2014 University Turbine Systems Research Workshop Co-organized by Purdue and DoE NETL 21-23 October 2014

Issues in Modelling and Simulation of Turbine Cooling

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Outline of Talk

Challenges in Modelling and Simulation

- Rim seals: Jason Liu, Adam Weaver
- Compound-Angle Film Cooling: Zach Stratton

Design Tools:

- Unsteady Conjugate Heat Transfer: Chien-Shing Lee
- Effects of Averaging: Chien-Shing Lee

Summary & Current Work





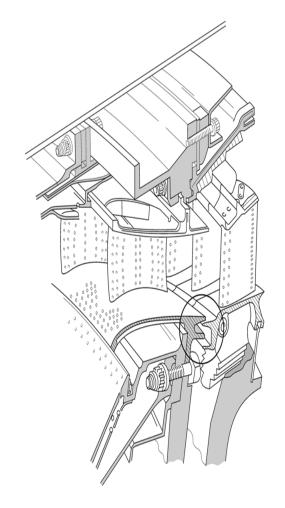
Up to 30% of the air entering the compressor is used for turbine cooling. One area where reduction may be possible is the rim seals.

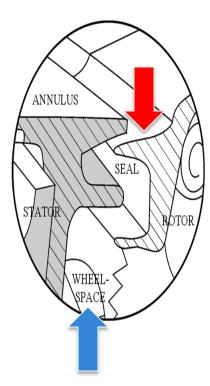
Previous and Current Studies:

- Chupp, Hendricks, Lattime, Steinetz, Aksit
- Bath: Owens, Lock, Sangan
- Penn State: Thole

Key Findings by Bath:

- Pressure downstream of stator vanes dominate ingress.
- Rotor blades play no role on ingress.
- CFD can accurately predict CO₂ injection with sealant flow as a way to measure ingress.

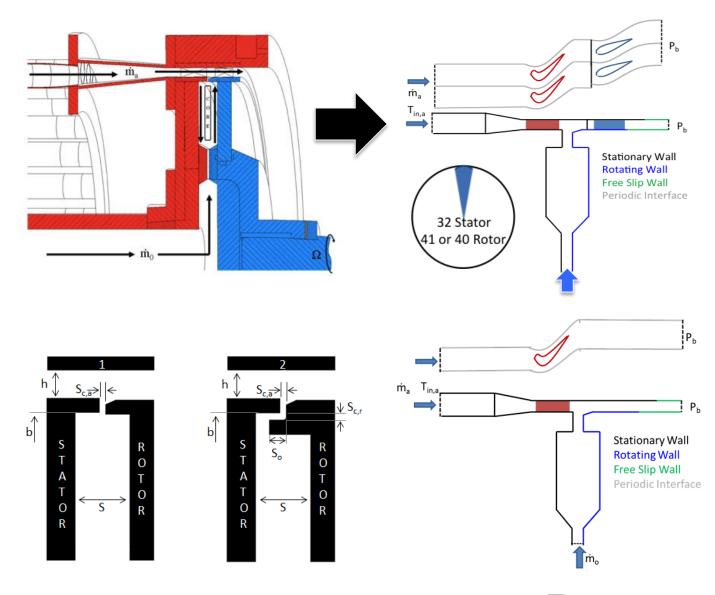






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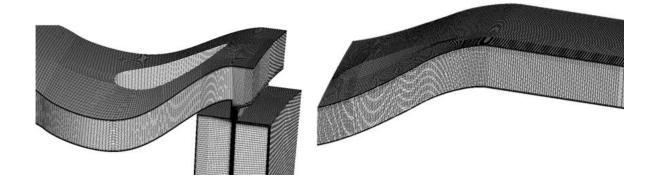


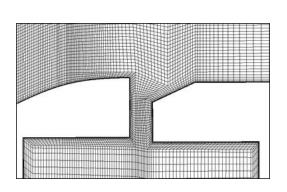
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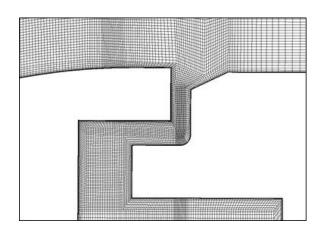
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RANS Study of Stator-Rotor:

- time-accurate Fourier on 32-41 and 32-40 → 4-5
- **steady-state** without blades on the rotor (inertial frame)



