

- Pressure drop testing will be performed on each line using Nitrogen. Then we will know how much pressure on the tank will be needed to satisfy the desired chamber pressure

## Hot firing test

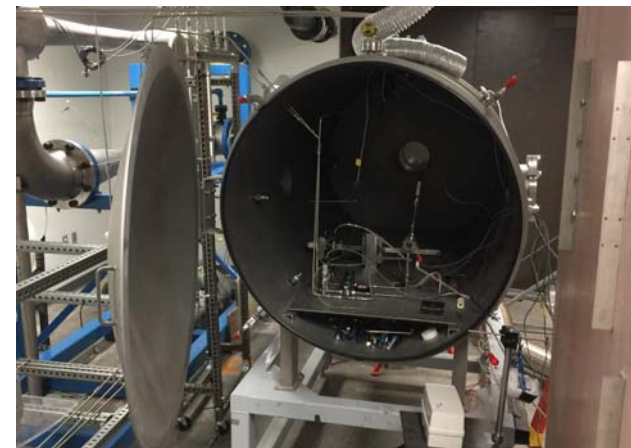
- The test will begin by setting the k-bottles to the indicated pressure indicated in the test matrix and setting LabVIEW to the automated sequence.



# Smart Fuel Injector Testing Setup



Multi-purpose  
Optically Accessible  
Combustor  
(MOAC)



# MOAC System

- Designed primarily for LOX/Methane combustion research
- Capability to simulate up to 50 lb thrusters
- Square chamber, inner dimensions 80x80x150mm
- Wide side quartz windows for optical access and laser diagnostics
- Modular injector/converging section
- Stands 20 bar as maximum pressure

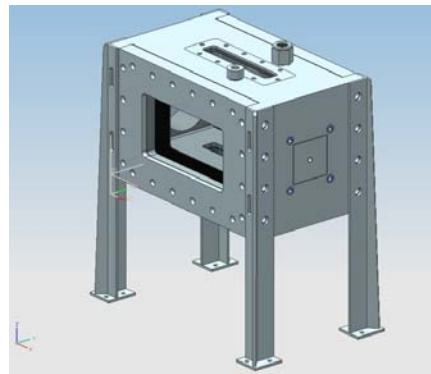
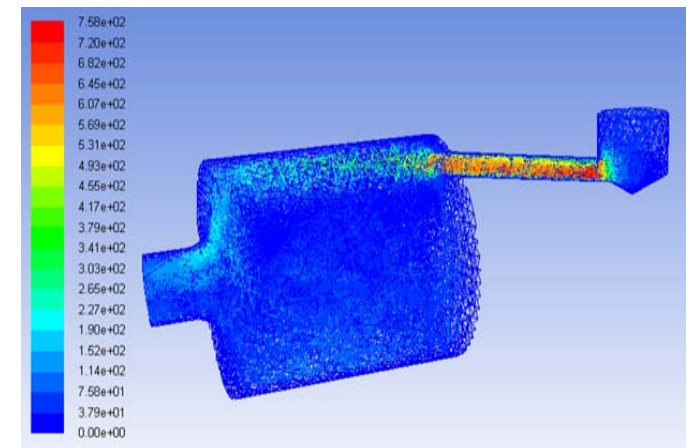
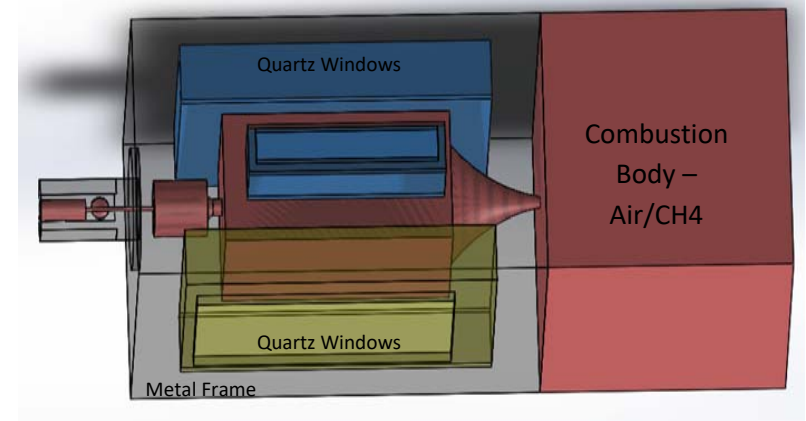