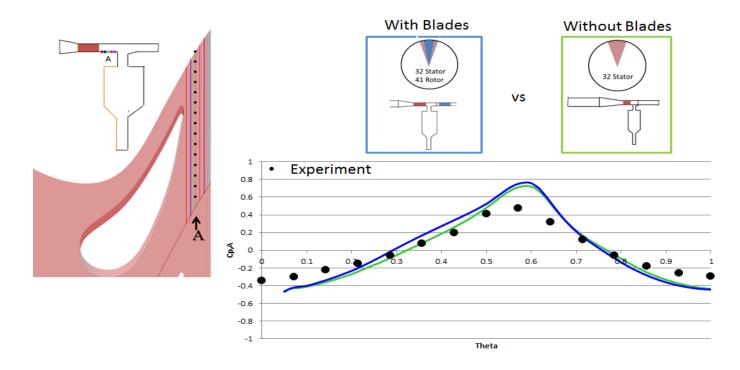




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CFD Studies of Stator-Rotor:

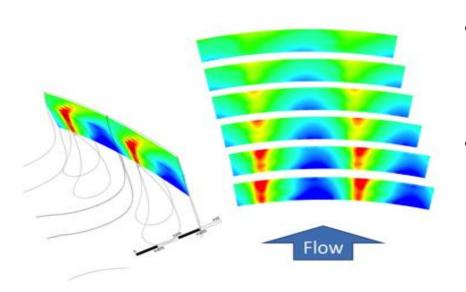


- Pressure downstream of the stator relatively independent of the blades on the rotor.
- Thus, blades on rotor could be removed for Bath configuration to get this pressure distribution.
- BUT, still need to assess how well CFD can predict that pressure.

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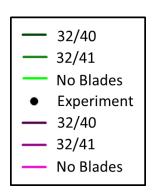
CFD Studies of Stator-Rotor:



Axial Seal: φ/φmin = 0

1
0.8
0.6
0.4
0.2
0.0
0.4
0.6
-0.8
-0.8
-1

- Each plane is 1 mm apart, and probe diameter is 1 mm.
- Magnitude of the peak & trough in P diminishes rapidly downstream of stator vanes.
- CFD can predict pressure distribution to within 5%.



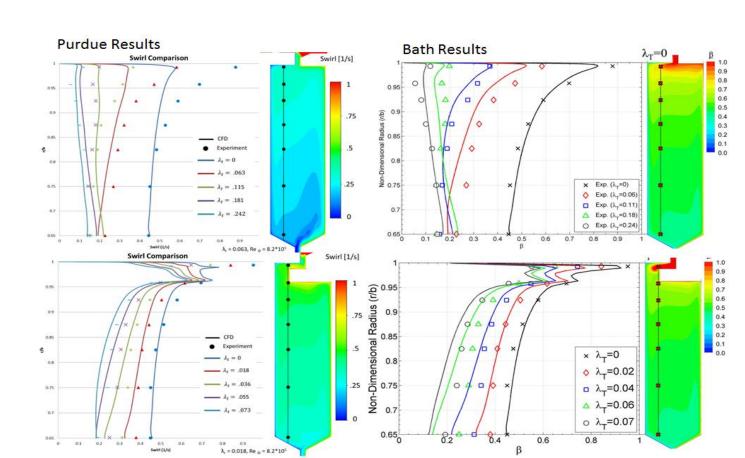
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CFD Studies of Stator-Rotor:

By using an inertial frame of reference,

- swirl is predicted reasonably well (esp. at lower radii)
- cannot predict the measured ingress
- do not match the CFD results from Bath.



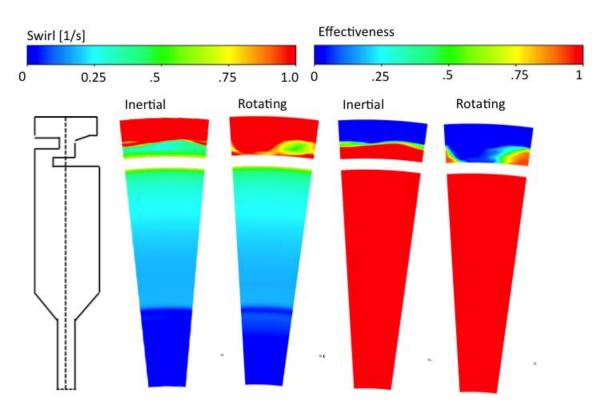
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CFD Studies of Stator-Rotor:

- Inertial frame (Purdue) & inertial+noninertial+frozen rotor BC (Bath) yield different flow fields. The culprit is in the frozen rotor BC.
- The Bath approach matches experimental data only at 3000 rpm case, which is what was reported.

Thus, the blades on the rotor do play a role on ingress.



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Summary & Current Work





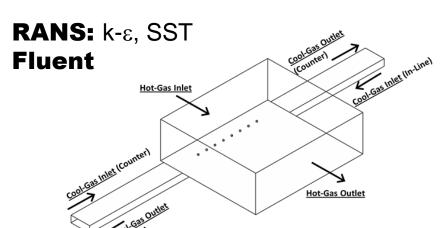
Why compoundangle film cooling?

- Higher adiabatic effectiveness over streamwise injected holes [Ligrani]
- Improved lateral spreading [Schmidt]

Objectives:

- What is affect of flow direction in the internal coolant passage?
- Assess k-ε, SST, LES?

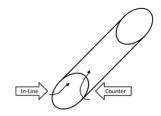
Supported by GE and DoE NETL



Hot Gas (Air)
$T_{\infty} = 303^{\circ} \text{K}$
$u = u(y); \ \delta = 2.8d$
$u_{\infty} = 13.8 \text{ m/s}$
Turbulence Intensity = 6%

Cool gas (N_2)
$T_c = 202^{\circ} \text{K}$
$\dot{m} = 0.02145 \text{ kg/s}$
$Re_{d_H} = 35,000$

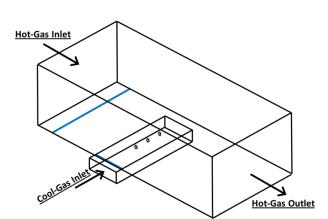
Case	Flow Direction Blowing Rati		
1a	In-Line	0.5	
1b	In-Line	1.0	
1c	In-Line	1.5	
2 a	Counter	0.5	
2b	Counter	1.0	
2c Counter		1.5	

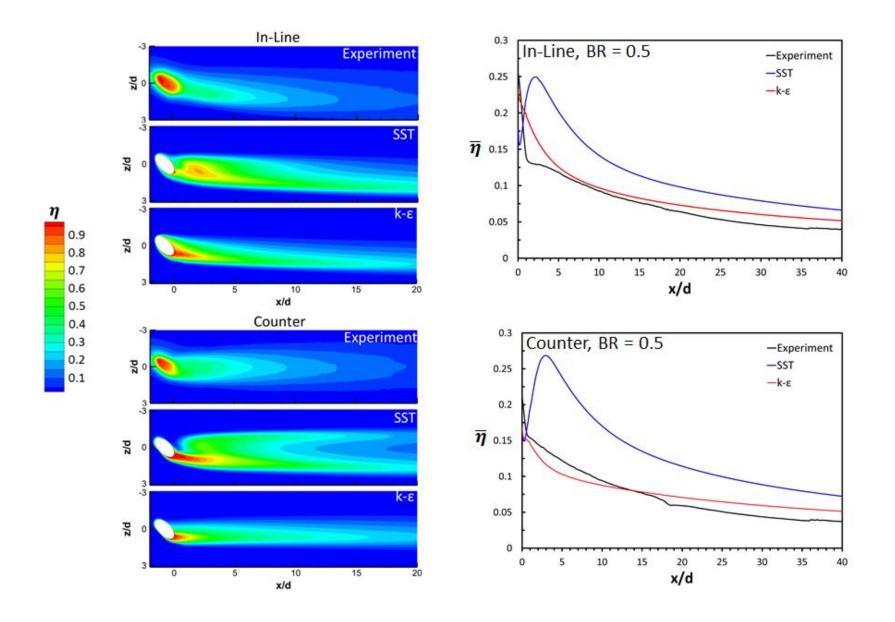


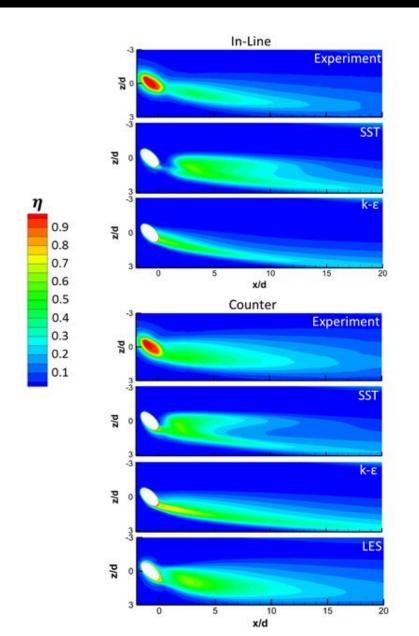
Hole diameter (d) = 5 mm Hole length = 6d Hole spacing = 6.25d Adiabatic walls