Fig 1. MOAC CAD model

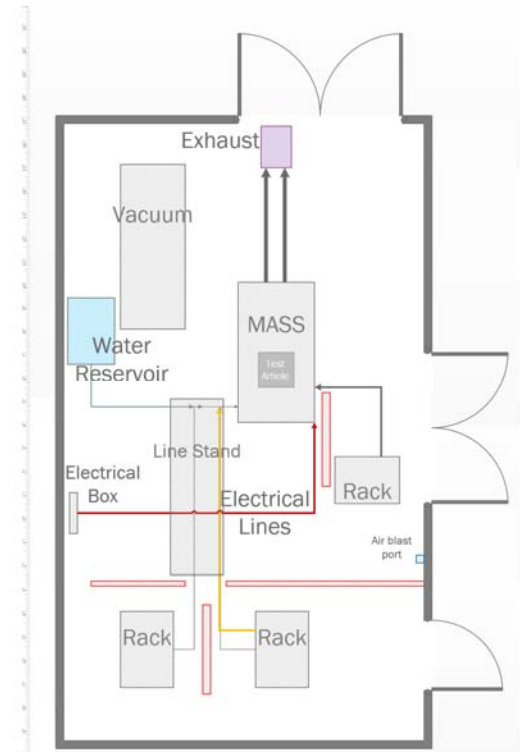
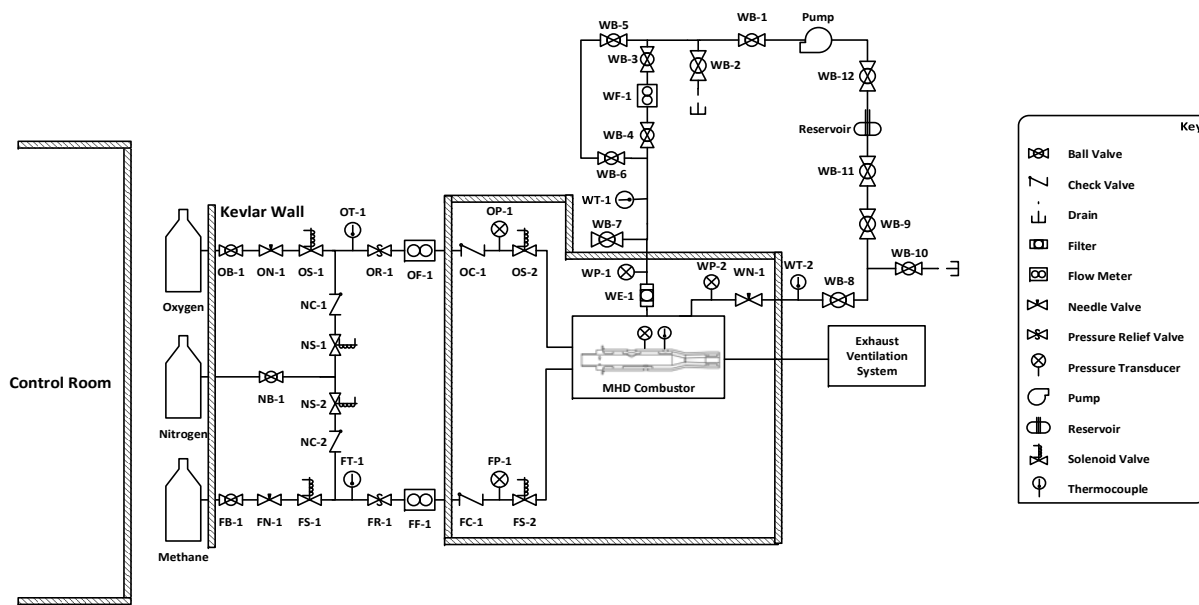


Fig 2. MOAC assembly



Modeling of the Surface roughness vs Pressure drop

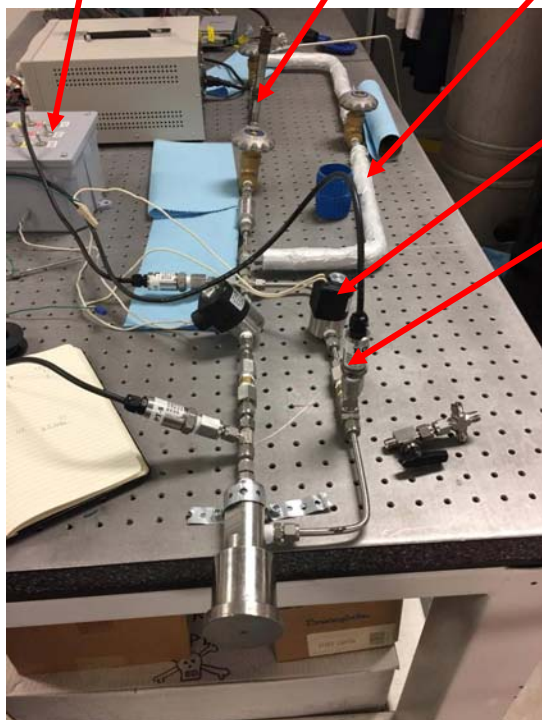
# Schematic and bunker diagram



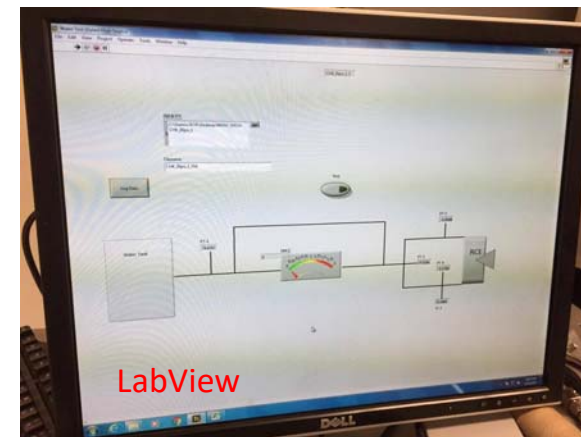
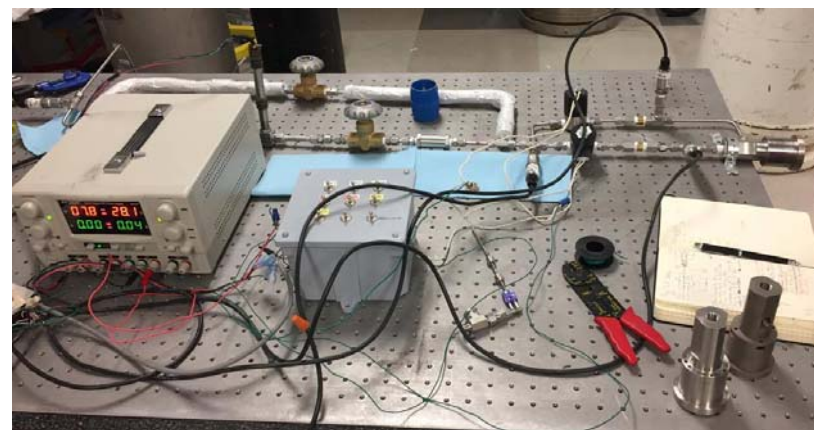