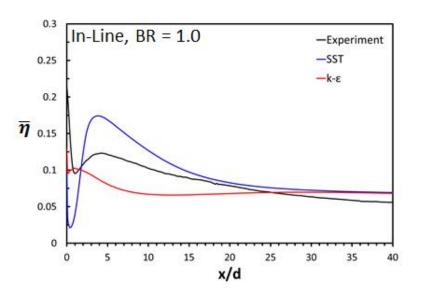
LES PowerFlow

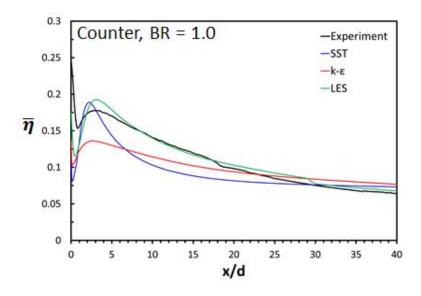
Experimental data: Dave Bogard



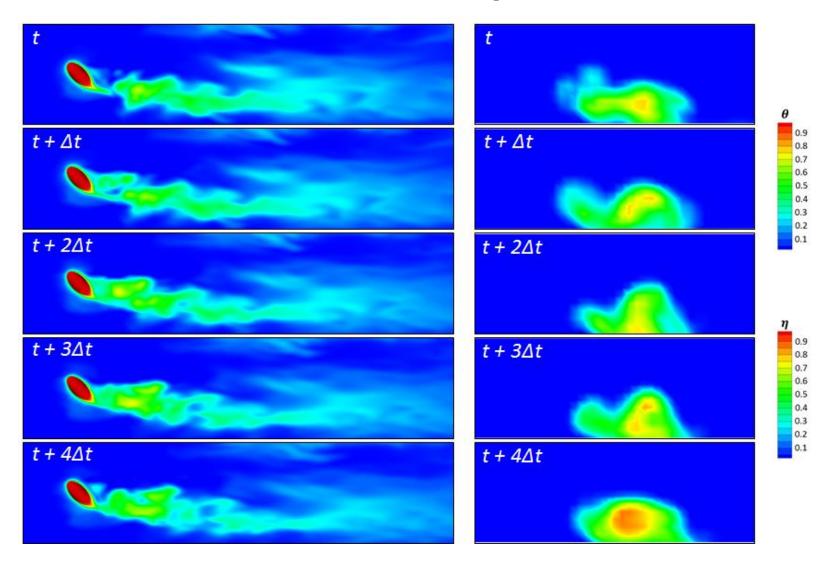








LES: instantaneous normalized temperature



Conclusion:

- Separation induces a vortex that causes flow to swirl in the hole.
- Vortex is unsteady causing side-to-side shedding.
- Steady RANS compared poorly with experiment.
- LES was able to predict adiabatic effectiveness with reasonable accuracy, but MUST simulate the trip in the experiment.

Our Current Efforts:

- Examine LES models in the near-wall region for surface heat transfer.
- Examine RANS to LES interface boundary conditions.
- Understand statistics from LES to guide RANS modeling for internal cooling and film cooling.



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Summary & Current Work





One source of failure in GTs is due to **inadequate cooling during** transient operations – not startup, but from a lower load state to a higher load state.

Previous Work:

- Very little work reported that are relevant to gas turbines. Mostly on startup.
- Lee, at al. (2013) showed the temperature in the material could exceed the maximum permitted during the transients even though the cooling provided is adequate once steady-state is reached.

Objective:

- Develop a model that can be used to guide the design of cooling strategies subjected to sudden changes in heating loads.
- Want to estimate the over temperature, its duration, ...