# Pressure drop and flow rate test of machined injector

Solenoid valve control  
Flow meter  
Bypass

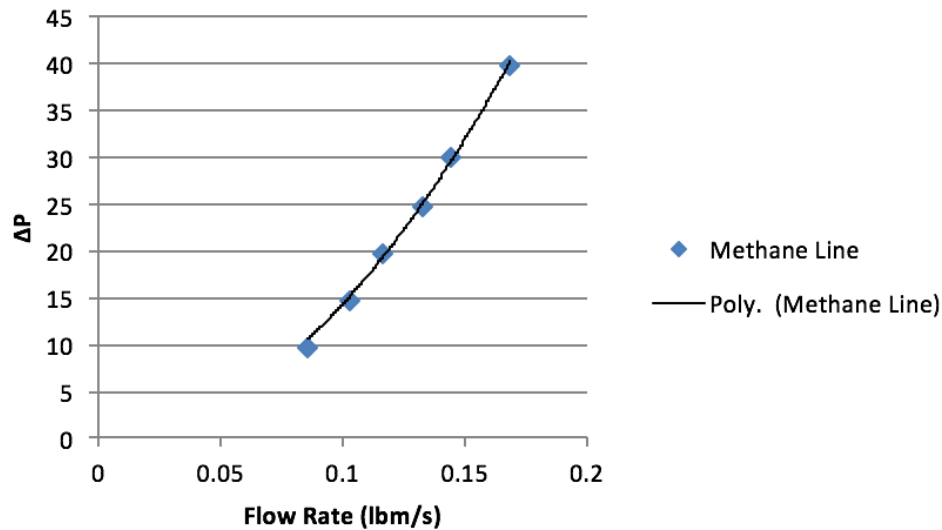


Solenoid valve  
Pressure transducer

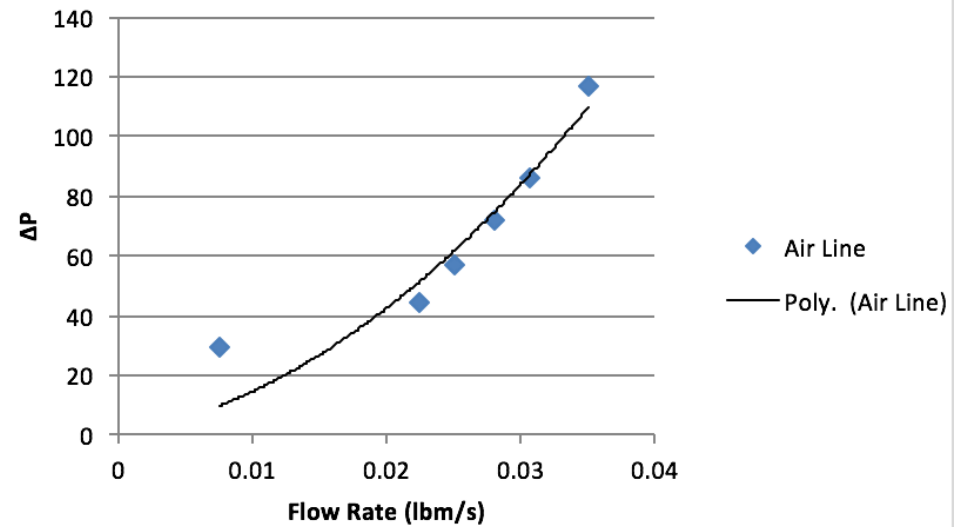


# Flow rate and pressure drop results of machined injector

### Methane Line (Manufactured)



### Air Line (Manufactured)

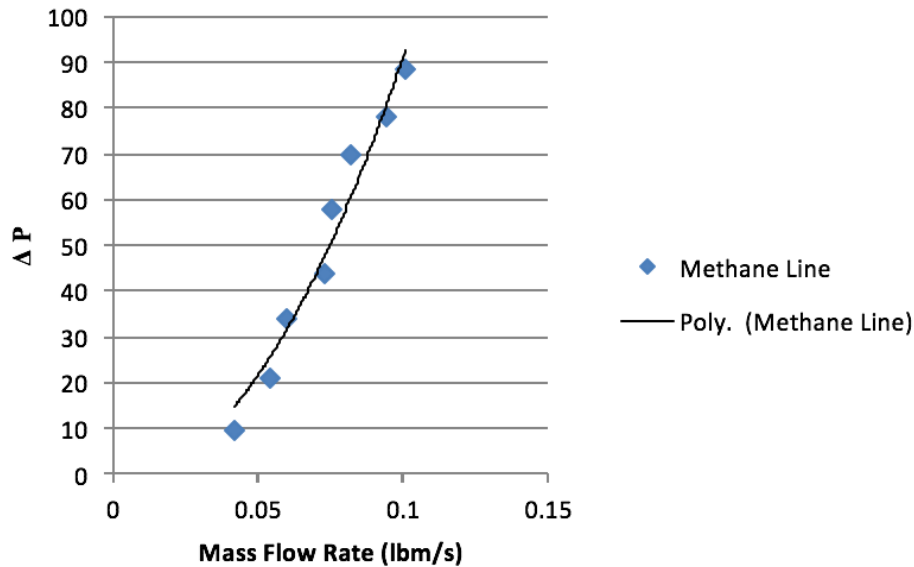


# Pressure drop and flow rate test of 3D printed injector

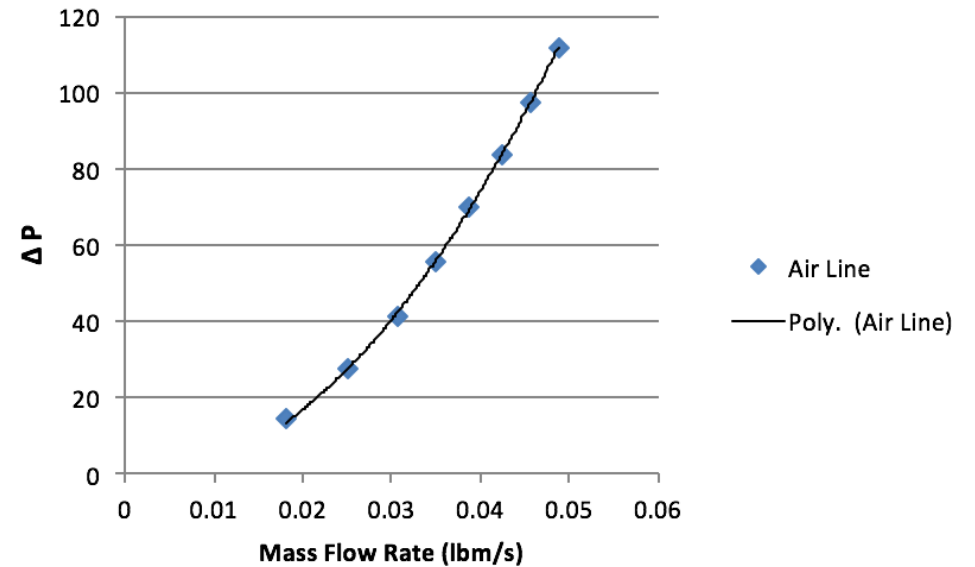


# Flow rate and pressure drop results of 3D printed injector

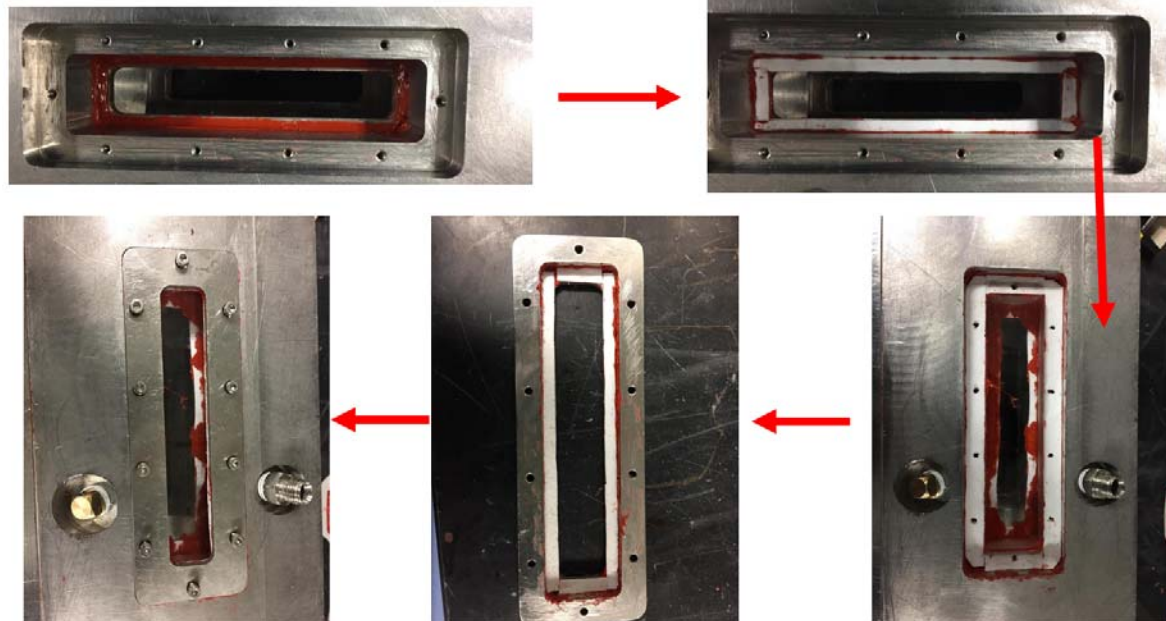
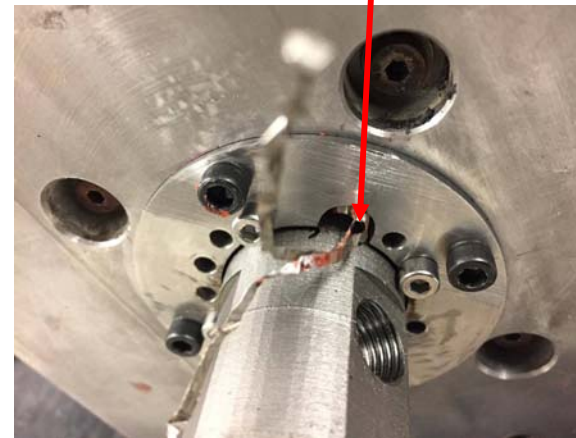
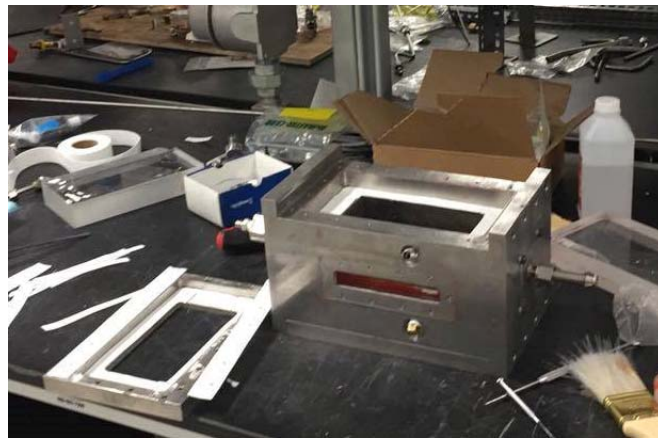
### Methane Line