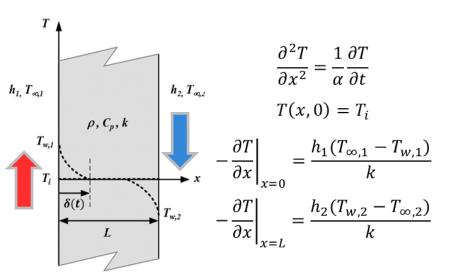
Approach:

Develop a closed-form approximate solution of unsteady 1-D HT in a flat plate.





Approximate Solution by an Integral Method



1st time domain:

when conduction from both sides reaches the same point in the plate.

2nd time domain:

from the end of the 1st time domain to the time when the temperature in the plate reach its maximum (referred to as its peak temperature).

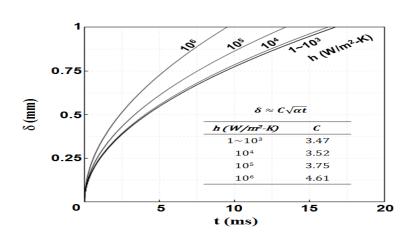
3rd time domain:

from the time of the peak temperature to the time when steady state is reached.

1st Time Domain:

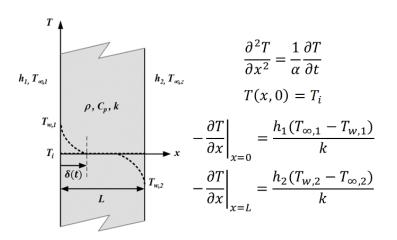
$$\int_{T_{i}}^{T_{w,1}} \left(\frac{2 \left(T_{w,1} - T_{i}\right) \left(\frac{h_{1} \left(T_{\infty,1} - T_{w,1}\right)}{k}\right) + \frac{h_{1}}{k} \left(T_{w,1} - T_{i}\right)^{2}}{\left[\frac{h_{1} \left(T_{\infty,1} - T_{w,1}\right)}{k}\right]^{3}} \right) dT_{w,1} = \frac{4}{3} \alpha t$$

 $\delta_1 \approx 3.47 \sqrt{\alpha t}$ (Valid for h < 10⁴ W/m²-K)



See IGTI2015-43526 for details.

Approximate Solution by an Integral Method

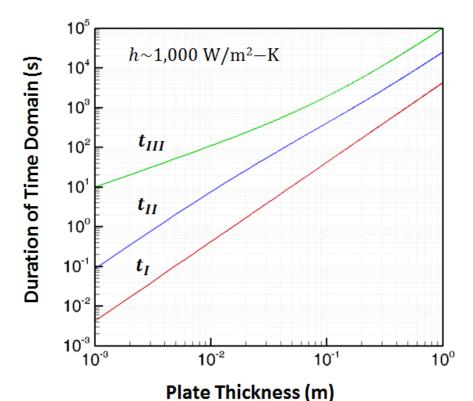


2nd and 3rd Time Domains:

$$\mathbb{T} = \mathcal{C}_1 \mathbb{X}_1 e^{-\frac{t}{\tau_{III}}} + \mathcal{C}_2 \mathbb{X}_2 e^{-\frac{t}{\tau_{II}}} + \mathbb{R}$$

$$\Gamma = C_{1} X_{1} e^{-\frac{t}{\tau_{III}}} + C_{2} X_{2} e^{-\frac{t}{\tau_{II}}} + \mathbb{R}$$

$$\tau_{II, III} = \rho C_{P} L \left(\frac{48 + 7 \frac{h_{1}L}{k} + \frac{h_{1}L}{k} \cdot \frac{h_{2}L}{k} + 7 \frac{h_{2}L}{k}}{\frac{h_{1}L}{k} \cdot \frac{h_{2}L}{k} + 5 \frac{h_{1}L}{k} \cdot \frac{h_{2}L}{k} + 20 \frac{h_{2}L}{k}}{\frac{h_{2}L}{k}} + 3 \sqrt{\left(16 + 4 \frac{h_{1}L}{k} + \frac{h_{1}L}{k} \cdot \frac{h_{2}L}{k} + 4 \frac{h_{2}L}{k}\right)^{2} + 16 \left(\frac{h_{1}L}{k} - \frac{h_{2}L}{k}\right)^{2}} \right)$$