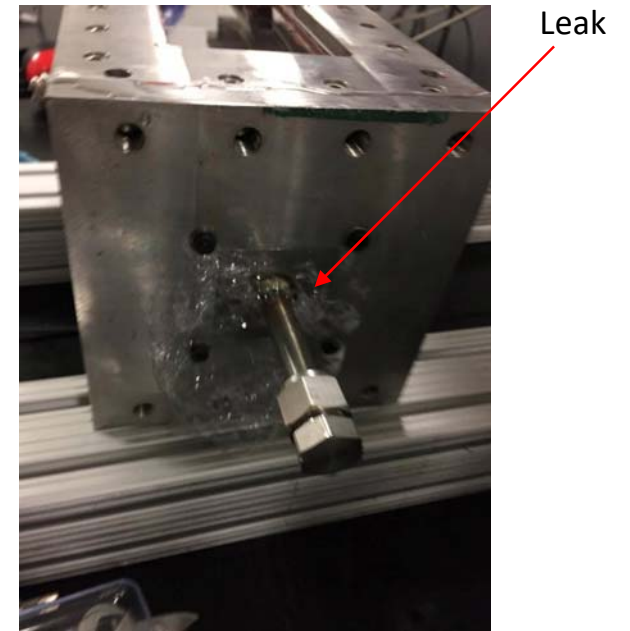
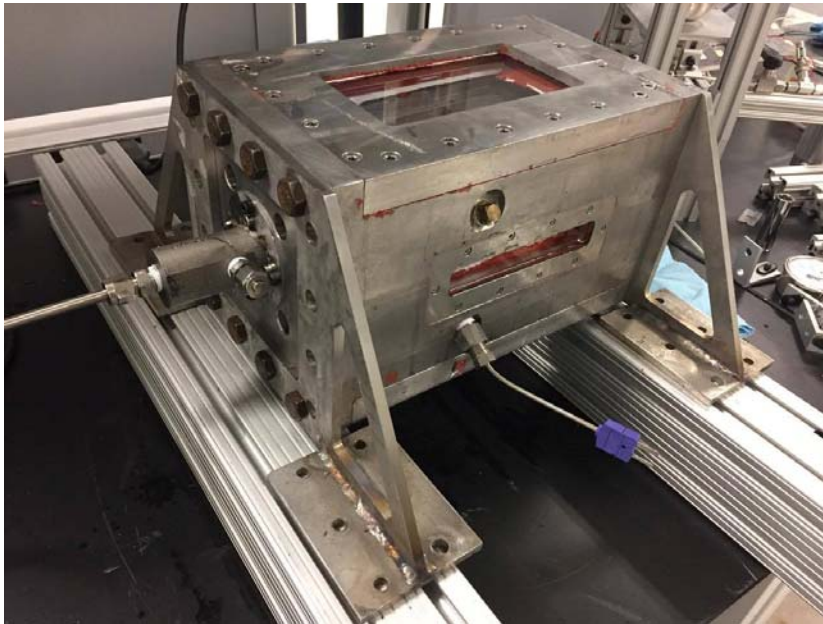
### Air Line