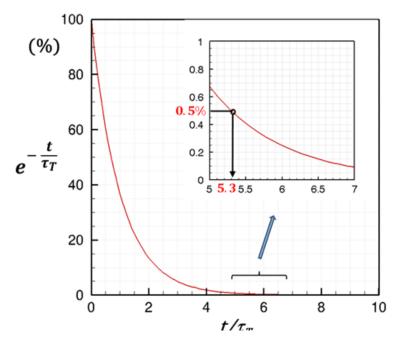


Estimate Duration of Over Temperature:

$$P \simeq 5.3 \tau_T$$

$$au_T = au_{II} + au_{III}$$

Estimate "Maximum" Over Temperature:



$$\begin{aligned} \theta_{w,1,max} &= \mathcal{M}_1 + \frac{1}{2} (\theta_{w,1,i} - \mathcal{M}_1 + \mathcal{M}_2) (e^{-\mathcal{N}_{II}(Fo_c - Fo_i)}) + \\ &+ \frac{1}{2} (\theta_{w,1,i} - \mathcal{M}_1 - \mathcal{M}_2) (e^{-\mathcal{N}_{III}(Fo_c - Fo_i)}) \end{aligned}$$

What cooling is needed for a given heating load to ensure T_{max} in material does nor exceed acceptable value?

$$\frac{Bi_1(1+Bi_2)}{Bi_1 + Bi_1Bi_2 + Bi_2} = \theta_{w,1,i}$$

0.8 0.6 0.4 0.2 0.4 0.2 0.4 0.6 0.8 1

To determine a **precooled wall temperature needed that ensures the max. temperature** in a plate never exceeds the max. allowable throughout the transient process:

$$\theta_{w,1,max} \leq \theta_{max.\,allowable}$$

$$\rightarrow \theta_{w,1,i}^* \leq \frac{\left((2-\mathcal{M}_{2,b})\theta_{max.\,allowable} - \mathcal{M}_1 + \mathcal{M}_{2,c}\right)}{\left(1-\mathcal{M}_{2,a}\right)}$$

In a GT operation:

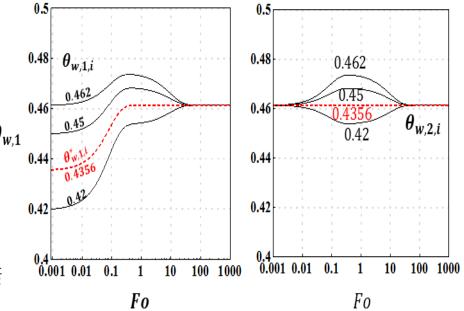
If maximum allowable = 900°C, and hot gas: $T_{\infty,1} = 1,482$ °C coolant: $T_{\infty,2} = 400$ °C

Then,
$$\theta_{max,allowable} = 0.462$$

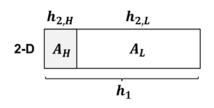
 $\rightarrow \theta_{w,1,i}^* = 0.4356$,
 $(T_{w,1,i}^* = 871^{\circ}\text{C})$

where

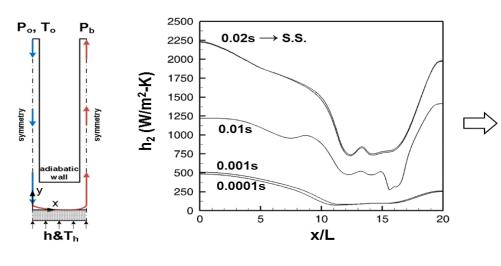
$$\begin{split} \theta_{w,1,i}^* &= \frac{T_{w,1,i}^* - T_{\infty,2}}{T_{\infty,1} - T_{\infty,2}} \qquad \mathcal{M}_1 = \frac{Bi_1(1 + Bi_2)}{Bi_1 + Bi_1Bi_2 + Bi_2} \\ \mathcal{M}_{2,a} &= \frac{4(Bi_1 - Bi_2)}{\sqrt{(4Bi_1 + Bi_1Bi_2 + 4Bi_2 + 16)^2 + 16(Bi_1 - Bi_2)^2}} \\ \mathcal{M}_{2,b} &= \frac{(4 + Bi_2)^2}{\sqrt{(4Bi_1 + Bi_1Bi_2 + 4Bi_2 + 16)^2 + 16(Bi_1 - Bi_2)^2}} \\ \mathcal{M}_{2,c} &= \frac{5Bi_1Bi_2^2 - 4Bi_1^2Bi_2 - 4Bi_1^2 + 12Bi_1Bi_2 + 16Bi_1}{(Bi_1 + Bi_1Bi_2 + Bi_2)\sqrt{(4Bi_1 + Bi_1Bi_2 + 4Bi_2 + 16)^2 + 16(Bi_1 - Bi_2)^2}} \end{split}$$