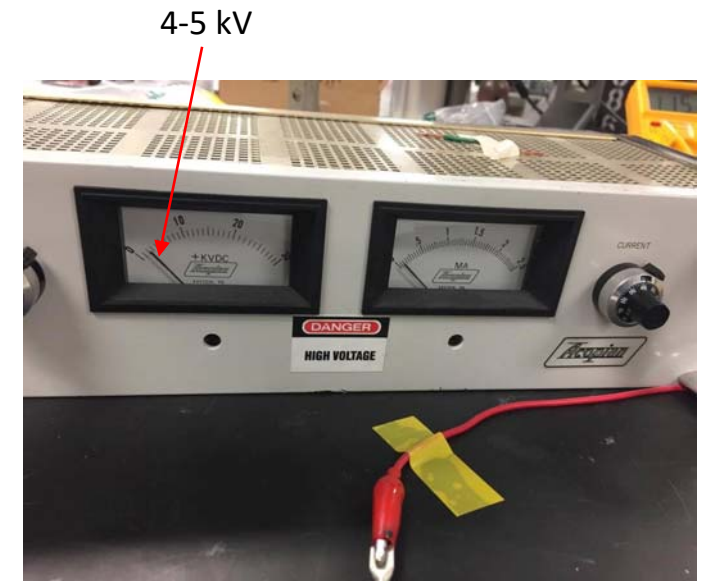
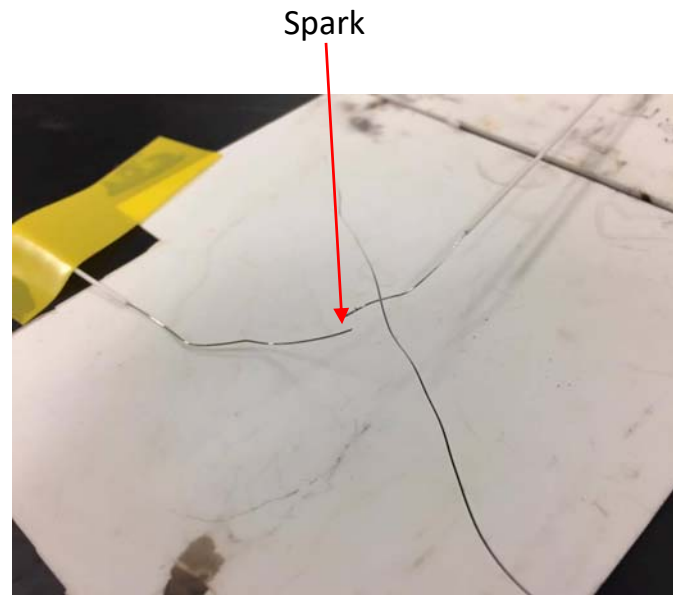
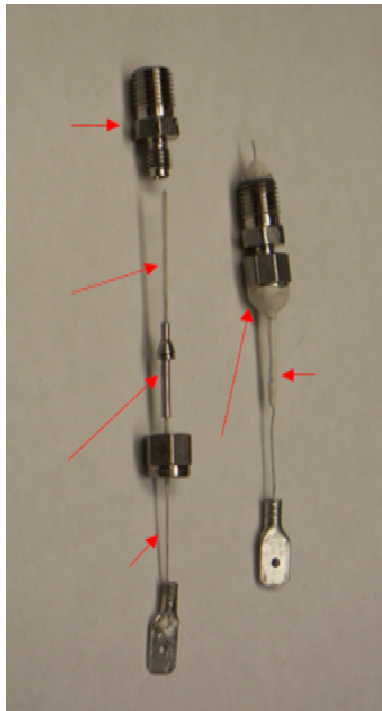
# Insertion of 3D printed injector



# Leak test using helium



# Spark electrodes fabrication and testing



# Torch igniter assembly

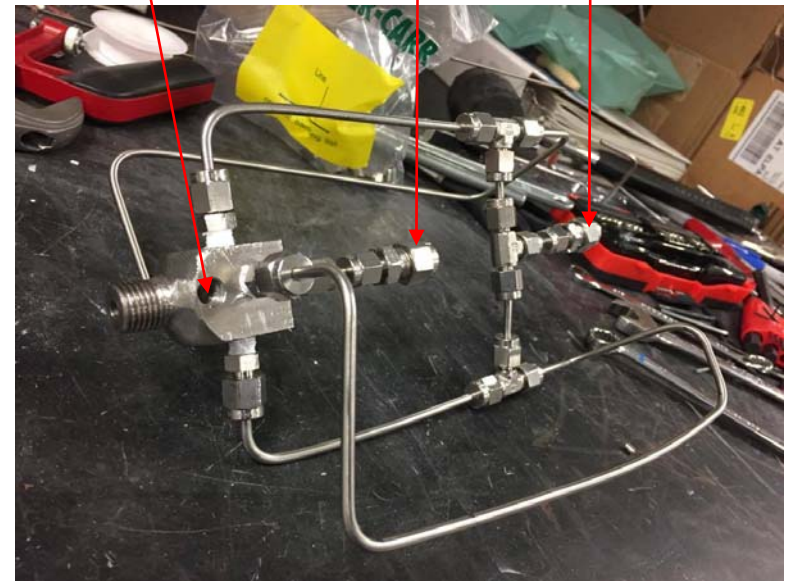
Bending



Sparker

Air

Methane







# Hot fire testing of CH<sub>4</sub> and air using a 3D printed injector



Stoichiometric equation for combustion of CH<sub>4</sub> and air:



Molecular weight of CH<sub>4</sub> = 16.043 g/mol

Molar mass

C = 12.011 X 1 atom X 1 mole

H = 1.008 X 4 atom X 1 mole

Molecular weight of 2(O<sub>2</sub> + 3.76N<sub>2</sub>) = 274.66 g/mol

Molar mass

O = 15.9994 X 2 atoms X 2 moles = 64

N = 14.007 x 2 atoms x 7.52 moles = 210.66 g/mol

$$O/f = \frac{274.66}{16.043}$$

$$O/f = 17.16$$

Chamber Pressure	Units	20	25	30	35	40	45
Methane flow	LPM	4.9	6.85	8.22	9.59	10.96	12.32
Air flow	LPM	93.26	109.63	131.54	153.45	175.36	209.6
Fuel tank pressure	PSI						
Air tank pressure	PSI						

Stoichiometric O/F calculated and estimated chamber pressures were used in CEA to calculate the temperatures experienced in the chamber and at the throat as well as the characteristic velocity  $c^*$  (cstar). cstar was used to calculate the total flow rate exiting the chamber at the throat as follows:

$$c^* = \frac{P_o * A_t}{\dot{m}}$$

Once the temperature has been calculated from CEA, this can be used to describe the enthalpy change of the combustion and calculate energy, and then finding flow rate of fuel is possible using the following equations:

$$Q = H_p - H_r$$

or

$$Q = (LHV)_{\text{methane}} * \dot{m}_f$$

Flow rates for both the air and fuel are now known and test matrix can be done using these expected flow rates and chamber pressures to begin cold test. The time that the test would take to get to temperature desired is also calculated by the following:

$$\dot{Q} = m_c * c_p \frac{\Delta T}{\Delta t}$$

Test matrix will be followed during the cold testing. Tank pressures will be added once pressure drop is known.

# Testing Setup Ready





# Publication and Patent



- Gonzalez, J., Mireles, J., Lin, Y., and Wicker, R., 2017, "Economical analysis of different metal 3D printing technologies," *Additive Manufacturing*, in review.
- Hossain, M., Gonzalez, J., Mireles, J., Choudhuri., Lin, Y. and Wicker., R., 2017. "Interfacial tuning of Electron Beam Melting 3D printing in 'Stop and Go' Metal Fabrication". *Additive Manufacturing*, in review.
- Martinez, R., Hossain, M., Mireles, J., Lin, Y., and Wicker, R., 2017, "Design, Fabrication, and Testing of smart tube with embedded smart materials using electron beam melting technology ," *Smart Materials and Structures*, in review.
- Hossain, M., Mireles, J., Wicker, R., 2017, "Computer vision enabled 'stop and go' alignment process in metal 3D printing," *Computer-aided design and manufacturing*, in review.
- Gonzalez, J., Mireles, J., Lin, Y., and Wicker, R., 2016, "Characterization of ceramic components fabricated using binder jetting additive manufacturing technology," *Ceramics International*, in press.
- Hossain, M., Gonzalez, J., Martinez, R., Shuvo, M., Mireles, J., Choudhuri., Wicker., and Lin, Y., 2015. "Fabrication and Characterization of Smart Parts using Electron Beam Melting Additive Manufacturing Technology". *Additive Manufacturing*, in Press.
- Gaytan, S., Cadena, M., Karim, H., Delfin, D., Lin, Y., Espalin, D. MacDonald, E. and Wicker, R., 2015, "Fabrication of barium titante by binder jetting additive manufacturing technology," *Ceramics International*, 41, 6610-6619.
- M. S. Hossain, J. Mireles, and R. Wicker, "Method of Fabrication for the repair and augmentation of part functionality of metallic components", U.S. Patent Pending, filed with U.S. Patent and Trademark Office, October 2015
- Gonzalez, J. A., Hossain, M. S., Martinez, R., Rodriguez, G., Shuvo, M.A.I., Mireles, J., Wicker, R., Choudhuri, A., Lin, Y. 2015, "Investigation on Smart Parts with Embedded Piezoelectric Sensors via Additive Manufacturing: Characterization of Smart Parts", 5th Southwest Energy Science and Engineering Symposium (SESES), April 4th, El Paso, TX.
- Hossain, M. S., Gonzalez, J. A., Mireles, J., Lin, Y., Choudhuri, A., and Wicker, R., 2015, "Smart Part Fabrication using Electron Beam Melting Additive Manufacturing Technology", 5th Southwest Energy Science and Engineering Symposium, El Paso, TX.
- Gonzalez, Jose A., Mireles J., Lin Y., Wicker R.B., 2015, "Fabrication of Ceramic Components Using Bi Binder Jetting Additive Manufacturing Technology." 5th Southwest Energy Science and Engineering Symposium (SESES), April 4th, El Paso, TX.
- Hossain, M. S., Gonzalez, J. A., Mireles, J., Lin, Y., Choudhuri, A., and Wicker, R., 2015, "Smart Part Fabrication using Electron Beam Melting Additive Manufacturing Technology", 2016 Southwest Emerging Technology Symposium, El Paso, TX.
- Hossain, M. S., Gonzalez, J. A., Gaytan, S. M., Lin, Y., Choudhuri, A., and Wicker, R., "Stop and Go Process to Fabricate Smart Parts using Electron Beam Melting", Power Industry Division Symposium, 2014.



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- Maria Reidpath
  - Federal Project Manager, Crosscutting Research, NETL, U.S. DOE
- Robert Romanosky
  - Acting Technology Manager, Crosscutting Research, NETL, U.S. DOE



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Arconic



Thank you

Questions?