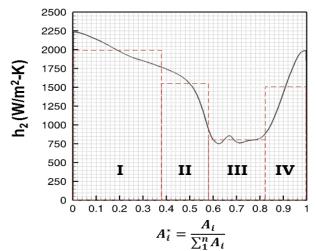


Generalization to Multidimensions



$$\bar{h}_2 = \frac{h_{2,H}A_H + h_{2,L}A_L}{A_H + A_L} = h_{2 (1D)}$$





Segment #		I	II	III	IV
		0.38	0.2	0.24	0.18
$h_1(W/m^2-K)$		1,090	1,090	1,090	1,090
$h_2(W/m^2-K)$		2,000	1,550	800	1,500
τ_{II}	$R_T^i \cdot C_i(s)$	0.0165	0.0166	0.0167	0.0166
τ_{III}	$R_T^i \cdot C_i(s)$	1.579	1.841	2.564	1.876
	(s)	1.94			

Duration of Over Temperature

Solid Only - α=constant - Ti=900°C	CFD	Model =1.94s	Error
99.5%	10.8s	10.3s	4.6%
99.9%	14s	13.6s	3%

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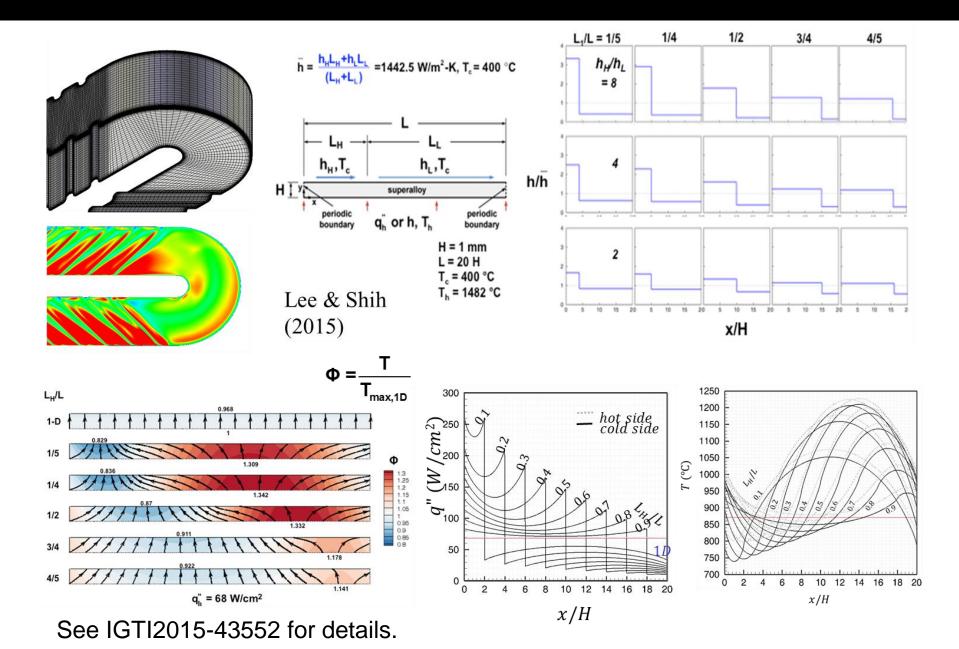
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Effects of Averaging: C.S. Lee, T. I-P. Shih



Summary

Performed a CFD study to examine the Bath rim-seal configuration. Found that blades on the rotor indeed do not affect the pressure distribution downstream of the stator. However, inertial frame and inertial plus non-inertial frame with frozen rotor do not yield the same results. The culprit is the frozen-rotor BC.

Developed a model to estimate the maximum over temperature, its duration, cooling needed at steady state, and precooling temperature needed before sudden increase in heating load to ensure no over temperature during the transient.

When the variation in the HTC is accounted for, the maximum temperature in the plate could be as high as 1.363 times the maximum temperature predicted by assuming an averaged HTC. Also, the difference in the maximum and minimum temperature in the plate can increase by a factor of 16, which strongly affects thermal stress.

